Heidrive

A Company of Allied Motion

HMD Next Generation - Servo drive systems

HeiMotion Dynamic

Introduction

The new highly dynamic HMD - Next Generation series presents itself with overall lengths reduced by over 20 % compared to the predecessor motors and strongly optimised moments of inertia. The considerable reduction in length and the variety of flange sizes offer the optimum, highly dynamic solution for particularly small installation space. Numerous voltage variants and the finest power gradations leave nothing to be desired.

The HeiMotion Dynamic motors are available in six different flange sizes:

- ☐ 60 mm - HMD06
- ☐ 80 mm - HMD08
- ☐ 100 mm - HMD10
- ☐ 130 mm - HMD13
- ☐ 150 mm - HMD15
- ☐ 190 mm - HMD19

Overview of features:

- 5 pole pairs
- Concentrated winding technology with high efficiency
- Voltage slope dU / dt 14 kV / µs due to encapsulated stator and special connection technology
- Temperature sensor KTY as standard, as well as PT1000 on request
- Shortened end caps as standard for various encoders and plug-in systems

Contents

Overview

HeiMotion Dynamic Next Generation motors

Type	Model	U_{bus} [V_{DC}]	I_o [A]	I_n [A]	M_o [Nm]	M_n [Nm]	M_{max} [Nm]	n_n [rpm]	J [kg-cm²]	P_n (S1) [W]
HMD06	HMD06-011	24	15.0	15.0	1.0	1.0	2.5	3,000	2.68E-01	315
		48	**8.4**	**8.4**	**1.0**	**1.0**	**2.5**	**3,000**	**2.68E-01**	**315**
		48	15.0	15.3	1.0	1.0	2.5	6,000	2.68E-01	630
		320	**1.2**	**1.2**	**1.0**	**1.0**	**2.5**	**3,000**	**2.68E-01**	**315**
		320	2.3	2.3	1.0	1.0	2.5	6,000	2.68E-01	630
		560	0.7	0.7	1.0	1.0	2.5	3,000	2.68E-01	315
		560	1.2	1.2	1.0	1.0	2.5	6,000	2.68E-01	630
	HMD06-019	**48**	**15.0**	**13.7**	**1.9**	**1.7**	**4.8**	**3,000**	**4.89E-01**	**530**
		320	**2.3**	**2.1**	**1.9**	**1.7**	**4.8**	**3,000**	**4.89E-01**	**530**
		320	4.1	3.8	1.9	1.45	4.8	6,000	4.89E-01	915
		560	1.2	1.1	1.9	1.7	4.8	3,000	4.89E-01	530
		560	2.3	2.1	1.9	1.45	4.8	6,000	4.89E-01	915
	HMD06-026	**48**	**19.5**	**19.0**	**2.6**	**2.5**	**6.5**	**3,000**	**7.11E-01**	**775**
		48	36.4	28.7	2.6	2.0	6.5	6,000	7.11E-01	1,250
		320	**3.0**	**3.0**	**2.6**	**2.5**	**6.5**	**3,000**	**7.11E-01**	**775**
		320	5.5	4.5	2.6	2.0	6.5	6,000	7.11E-01	1,250
		560	1.6	1.6	2.6	2.5	6.5	3,000	7.11E-01	775
		560	2.5	2.5	2.6	2.0	6.5	6,000	7.11E-01	1,250
HMD08	HMD08-024	24	45.0	44.9	2.4	2.3	6.0	3,000	8.00E-01	720
		48	**24.3**	**23.3**	**2.4**	**2.3**	**6.0**	**3,000**	**8.00E-01**	**720**
		48	45.0	42.0	2.4	2.1	6.0	5,500	8.00E-01	1,210
		320	**3.4**	**3.3**	**2.4**	**2.3**	**6.0**	**3,000**	**8.00E-01**	**720**
		320	5.6	5.4	2.4	2.1	6.0	5,500	8.00E-01	1,210
		560	**2.0**	**1.9**	**2.4**	**2.3**	**6.0**	**3,000**	**8.00E-01**	**720**
		560	3.4	3.1	2.4	2.1	6.0	5,500	8.00E-01	1,210
	HMD08-032	24	50.0	48.7	3.2	3.0	8.0	3,000	1.13E+00	940
		48	**26.2**	**25.9**	**3.2**	**3.0**	**8.0**	**3,000**	**1.13E+00**	**940**
		48	50.0	44.0	3.2	2.6	8.0	5,500	1.13E+00	1,500
		320	**4.2**	**4.1**	**3.2**	**3.0**	**8.0**	**3,000**	**1.13E+00**	**940**
		320	7.1	6.4	3.2	2.6	8.0	5,500	1.13E+00	1,500
		560	**2.2**	**2.1**	**3.2**	**3.0**	**8.0**	**3,000**	**1.13E+00**	**940**
		560	4.2	3.6	3.2	2.6	8.0	5,500	1.13E+00	1,500
	HMD08-042	24	58.4	57.6	4.2	3.9	10.5	3,000	1.46E+00	1,225
		48	**33.0**	**30.8**	**4.2**	**3.9**	**10.5**	**3,000**	**1.46E+00**	**1,225**
		48	60.8	52.3	4.2	3.4	10.5	5,500	1.46E+00	1,950
		320	**5.0**	**4.6**	**4.2**	**3.9**	**10.5**	**3,000**	**1.46E+00**	**1,225**
		320	8.5	7.4	4.2	3.4	10.5	5,500	1.46E+00	1,950
		560	**2.7**	**2.6**	**4.2**	**3.9**	**10.5**	**3,000**	**1.46E+00**	**1,225**
		560	5.0	4.1	4.2	3.4	10.5	5,500	1.46E+00	1,950
	HMD08-057	**48**	**48.0**	**45.8**	**5.7**	**5.3**	**14.3**	**3,000**	**2.12E+00**	**1,665**
		320	**6.6**	**6.3**	**5.7**	**5.3**	**14.3**	**3,000**	**2.12E+00**	**1,665**
		320	11.4	8.9	5.7	4.3	14.3	5,500	2.12E+00	2,480
		560	**3.6**	**3.4**	**5.7**	**5.3**	**14.3**	**3,000**	**2.12E+00**	**1,665**
		560	6.6	5.3	5.7	4.3	14.3	5,500	2.12E+00	2,480

