Megaflux Frameless Brushless Torque Motors-MF0255

Brushless thin-ring component (rotor and stator) torque motor

Allied Motion's Megaflux family of brushless torque motors includes 12 series of high performance frameless component torque motors, ranging in outside diameter from 60 mm up to 792 mm (2.36 in. up to 31.2 in.). Each motor consists of a matched rotor and stator pair. The stator is wound WYE with the three phase terminals made available.

This datasheet provides a specification overview of the MF family and specific data for the MF0255 series motors.

Megaflux frameless brushless torque motors are computer-designed and -optimized to provide the highest torque density brushless torque motors available. Special attention has been given to cogging torque minimization to enhance their performance in precision applications.

Frameless Megaflux motors are thin annular ring motors with large diameter-to-length ratios, and are intended to be integrated directly into mechanisms, effectively eliminating problems of torsional resonances due to couplings and backlash associated with gear trains. They are typically mounted directly to the driven axis, and their large open bore enables passing system electrical cabling, fluid piping or light beams through the motor center.

Features & Benefits

- 12 standard frame sizes from 60 mm up to 792 mm outside diameter
- Continuous stall torque as high as 1875 Nm (1383 lb-ft) covers a very wide range of applications
- Computer-optimized design maximizes torque density and performance
- Large, clear through bore—allows passage of air, water, or vacuum lines, optical beams, and/or electrical/signal wiring
- Three winding voltage designs for each size of 48, 150, and 300 VDC
- Hall sensor assembly standard on MF0060 through MF0127 series

Options & Accessories

- Custom winding designs to accommodate special voltage requirements
- Thin lamination MFS version for improved efficiency in applications requiring high speeds
- Hall-effect sensor array for commutation signals on larger series
- Special-engineered mechanical configurations to meet specific application needs
- Application-matched brushless servo drives



- High torque density, thin-ring frameless brushless torque motors
- 12 stator diameters, each with five stack heights, mean a wide selection of performances from which to choose
- High rated continuous stall torque of up to 1875 Nm (1383 lb-ft)
- Three winding designs: 48, 150, and 300 VDC

SPECIFICATION SUMMARY

Model	Units	MF0060	MF0076	MF0095	MF0127	MF0150	MF0210
Continuous Stall Torque	lb-ft	0.22 - 0.76	0.38 - 1.62	0.68 - 3.24	1.2 - 6.2	2.3 - 18.2	5.9 - 55.3
	Nm	0.29 - 1.04	0.51 - 2.20	0.92 - 4.39	1.6 - 8.4	3.1 - 24.7	8.0 - 75.0
No Load Speed	RPM	2076 - 7098	1640 - 6447	1300 - 5436	939 - 5097	416 - 2500	338 - 1894
Diameter (Outer)	in	2.38	2.99	3.73	5.00	6.69	9.06
	mm	60.4	76.0	94.7	127.0	170.0	230.0
Model	Units	MF0255	MF0310	MF0410	MF0510	MF0610	MF0760
Continuous Stall Torque	lb-ft	7.2 - 75.9	12.8 - 133.7	50.6 - 280	81 - 504	127 - 762	225 - 1383
	Nm	9.7 - 102.9	17.3 - 181.3	68.6 - 380	110 - 684	172 - 1034	304 - 1875
No Load Speed	RPM	280 - 1591	100 - 1260	71 - 926	42 -771	25 - 595	17.1 - 422
Diameter (Outer)	in	10.83	13.0	16.9	21.1	25.2	31.18
	mm	275.0	330	430	535	640	792

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SPECIFICATIONS (all data measured at 20 °C ambient)

Model No.		MF0255010			MF0255025			MF0255050		
Winding Voltage	V	48	150	300	48	150	300	48	150	300
Stall Torque (continuous) (1)	lb-ft	7.5	7.5	7.2	18.3	19.4	18.9	40.5	41.1	41.1
	Nm	10.1	10.1	9.7	24.8	26.3	25.6	54.9	55.7	55.7
Peak Torque (±25%)	lb-ft	53.3	53.3	53.3	143	143	143	293	293	293
	Nm	72.3	72.3	72.3	194	194	194	398	398	398
Peak Current	Α	135	77.3	42.7	232	136	77	316	197	121
No Load Spood	RPM	806	1439	1591	520	948	1083	343	659	825
No Load Speed	rad/s	84	151	167	54	99	113	36	69	86
Cogging Torque (may)	lb-ft	0.17			0.42			0.70		
Cogging Torque (max.)	Nm	0.23			0.56			0.95		
Torque Constant (±10%)	lb-ft/A	0.394	0.689	1.246	0.616	1.057	1.849	0.929	1.487	2.416
Torque Constant (±10%)	Nm/A	0.534	0.934	1.689	0.835	1.433	2.507	1.260	2.016	3.276
Voltage Constant (±10%)	V/kRPM	56	98	177	87	150	263	132	211	343
Voltage Constant (±10%)	V/rad/s	0.534	0.934	1.689	0.835	1.433	2.507	1.260	2.016	3.276
Motor Constant	lb-ft/√W	0.89	0.89	0.85	1.86	1.91	1.86	3.15	3.20	3.20
MOTOL COLISIANT	Nm/√W	1.20	1.20	1.15	2.52	2.59	2.52	4.27	4.34	4.33
Elect. Time Constant	ms	3.40	3.39	3.11	4.89	5.15	4.89	6.00	6.17	6.17
Mech. Time Constant	ms	2.33	2.33	2.54	1.40	1.33	1.40	0.97	0.93	0.94
Terminal Resistance (±12%)	Ohm	0.197	0.605	2.158	0.110	0.307	0.991	0.087	0.216	0.517
Terminal Inductance (±30%)	mH	0.669	2.048	6.708	0.538	1.581	4.842	0.521	1.333	3.521
Thermal Resistance (1)	°C/W	0.900			0.620			0.395		
Motor Inertia	lb-ft-s²	2.6E-3			6.9E-3			1.4E-2		
	kg-m²	3.6E-3			9.4E-3			1.9E-2		
Motor Weight	lb	5.1	5.1	5.0	12.3	12.2	12.1	23.1	23.2	23.2
	kg	2.33	2.33	2.27	5.57	5.53	5.48	10.47	10.51	10.51
Ambient Storage Temperature	°C	-55 to 150								
Poles	-	40								

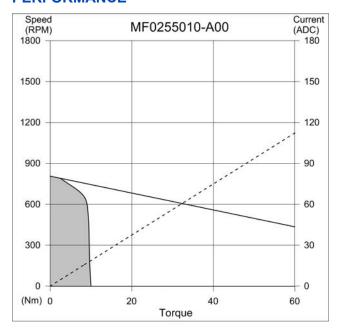
⁽¹⁾ Housed version of motor mounted to 406 mm sq. x 12.7 mm (16 in. sq. x 0.5 in.) aluminum plate in still air; maximum operating temperature (ambient + rise) is 130 °C