Type	Model	U_{bus} [V_{DC}]	I_o [A]	I_n [A]	M_o [Nm]	M_n [Nm]	M_{max} [Nm]	n_n [rpm]	J [kg-cm²]	P_n (S1) [W]
HMD10	HMD10-039	**48**	**34.6**	**32.9**	**3.9**	**3.6**	**9.8**	**3,000**	**1.94E+00**	**1,130**
		48	56.0	48.5	3.9	3.2	9.8	5,000	1.94E+00	1,675
		320	**5.0**	**4.7**	**3.9**	**3.6**	**9.8**	**3,000**	**1.94E+00**	**1,130**
		320	8.2	7.0	3.9	3.2	9.8	5,000	1.94E+00	1,675
		560	**2.8**	**2.7**	**3.9**	**3.6**	**9.8**	**3,000**	**1.94E+00**	**1,130**
		560	5.0	4.3	3.9	3.2	9.8	5,000	1.94E+00	1,675
	HMD10-057	**48**	**47.1**	**44.4**	**5.7**	**5.2**	**14.3**	**3,000**	**2.75E+00**	**1,635**
		48	70.6	53.3	5.7	4.0	14.3	5,000	2.75E+00	2,095
		320	**6.5**	**6.1**	**5.7**	**5.2**	**14.3**	**3,000**	**2.75E+00**	**1,635**
		320	10.2	7.6	5.7	4.0	14.3	5,000	2.75E+00	2,095
		560	**3.6**	**3.4**	**5.7**	**5.2**	**14.3**	**3,000**	**2.75E+00**	**1,635**
		560	6.5	4.8	5.7	4.0	14.3	5,000	2.75E+00	2,095
	HMD10-076	**48**	**57.7**	**50.3**	**7.6**	**6.5**	**19.0**	**3,000**	**3.57E+00**	**2,000**
		320	**9.1**	**8.0**	**7.6**	**6.5**	**19.0**	**3,000**	**3.57E+00**	**2,000**
		320	13.5	9.4	7.6	4.8	19.0	5,000	3.57E+00	2,500
		560	**4.9**	**4.3**	**7.6**	**6.5**	**19.0**	**3,000**	**3.57E+00**	**2,000**
		560	9.1	6.3	7.6	4.8	19.0	5,000	3.57E+00	2,500
	HMD10-105	**48**	**82.3**	**70.6**	**10.5**	**8.6**	**26.3**	**3,000**	**5.21E+00**	**2,700**
		320	**11.0**	**9.0**	**10.5**	**8.6**	**26.3**	**3,000**	**5.21E+00**	**2,700**
		320	18.0	10.6	10.5	5.5	26.3	5,000	5.21E+00	2,900
		560	**6.4**	**5.5**	**10.5**	**8.6**	**26.3**	**3,000**	**5.21E+00**	**2,700**
		560	6.5	9.0	10.5	5.5	26.3	5,000	5.21E+00	2,900
HMD13	HMD13-133	560	5.5	4.8	13.3	11.5	33.3	2,000	8.21E+00	2,400
		560	**9.3**	**6.3**	**13.3**	**9.0**	**33.3**	**3,600**	**8.21E+00**	**3,400**
	HMD13-190	560	7.5	6.3	19.0	16.0	47.5	2,000	1.20E+01	3,350
		560	**13.7**	**8.2**	**19.0**	**11.2**	**47.5**	**3,600**	**1.20E+01**	**4,200**
	HMD13-245	560	9.7	8.2	24.5	20.5	61.3	2,000	1.58E+01	4,300
		560	**17.1**	**9.6**	**24.5**	**13.3**	**61.3**	**3,600**	**1.58E+01**	**5,000**
HMD15	HMD15-036	560	15.1	11.7	36.0	28.0	72.0	2,000	3.87E+01	5,850
		560	**22.6**	**13.2**	**36.0**	**21.0**	**72.0**	**3,000**	**3.87E+01**	**6,600**
	HMD15-043	560	18.0	13.8	42.5	32.5	85.0	2,000	4.82E+01	6,800
		560	**26.0**	**15.3**	**42.5**	**25.0**	**85.0**	**3,000**	**4.82E+01**	**7,850**
	HMD15-049	560	20.4	15.5	49.0	37.0	98.0	2,000	5.76E+01	7,750
		560	**30.0**	**17.8**	**49.0**	**29.0**	**98.0**	**3,000**	**5.76E+01**	**9,110**
HMD19	HMD19-051	560	24.5	16.6	51.0	35.5	102.0	2,000	7.42E+01	7,435
		560	35.9	17.6	51.0	25.5	102.0	3,000	7.42E+01	8,000
	HMD19-078	**560**	**38.0**	**24.4**	**78.0**	**51.5**	**156.0**	**2,000**	**1.10E+02**	**10,780**
		560	56.6	24.1	78.0	34.0	156.0	3,000	1.10E+02	10,680
	HMD19-105	**560**	**52.5**	**32.5**	**105.0**	**66.5**	**210.0**	**2,000**	**1.45E+02**	**13,920**

Standard version

If rated current > 30 A observe connection technology (p. 76) and encoder selection (p. 74)!

Overview

HeiMotion Dynamic motors mating servo drive matrix

Type	Model	n [rpm]	U_{bus} [V_{DC}]	I_o [A]	HCD 1 x 230 V_{AC}	HCB 1 x 230 V_{AC}	HCB 3 x 400 V_{AC}	HCF 24 - 48 V_{DC}	HCJ 1 x 230 V_{AC}	HCJ 3 x 400 V_{AC}
HMD06	HMD06-011	3000	24	15						HCJ 24.016 *
		3000	48	8,4				HCF		HCJ 24.012 *
		6000	48	15						HCJ 24.016 *
		3000	320	1,2	HCD	HCB 2/6-1	HCB 4/12-3		HCJ 22.003	HCJ 24.002
		6000	320	2,3	HCD	HCB 4/12-1	HCB 4/12-3		HCJ 22.003	HCJ 24.004
		3000	560	0,7	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.002
		6000	560	1,2	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.002
	HMD06-019	3000	48	15						HCJ 24.016 *
		3000	320	2,3	HCD	HCB 4/12-1	HCB 4/12-3		HCJ 22.003	HCJ 24.004
		6000	320	4,1			HCB 8/24-3		HCJ 22.006	HCJ 24.007
		3000	560	1,2	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.002
		6000	560	2,3	HCD	HCB 4/12-1	HCB 4/12-3		HCJ 22.003	HCJ 24.004
	HMD06-026	3000	48	19,5						
		6000	48	36,4						
		3000	320	3	HCD	HCB 4/12-1	HCB 4/12-3		HCJ 22.003	HCJ 24.004
		6000	320	5,5			HCB 8/24-3		HCJ 22.006	HCJ 24.007
		3000	560	1,6	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.002
		6000	560	3,0	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.004
HMD08	HMD08-024	3000	24	45						
		3000	48	24,3						
		5500	48	45						
		3000	320	3,4	HCD	HCB 4/12-1	HCB 4/12-3		HCJ 22.006	HCJ 24.004
		5500	320	5,6			HCB 8/24-3		HCJ 22.006	HCJ 24.007
		3000	560	2,0	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.002
		5500	560	3,4	HCD		HCB 4/12-3		HCJ 22.006	HCJ 24.004
	HMD08-032	3000	24	50						
		3000	48	26,2						
		5500	48	50						
		3000	320	4,2			HCB 8/24-3		HCJ 22.006	HCJ 24.007
		5500	320	7,1			HCB 8/24-3		HCJ 22.008	HCJ 24.012
		3000	560	2,2	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.004
		5500	560	4,2	HCD		HCB 8/24-3		HCJ 22.006	HCJ 24.007
	HMD08-042	3000	24	58,4						
		3000	48	33						
		5500	48	58,4						
		3000	320	5			HCB 8/24-3		HCJ 22.006	HCJ 24.007
		5500	320	8,5			HCB 12/30-3			HCJ 24.012
		3000	560	2,7	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.004
		5500	560	5			HCB 8/24-3		HCJ 22.006	HCJ 24.007
	HMD08-057	3000	24	76,6						
		3000	48	48						
		5500	48	76,6						
		3000	320	6,6			HCB 8/24-3		HCJ 22.008	HCJ 24.012
		5500	320	11,4			HCB 12/30-3			HCJ 24.012
		3000	560	3,6	HCD		HCB 4/12-3		HCJ 22.006	HCJ 24.007
		5500	560	6,6			HCB 8/24-3		HCJ 22.008	HCJ 24.012

Type	Model	n [rpm]	U_{bus} [V_{DC}]	I_o [A]	HCD 1 x 230 V_{AC}	HCB 1 x 230 V_{AC}	HCB 3 x 400 V_{AC}	HCF 24 - 48 V_{DC}	HCJ 1 x 230 V_{AC}	HCJ 3 x 400 V_{AC}
HMD10	HMD10-039	3000	48	34,6						
		5000	48	56						
		3000	320	5			HCB 8/24-3		HCJ 22.006	HCJ 24.007
		5000	320	8,2			HCB 12/30-3			HCJ 24.012
		3000	560	2,8	HCD		HCB 4/12-3		HCJ 22.003	HCJ 24.004
		5000	560	5			HCB 8/24-3		HCJ 22.006	HCJ 24.007
	HMD10-057	3000	48	47,1						
		5000	48	70,6						
		3000	320	6,5			HCB 8/24-3			HCJ 24.007
		5000	320	10,2			HCB 12/30-3			HCJ 24.012
		3000	560	3,6	HCD		HCB 4/12-3		HCJ 22.006	HCJ 24.012
		5000	560	6,5			HCB 8/24-3		HCJ 22.008	HCJ 24.007
	HMD10-076	3000	48	57,7						
		3000	320	9,1			HCB 12/30-3			HCJ 24.012
		5000	320	13,5						HCJ 24.012
		3000	560	4,9			HCB 8/24-3		HCJ 22.006	HCJ 24.007
		5000	560	9,1			HCB 12/30-3			HCJ 24.012
	HMD10-105	3000	48	82,3						
		3000	320	11			HCB 12/30-3			HCJ 24.012
		5000	320	18						
		3000	560	6,4			HCB 8/24-3		HCJ 22.008	HCJ 24.007
		5000	560	11			HCB 12/30-3		HCJ 22.008	HCJ 24.007
HMD13	HMD13-133	2000	560	5,5			HCB 8/24-3		HCJ 22.008	HCJ 24.007
		3600	560	9,3			HCB 12/30-3			HCJ 24.012
	HMD13-190	2000	560	7,5			HCB 8/24-3		HCJ 22.008	HCJ 24.012
		3600	560	13,7						HCJ 24.016
	HMD13-245	2000	560	9,7			HCB 12/30-3			HCJ 24.012
		3600	560	17,1						
HMD15	HMD15-036	2000	560	15,1						HCJ 24.016
		3000	560	22,6						
	HMD15-043	2000	560	18						
		3000	560	26						
	HMD15-049	2000	560	20,4						
		3000	560	30						
HMD19	HMD19-051	2000	560	24,5						
		3000	560	35,9						
	HMD19-078	2000	560	38						
		3000	560	56,6						
	HMD19-105	2000	560	52,5						