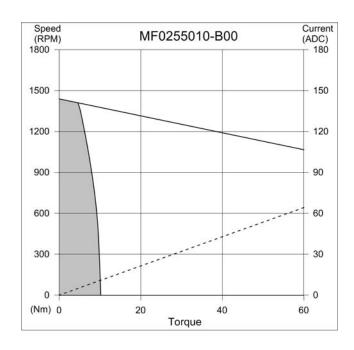
Model No.		MF0255075		MF0255100				
Winding Voltage	V	48	150	300	48	150	300	
Stall Targue (continuous) (1)	lb-ft	60.1	61.7	60.7	76.4	77.3	75.9	
Stall Torque (continuous) (1)	Nm	91.5	83.7	82.3	103.5	104.8	102.9	
Dook Torque (+25%)	lb-ft	427	427	427	518	518	518	
Peak Torque (±25%)	Nm	578	578	578	703	703	703	
Peak Current	Α	383	256	170	467	280	200	
No Load Speed	RPM	280	584	778	287	538	769	
	rad/s	29	61	81	30	56	81	
Cogging Torque (may)	lb-ft	1.00			1.44			
Cogging Torque (max.)	Nm		1.36		1.95			
Torque Constant (±10%)	lb-ft/A	1.113	1.667	2.505	1.110	1.850	2.590	
Torque Constant (±10%)	Nm/A	1.509	2.60	3.396	1.505	2.508	3.512	
Voltage Constant (±10%)	V/kRPM	158	237	356	158	263	368	
Voltage Constant (±10%)	V/rad/s	1.509	2.60	3.396	1.505	2.508	3.512	
Motor Constant	lb-ft/√W	4.03	4.13	4.07	4.73	4.78	4.70	
WOOLOI CONSTANT	Nm/√W	5.46	5.60	5.52	6.41	6.48	6.37	
Elect. Time Constant	ms	6.46	6.80	6.58	6.64	6.77	6.5	
Mech. Time Constant	ms	0.87	0.82	0.85	0.86	0.84	0.87	
Terminal Resistance (±12%)	Ohm	0.076	0.63	0.379	0.055	0.150	0.304	
Terminal Inductance (±30%)	mH	0.493	1.108	2.494	0.366	1.016	1.991	
Thermal Resistance (1)	°C/W	0.293			0.235			
Mataninastia	lb-ft-s²	2.1E-2			2.8E-2			
Motor Inertia	kg-m²	2.8E-2			3.8E-2			
Matar Waight	lb	35.8	34.0	34.2	45.1	45.2	45.0	
Motor Weight	kg	16.26	15.43	15.53	20.44	20.49	20.41	
Ambient Storage Temperature	°C	-55 to 150						
Poles	-	40						
(1) Housed version of motor mounted to 406 mm sq. v 12.7 mm (16 in. sq. v 0.5 in.) aluminum plate in still air: maximum operating								

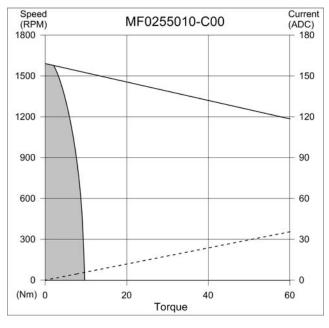
⁽¹⁾ Housed version of motor mounted to 406 mm sq. x 12.7 mm (16 in. sq. x 0.5 in.) aluminum plate in still air; maximum operating temperature (ambient + rise) is 130 $^{\circ}$ C

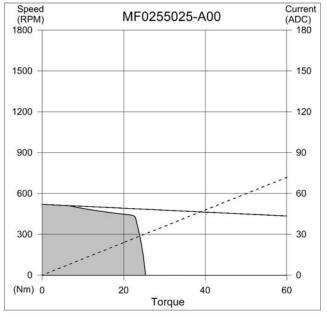


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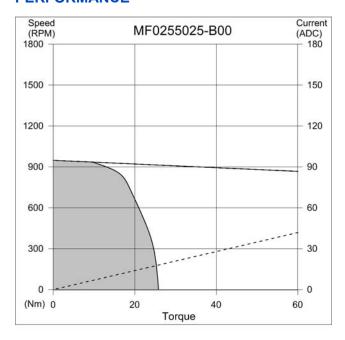