HCD
p. 100

HCB
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HCF
p. 106

HCJ
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* Power adapter required

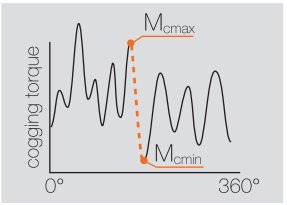
General information

Ambient conditions and technical characteristics

Motor type		Permanent magnet three-phase synchronous servo motor
Ambient operating temperature		- 10 °C to + 40 °C
Ambient storage temperature		- 25 °C to + 70 °C
Humidity		< 90 % relative humidity (without condensation)
Insulation class		F (155 °C) Δ T = 115 K
Pollution level		2
Protection class		IP65 (standard version), (except drive end, protection class is IP21, without shaft oil seal)
Cooling		Natural convective
Overvoltage category		II max. 4000 meters above sea level; III max. 3000 meters above sea level
Bearing life		20,000 h under rated operation conditions (M_n)
Temperature sensor		KTY84-130
Voltage slew rate dU/dt		14 kV / µs
Maximum altitude		4,000 meters above sealevel; derate 1% per 100 meters above 1,000 meters
Concentricity, coaxiality and axial run-out		N (normal) per DIN 42955
Vibration		Stage N in accordance to ISO 2373
Cogging torque factor c_t	HMD06	< 2.0 % based on the stall torque (M_0)
	HMD08	< 1.5 % based on the stall torque (M_0)
	HMD10	< 1.2 % based on the stall torque (M_0)
	HMD13	< 1.0 % based on the stall torque (M_0)
	HMD15	< 1.0 % based on the stall torque (M_0)
	HMD19	< 1.0 % based on the stall torque (M_0)
Coating		Black top coat, RAL 9005
Magnet material		Neodymium-Iron-Boron (NdFeB)
Shaft end		Cylindrical shaft end with / without keyway
Balancing quality		Q 2.5
Encoder systems		Resolver, HIPERFACE®, HIPERFACE DSL®, Incremental encoder, SSI/BiSS, EnDat 2.2
Approvals		CE, c UL us - certification (see E341694)

Abbreviations and definitions

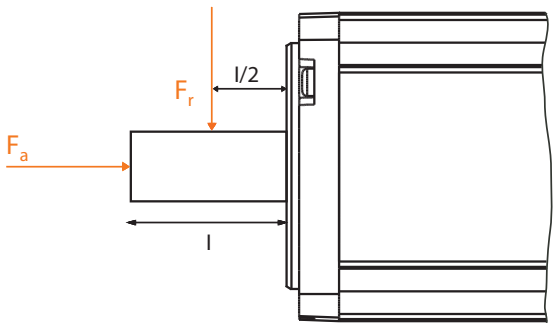
Abbr.	Unit	Explanation
f_n	[Hz]	Rated frequency
I_0	[A_{rms}]	Stall current per phase (motor current at stall torque M_0)
I_n	[A_{rms}]	Rated current (rated current per phase)
I_{max}	[A_{rms}]	Peak current (maximum permissible current per phase)
J	[kg-cm^2]	Moment of inertia rotor (motor without brake)
k_e	[V_{rms} / krpm]	Voltage constant (induced voltage between two phases at 1,000 rpm) rms (root mean square value)
k_{tn}	[Nm / A_{rms}]	Torque constant (rms) at nominal point at 20 °C
L_{p-p}	[mH]	Winding inductance (2 phases) at rated current I_n
m	[kg]	Weight (motor without brake)
M_0	[Nm]	Stall torque (stall torque at S1)
M_n	[Nm]	Rated torque (continuous torque at S1)
M_{max}	[Nm]	Peak torque (maximum permissible torque for short periods)
n_n	[rpm]	Rated speed
n_{max}	[rpm]	Maximum speed
P_n	[W]	Rated power (mechanical power at the shaft)
R_{p-p}	[Ω]	Winding resistance (2 phases, at winding temperature of 20 °C)
c_t	[%]	Local cogging torque $c_t = \frac{M_{cmax} - M_{cmin}}{M_0} \times 100\ \%$
M_{cmax}	[Nm]	Local maximum of the cogging torque
M_{cmin}	[Nm]	Local minimum of the cogging torque
T_{el}	[ms]	Electrical time constant
T_{th}	[min]	Thermal time constant
U_{mot}	[V_{rms}]	Rated motor voltage (2 phases at rated working point), rms
U_{bus}	[V_{DC}]	DC bus voltage



Life span

Shaft loading forces

Life span of the motors is at least 20,000 hours if operated under rated conditions. The table below shows admissible radial forces for the bearing load. Point of force application is in the middle of the shaft (see drawing).



Maximum radial force F_r, [N]

	1,000 [rpm]	2,000 [rpm]	3,000 [rpm]	4,000 [rpm]	5,000 [rpm]	6,000 [rpm]	7,000 [rpm]	8,000 [rpm]	9,000 [rpm]	10,000 [rpm]
HMD06-011	355	280	245	220	205	195	185	175	170	160
HMD06-019	390	310	270	240	230	210	200	190	185	180
HMD06-026	400	320	280	260	240	220	210	200	195	190
HMD08-024	430	340	300	270	250	240	225	215	-	-
HMD08-032	460	370	320	290	270	250	240	230	-	-
HMD08-042	480	380	330	300	280	265	250	240	-	-
HMD08-057	510	410	350	320	300	280	270	260	-	-
HMD10-039	800	640	560	510	470	440	420	-	-	-
HMD10-057	850	670	590	535	500	470	445	-	-	-
HMD10-076	885	705	615	560	520	490	465	-	-	-
HMD10-105	940	740	650	615	570	540	510	-	-	-
HMD13-133	1260	1000	880	790	740	-	-	-	-	-
HMD13-190	1340	1070	930	840	780	-	-	-	-	-
HMD13-245	1400	1110	970	880	820	-	-	-	-	-
HMD15-036	1640	1300	1140	1030	-	-	-	-	-	-
HMD15-043	1690	1340	1170	1070	-	-	-	-	-	-
HMD15-049	1730	1370	1200	1090	-	-	-	-	-	-
HMD19-051	2390	1900	1660	1510	-	-	-	-	-	-
HMD19-078	2530	2010	1750	1590	-	-	-	-	-	-
HMD19-105	2620	2080	1810	1650	-	-	-	-	-	-

Maximum axial force: $F_a = 0.2 \times F_r$

At stall, a one-time axial force of 40 % of the radial force may be applied during motor mounting. Maximum allowed axial and radial forces must not occur together at the same time.

Order code

HMD08-024-320-30-BPH2MW23W

Frame/flange size

60 mm	→	06
80 mm	→	08
100 mm	→	10
130 mm	→	13
150 mm	→	15
190 mm	→	19

Stall torque

1.1 Nm	→	011
1.9 Nm	→	019
2.4 Nm	→	024
2.6 Nm	→	026
3.2 Nm	→	032
3.9 Nm	→	039
4.2 Nm	→	042
5.7 Nm	→	057
7.6 Nm	→	076
10.5 Nm	→	105
13.3 Nm	→	133
19.0 Nm	→	190
24.5 Nm	→	245
36.0 Nm	→	036
42.5 Nm	→	043
49.0 Nm	→	049
51.0 Nm	→	051
78.0 Nm	→	078
105.0 Nm	→	105

DC bus voltage

24 V	→	024
48 V	→	048
320 V	→	320
560 V	→	560

Rated speed

2,000 rpm	→	20
3,000 rpm	→	30
3,600 rpm	→	36
5,000 rpm	→	50
5,500 rpm	→	55
6,000 rpm	→	60

Options

Without brake	0XXXXXXX
With brake	BXXXXXXX
Without feather key	X0XXXXXX
With feather key	XPXXXXXX
Resolver	XXR1PXXX
Resolver safely mounted	XXRAPXXX
HES 1 (1.0 V_{p-p})	XXM2SXXX
HEM 1 (1.0 V_{p-p} without battery)	XXM1MXXX
HEM 1 (1.0 V_{p-p} with battery)	XXM2MXXX
HES 3	XXM1IXXX
HS16	XXS1SXXX
HM16	XXB1MXXX
ECI 1118	XXE1SXXX
EQI 1131	XXE1MXXX
ECI 1319	XXE3SXXX
EQI 1331	XXE3MXXX
SEK 37	XXH1SXXX
SEL 37	XXH1MXXX
SKS 36	XXH2SXXX
SKS 36S safely mounted	XXHBSXXX
SKM 36	XXH2MXXX
SKM 36S safely mounted	XXHBMXXX
SRS 50	XXH3SXXX
SRM 50	XXH3MXXX
EES 37	XXD1SXXX
EES 37-2 safely mounted	XXDASXXX
EEM 37	XXD1MXXX
EEM 37-2 safely mounted	XXDAMXXX
EKS 36	XXD2SXXX
EKS 36-2 safely mounted	XXDBSXXX
EKM 36	XXD2MXXX
EKM 36-2 safely mounted	XXDBMXXX
CKS 36	XXI1SXXX
M23 angled	XXXXXW23X
M40 angled	XXXXXW40X
Y-Tec	XXXXXY17X
I-Tec	XXXXXI17X
Cable outlet 1.5 m[1]	XXXXXK15X
Cable outlet 5 m[1]	XXXXXK50X
Terminal box[1,2]	XXXXXKB0X
Terminal box[1,2]	XXXXXKB2X
Terminal box[1,2]	XXXXXKA0X
Terminal box[1,2]	XXXXXKA2X
Without radial shaft seal	XXXXXXXX0
With radial shaft seal	XXXXXXXXW

1) Upon request
2) Mounting direction and cable gland see page 96/97

Example: HMD08-024-320-30-BPH2MW23W

- Frame/flange size 80 mm
- Stall torque 2.4 Nm
- DC bus voltage 320 V
- Rated speed 3,000 rpm

Options:
- With brake
- Without feather key
- Encoder SKM 36
- Angled connector M23
- With radial shaft seal

HMD06-011

24 / 48 V

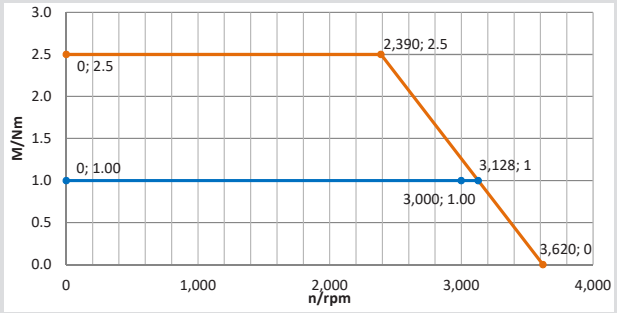
Specifications

		HMD06-011		
Rated speed [rpm]	n_n	3,000	3,000	6,000
Number of pole pairs		5	5	5
Wiring of the motor winding		Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	24	48	48
Rated voltage motor [V_{rms}]	U_{mot}	14.4	26.0	27.2
Rated power [W] [1)]	P_n	315	315	630
Rated torque [Nm]	M_n	1.0	1.0	1.0
Rated current per phase [A_{rms}]	I_n	15.0	8.4	15.0
Stall torque [Nm]	**M_0**	**1.0**	**1.0**	**1.0**
Stall current per phase [A_{rms}]	I_0	15.0	8.4	15.0
Peak torque [Nm]	M_{max}	2.5	2.5	2.5
Peak current [A_{rms}]	I_{max}	37.5	21.0	37.5
Maximum speed [rpm]	n_{max}	3,620	4,060	7,410
Voltage constant at 1,000 rpm [V_{rms}]	k_e	4.2	7.7	4.2
Torque constant [Nm / A_{rms}]	k_t	0.07	0.12	0.07
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.126	0.41	0.126
Winding inductance (2 phases) [mH]	L_{p-p}	0.138	0.445	0.138
Electrical time constant [ms]	t_{el}	1.1	1.1	1.1
Thermal time constant [min]	t_{th}	25	25	25
Moment of inertia rotor [kg-cm²]	J	2.68E-01	2.68E-01	2.68E-01
Weight of motor [kg]	m	1.2	1.2	1.2

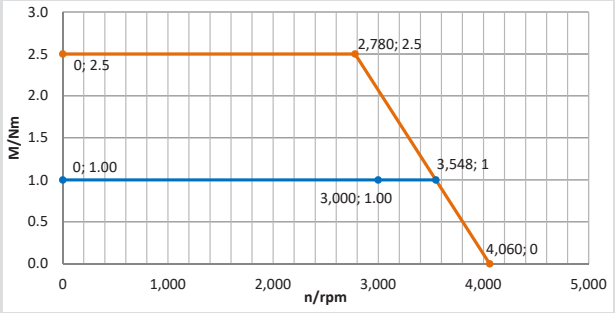
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

HMD06-011-024-30-*

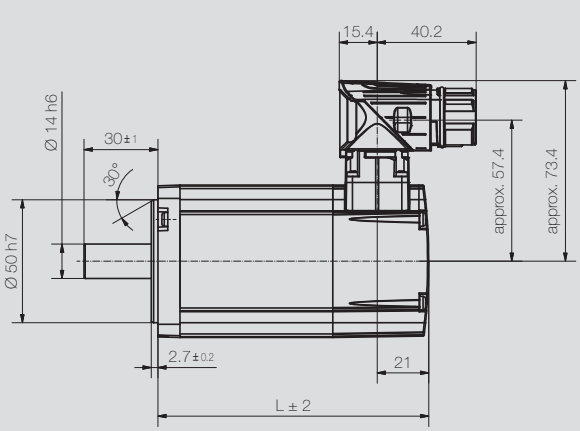


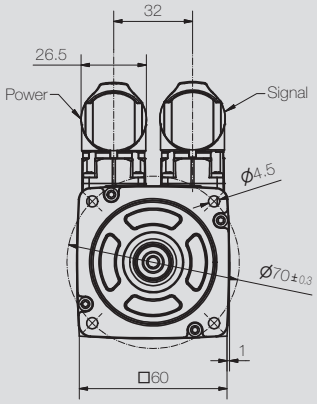
HMD06-011-048-30-*

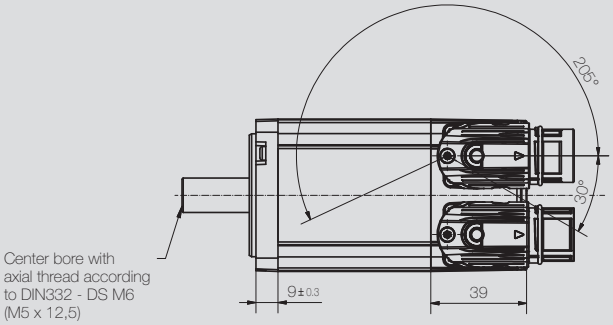


[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values

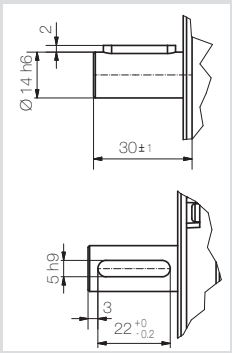
Dimensions





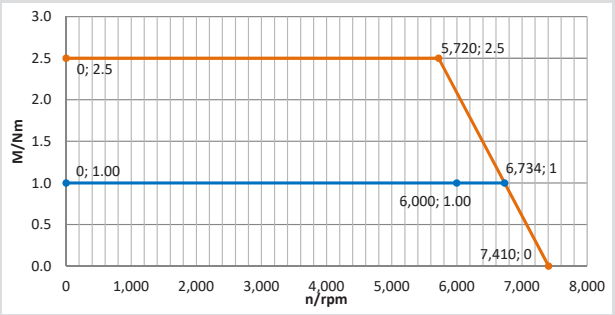


Feather key (option)