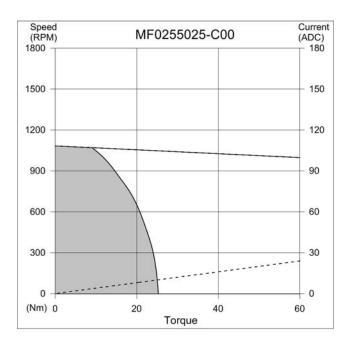


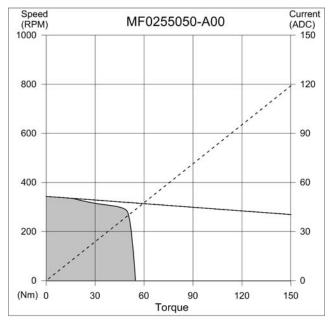


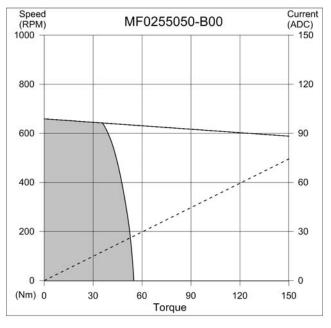


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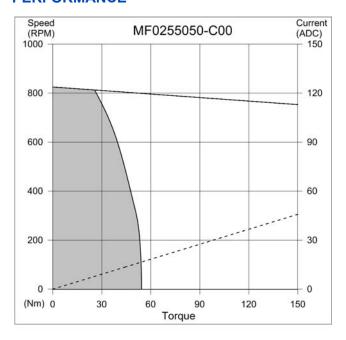


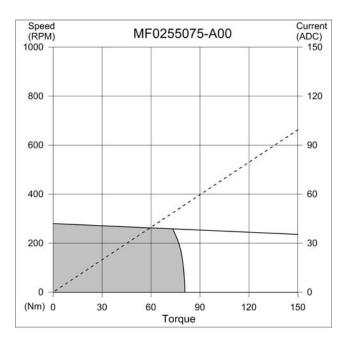


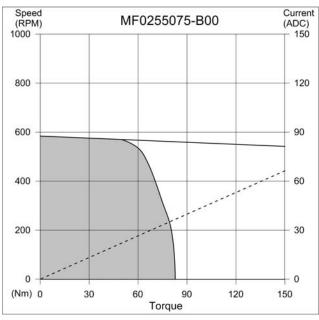


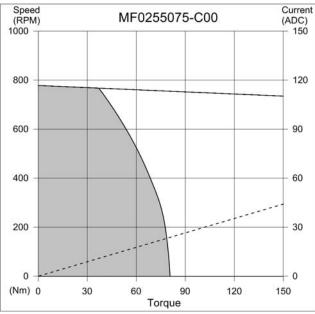


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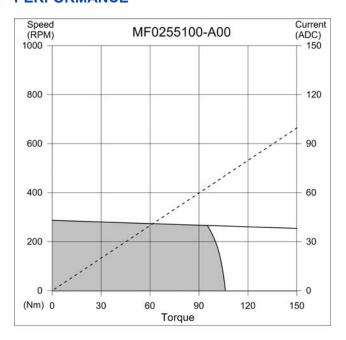


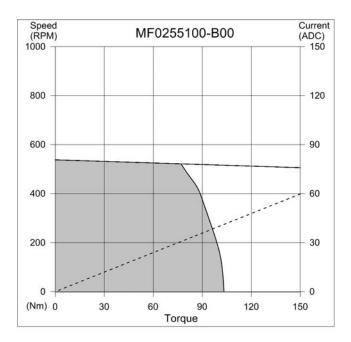


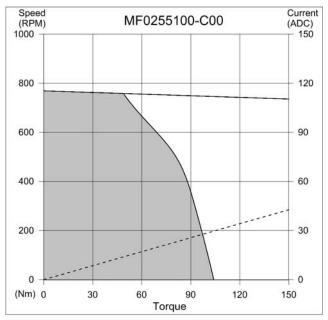


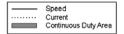


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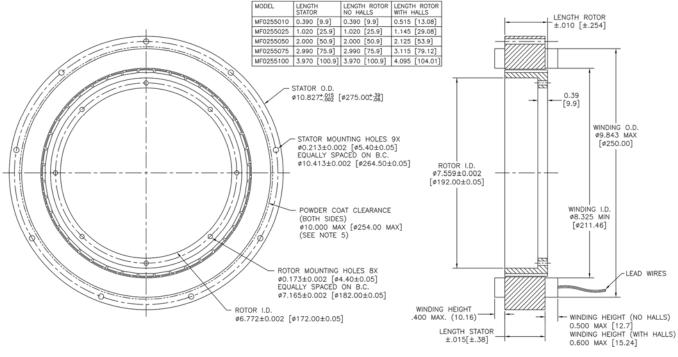






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DIMENSIONS



in (mm)



MODEL NUMBERING