	L [mm]	
Motor	without Brake	with Brake
HMD06-011	110 mm	149 mm

HMD06-011-048-60-*



HMD06-011

320 / 560 V

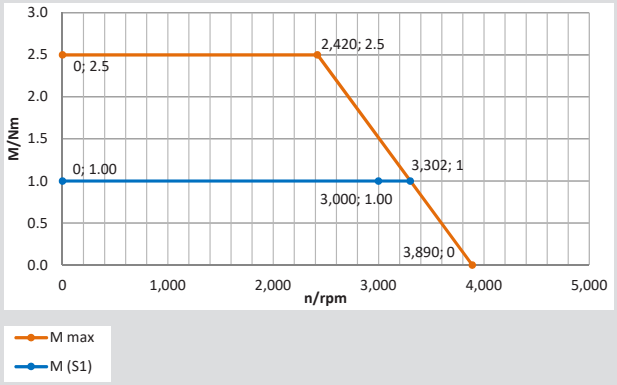
Specifications

		HMD06-011			
Rated speed [rpm]	n_n	3,000	6,000	3,000	6,000
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	188	185	301	351
Rated power [W]	P_n	315	630	315	630
Rated torque [Nm]	M_n	1.0	1.0	1.0	1.0
Rated current per phase [A_{rms}]	I_n	1.2	2.3	0.7	1.2
Stall torque [Nm]	**M_0**	**1.0**	**1.0**	**1.0**	**1.0**
Stall current per phase [A_{rms}]	I_0	1.2	2.3	0.7	1.2
Peak torque [Nm]	M_{max}	2.5	2.5	2.5	2.5
Peak current [A_{rms}]	I_{max}	3.0	5.8	1.9	3.0
Maximum speed [rpm]	n_{max}	3,890	7,520	4,320	7,160
Voltage constant at 1,000 rpm [V_{rms}]	k_e	54.2	28.0	85.4	54.2
Torque constant [Nm / A_{rms}]	k_t	0.83	0,44	1.35	0.83
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	23.8	6.6	61.4	23.8
Winding inductance (2 phases) [mH]	L_{p-p}	25.5	7.0	65.2	25.20
Electrical time constant [ms]	t_{el}	1.1	1.1	1.1	1.1
Thermal time constant [min]	t_{th}	25	25	25	25
Moment of inertia rotor [kg-cm²]	J	2.68E-01	2.68E-01	2.68E-01	2.68E-01
Weight of motor [kg]	m	1.2	1.2	1.2	1.2

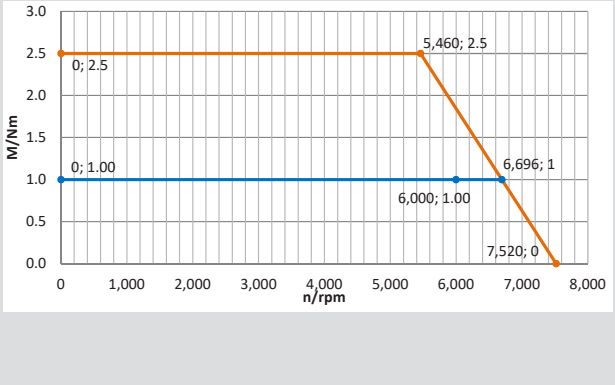
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

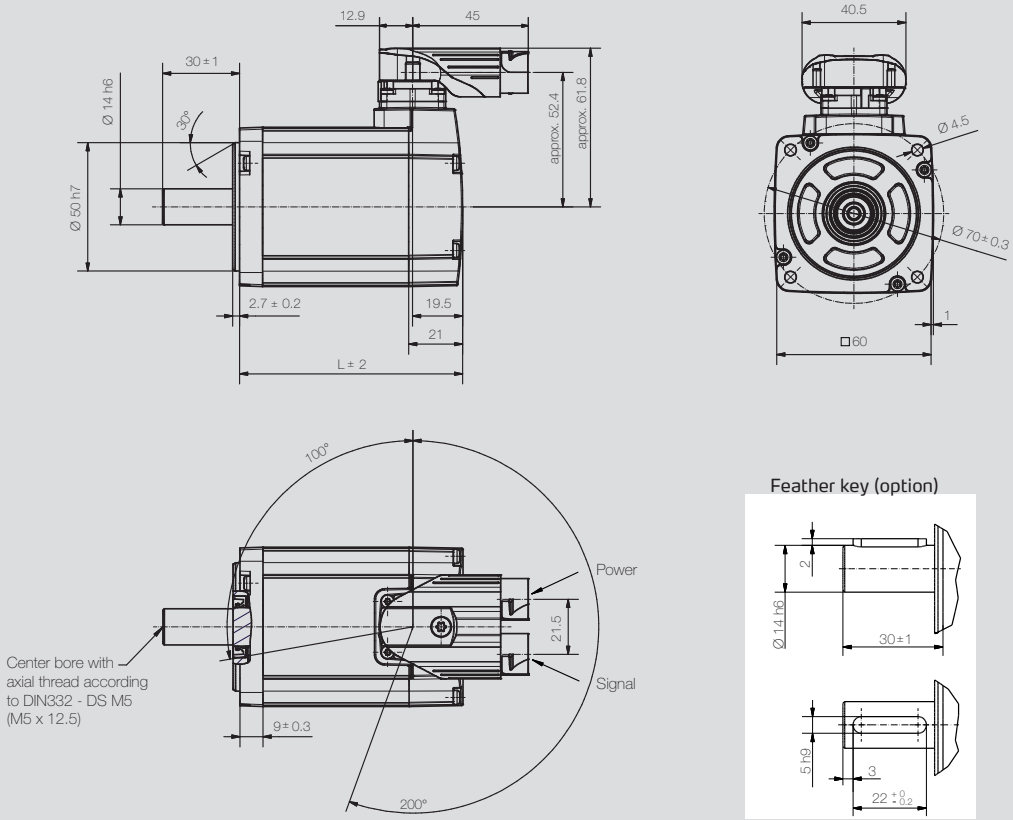
HMD06-011-320-30-*



HMD06-011-320-60-*



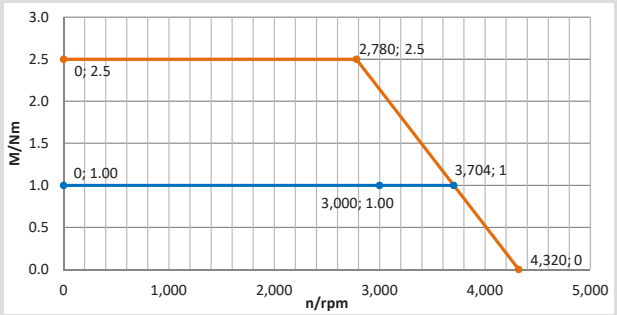
Dimensions



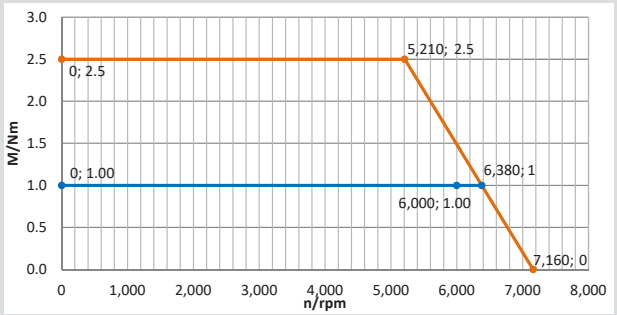
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD06-011	92 mm	131 mm	110 mm	149 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M 16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD06-011-560-30-*



HMD06-011-560-60-*



HMD06-019

48 V

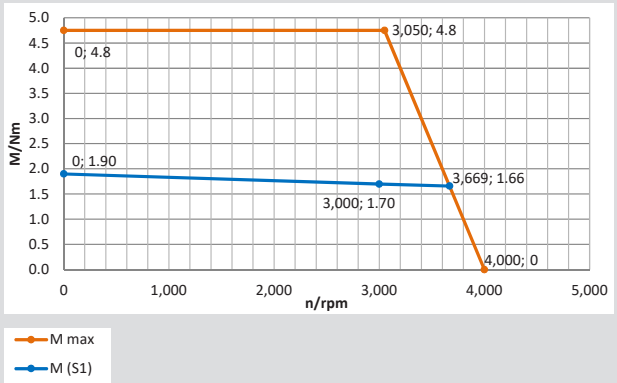
Specifications

		HMD06-019
Rated speed [rpm]	n_n	3,000
Number of pole pairs		5
Wiring of the motor winding		Y
DC bus voltage [V_{DC}]	U_{bus}	48
Rated voltage motor [V_{rms}]	U_{mot}	25.4
Rated power [W] [1)]	P_n	530
Rated torque [Nm]	M_n	1.7
Rated current per phase [A_{rms}]	I_n	13.7
Stall torque [Nm]	**M_0**	**1.9**
Stall current per phase [A_{rms}]	I_0	15.0
Peak torque [Nm]	M_{max}	4.8
Peak current [A_{rms}]	I_{max}	37.5
Maximum speed [rpm]	n_{max}	4,000
Voltage constant at 1,000 rpm [V_{rms}]	k_e	7.8
Torque constant [Nm / A_{rms}]	k_t	0.12
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.160
Winding inductance (2 phases) [mH]	L_{p-p}	0.22
Electrical time constant [ms]	t_{el}	1.4
Thermal time constant [min]	t_{th}	25
Moment of inertia rotor [kg-cm²]	J	4.89E-01
Weight of motor [kg]	m	1.6

For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

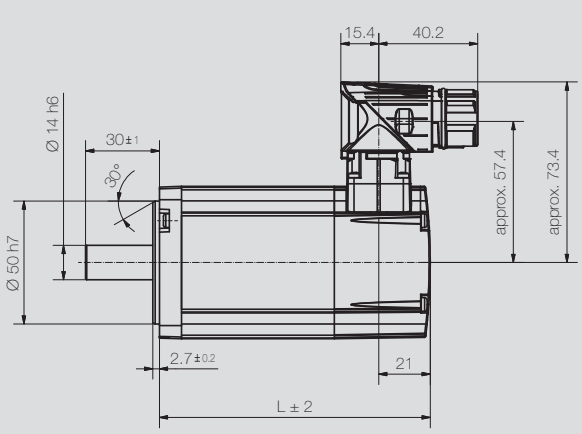
Performance

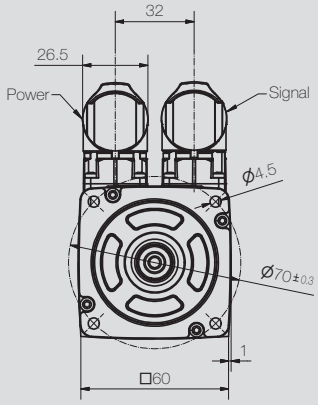
HMD06-019-048-30-*

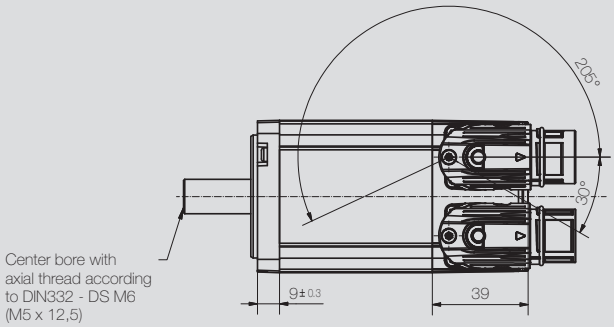


[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions

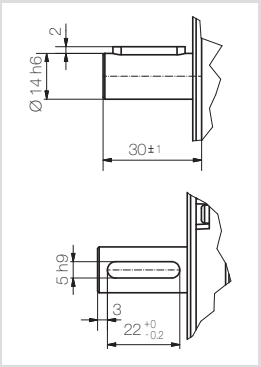






Center bore with axial thread according to DIN332 - DS M6 (M5 x 12,5)

Feather key (option)



	L [mm]	
Motor	without Brake	with Brake
HMD06-019	135 mm	174 mm

HMD06-019

320 / 560 V

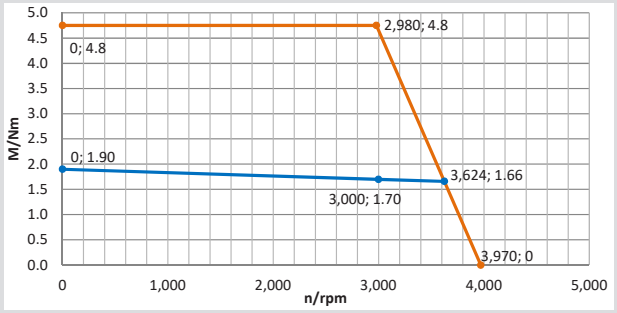
Specifications

		HMD06-019			
Rated speed [rpm]	n_n	3,000	6,000	3,000	6,000
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	173	178	331	329
Rated power [W]	P_n	530	915	530	915
Rated torque [Nm]	M_n	1.7	1.45	1.7	1.45
Rated current per phase [A_{rms}]	I_n	2.1	3.3	1.1	1.8
Stall torque [Nm]	**M_0**	**1.9**	**1.9**	**1.9**	**1.9**
Stall current per phase [A_{rms}]	I_0	2.3	4.1	1.2	2.3
Peak torque [Nm]	M_{max}	4.8	4.8	4.8	4.8
Peak current [A_{rms}]	I_{max}	5.8	10.3	2.9	5.8
Maximum speed [rpm]	n_{max}	3,970	7,390	3,610	6,940
Voltage constant at 1,000 rpm [V_{rms}]	k_e	53.1	28.5	102.0	53.1
Torque constant [Nm / A_{rms}]	k_t	0.81	0.44	1.55	0.83
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	7.46	2.18	27.40	7.46
Winding inductance (2 phases) [mH]	L_{p-p}	10.15	2.96	37.33	10.15
Electrical time constant [ms]	t_{el}	1.4	1.4	1.4	1.4
Thermal time constant [min]	t_{th}	25	25	25	25
Moment of inertia rotor [kg-cm²]	J	4.89E-01	4.89E-01	4.89E-01	4.89E-01
Weight of motor [kg]	m	1.6	1.6	1.6	1.6

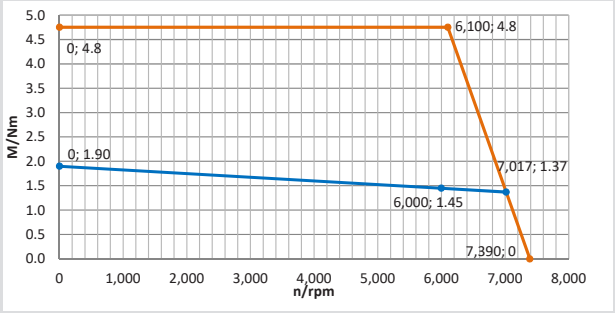
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

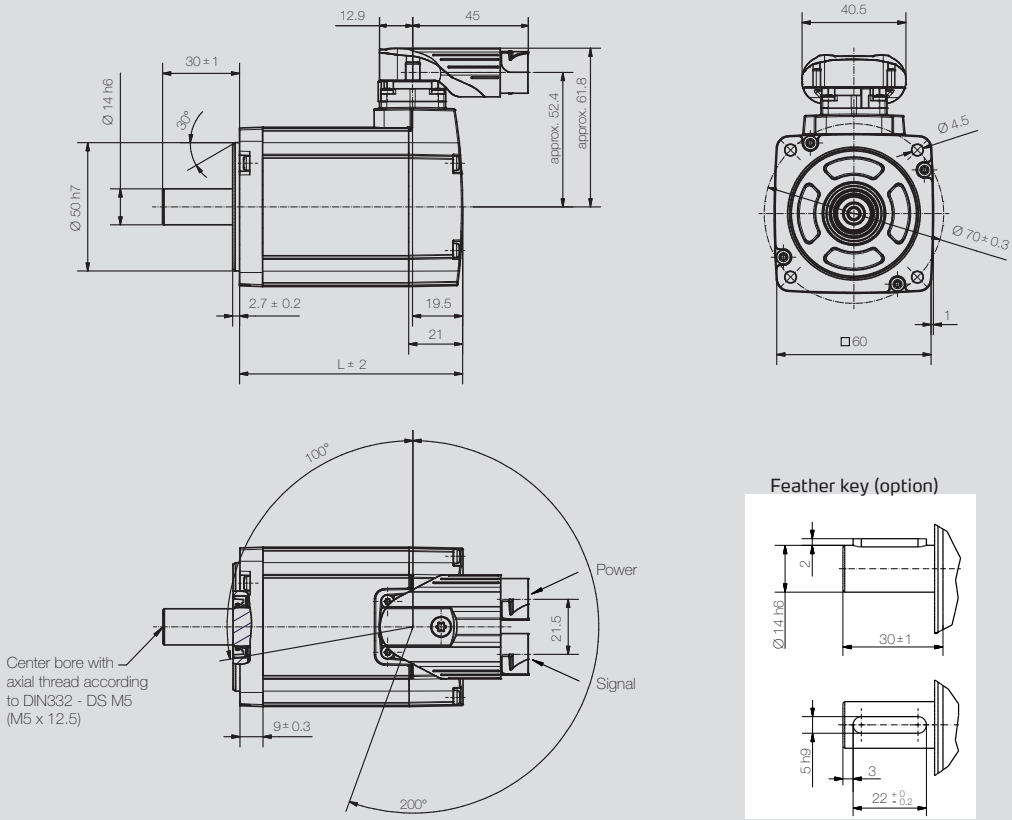
HMD06-019-320-30-*



HMD06-019-320-60-*



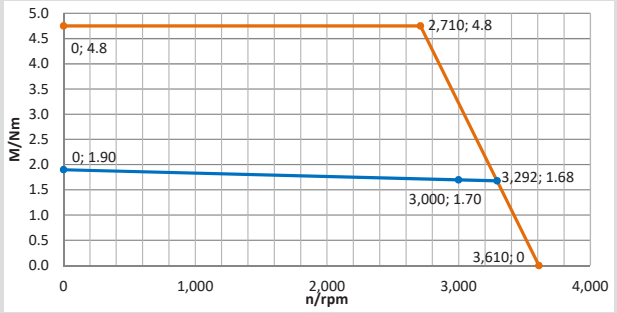
Dimensions



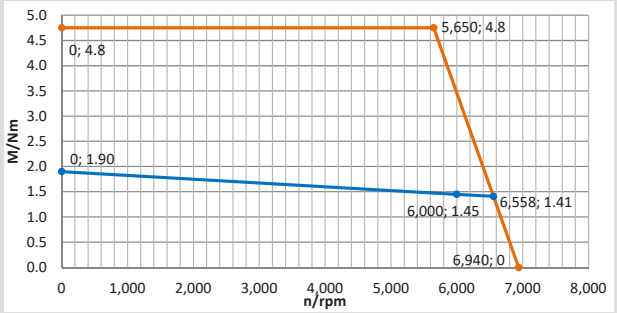
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD06-019	117 mm	156 mm	135 mm	174 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD06-019-560-30-*



HMD06-019-560-60-*



HMD06-026

48 V

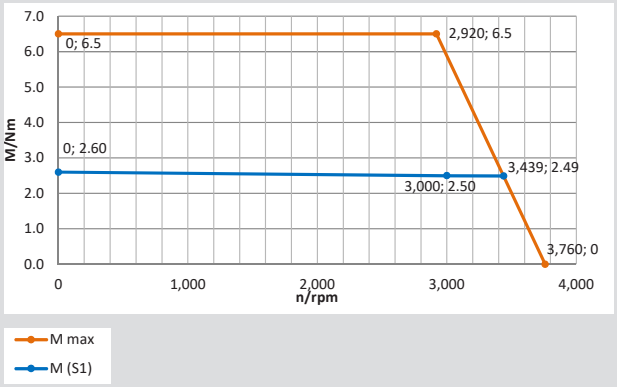
Specifications

		HMD06-026	
Rated speed [rpm]	n_n	3,000	6,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	48	48
Rated voltage motor [V_{rms}]	U_{mot}	26.7	27.4
Rated power [W] [1)]	P_n	785	1,250
Rated torque [Nm]	M_n	2.5	2.0
Rated current per phase [A_{rms}]	I_n	19.0	28.7
Stall torque [Nm]	**M_0**	**2.6**	**2.6**
Stall current per phase [A_{rms}]	I_0	19.5	36.4
Peak torque [Nm]	M_{max}	6.5	6.5
Peak current [A_{rms}]	I_{max}	48.8	91.0
Maximum speed [rpm]	n_{max}	3,760	6,990
Voltage constant at 1,000 rpm [V_{rms}]	k_e	8.3	4.5
Torque constant [Nm / A_{rms}]	k_t	0.13	0.07
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.120	0.033
Winding inductance (2 phases) [mH]	L_{p-p}	0.18	0.05
Electrical time constant [ms]	t_{el}	1.5	1.5
Thermal time constant [min]	t_{th}	25	25
Moment of inertia rotor [kg-cm²]	J	7.11E-01	7.11E-01
Weight of motor [kg]	m	2.0	2.0

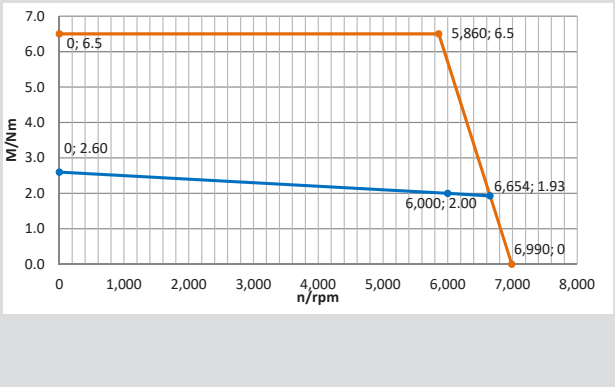
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

HMD06-026-048-30-*

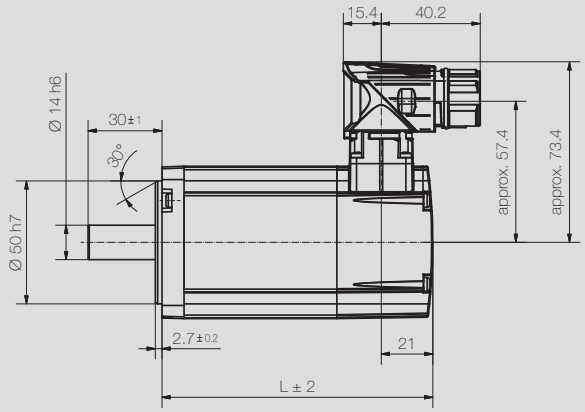


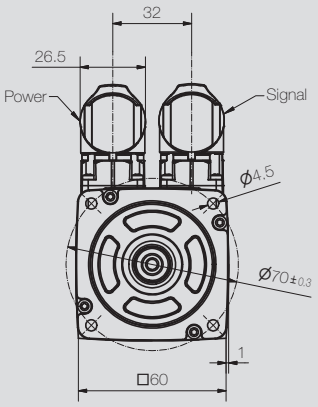
HMD06-026-048-60-*

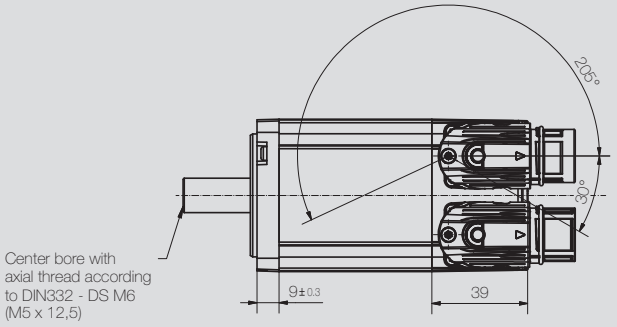


[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

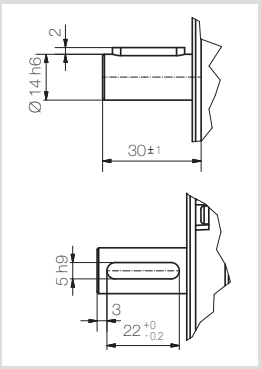
Dimensions







Feather key (option)



	L [mm]	
Motor	without Brake	with Brake
HMD06-026	165 mm	204 mm

HMD06-026

320 / 560 V

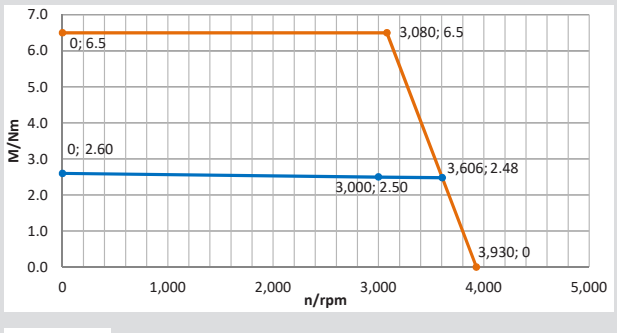
Specifications

		HMD06-026			
Rated speed [rpm]	n_n	3,000	6,000	3,000	6,000
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	173	181	333	330
Rated power [W]	P_n	785	1,250	785	1,250
Rated torque [Nm]	M_n	2.5	2.0	2.5	2.0
Rated current per phase [A_{rms}]	I_n	3.0	4.5	1.6	2.5
Stall torque [Nm]	**M_0**	**2.6**	**2.6**	**2.6**	**2.6**
Stall current per phase [A_{rms}]	I_0	3.0	5.5	1.6	3.0
Peak torque [Nm]	M_{max}	6.5	6.5	6.5	6.5
Peak current [A_{rms}]	I_{max}	7.5	13.8	4.0	7.5
Maximum speed [rpm]	n_{max}	3,930	7,210	3,570	6,880
Voltage constant at 1,000 rpm [V_{rms}]	k_e	53.6	29.2	103.3	53.6
Torque constant [Nm / A_{rms}]	k_t	0.83	0.44	1.61	0.80
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	4.8	1.45	18.0	4.8
Winding inductance (2 phases) [mH]	L_{p-p}	7.28	2.2	27.1	7.28
Electrical time constant [ms]	t_{el}	1.5	1.5	1.5	1.5
Thermal time constant [min]	t_{th}	25	25	25	25
Moment of inertia rotor [kg-cm²]	J	7.11E-01	7.11E-01	7.11E-01	7.11E-01
Weight of motor [kg]	m	2.0	2.0	2.0	2.0

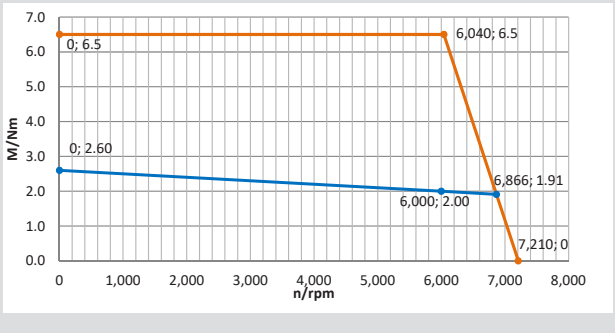
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

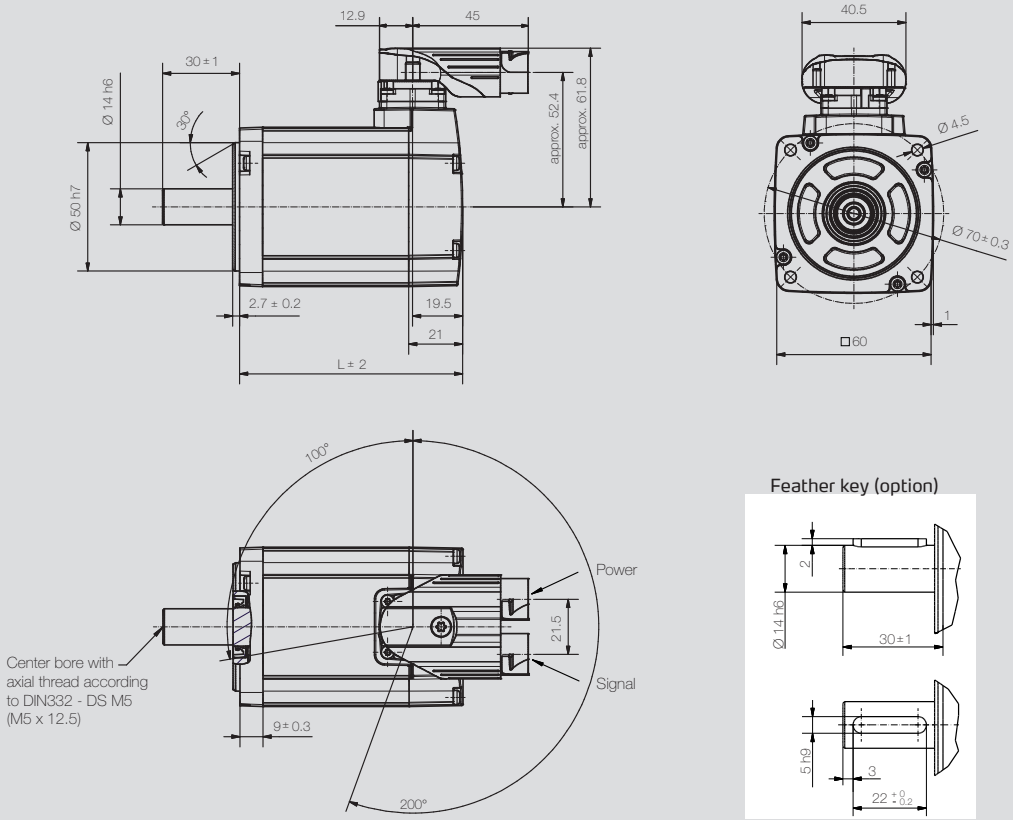
HMD06-026-320-30-*



HMD06-026-320-60-*



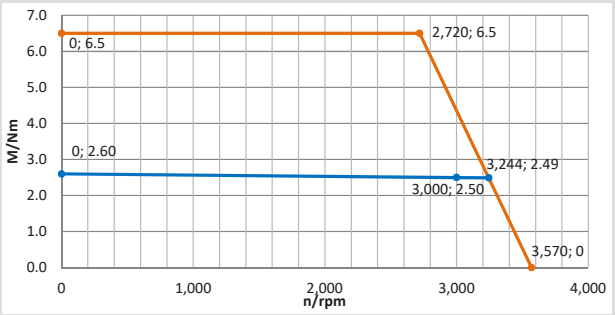
Dimensions



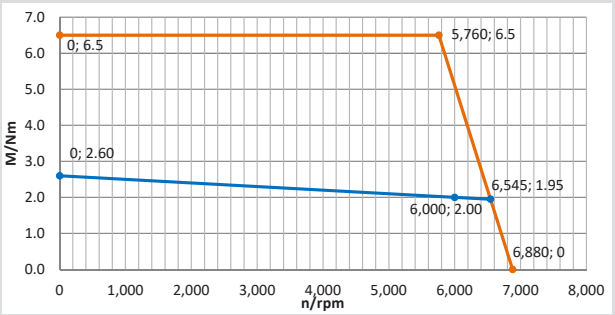
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD06-026	147 mm	186 mm	165 mm	204 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD06-026-560-30-*



HMD06-026-560-60-*



HMD08-024

24 / 48 V

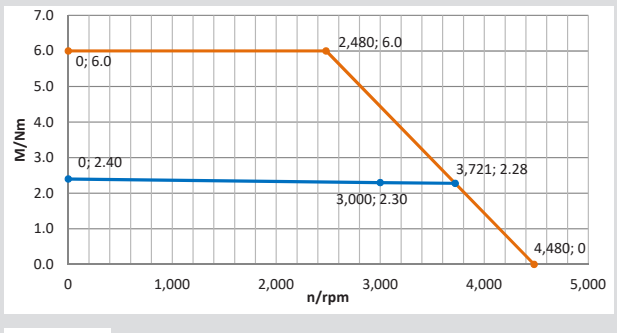
Specifications

		HMD08-024		
Rated speed [rpm]	n_n	3,000	3,000	5,500
Number of pole pairs		5	5	5
Wiring of the motor winding		Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	24	48	48
Rated voltage motor [V_{rms}]	U_{mot}	12.0	23.0	20.8
Rated power [W] [1)]	P_n	720	720	1,210
Rated torque [Nm]	M_n	2.3	2.3	2.1
Rated current per phase [A_{rms}]	I_n	44.9	23.3	42.0
Stall torque [Nm]	**M_0**	**2.4**	**2.4**	**2.4**
Stall current per phase [A_{rms}]	I_0	45.0	24.3	45.0
Peak torque [Nm]	M_{max}	6.0	6.0	6.0
Peak current [A_{rms}]	I_{max}	112.5	60.8	112.5
Maximum speed [rpm]	n_{max}	4,480	4,800	9,170
Voltage constant at 1,000 rpm [V_{rms}]	k_e	3.4	6.5	3.4
Torque constant [Nm / A_{rms}]	k_t	0.05	0.1	0.05
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.034	0.12	0.034
Winding inductance (2 phases) [mH]	L_{p-p}	0.077	0.284	0.077
Electrical time constant [ms]	t_{el}	2.3	2.4	2.4
Thermal time constant [min]	t_{th}	30	30	30
Moment of inertia rotor [kg-cm²]	J	8.00E-01	8.00E-01	8.00E-01
Weight of motor [kg]	m	2.5	2.5	2.5

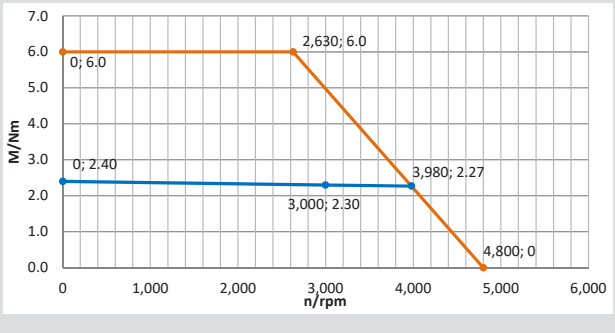
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

HMD08-024-024-30-*

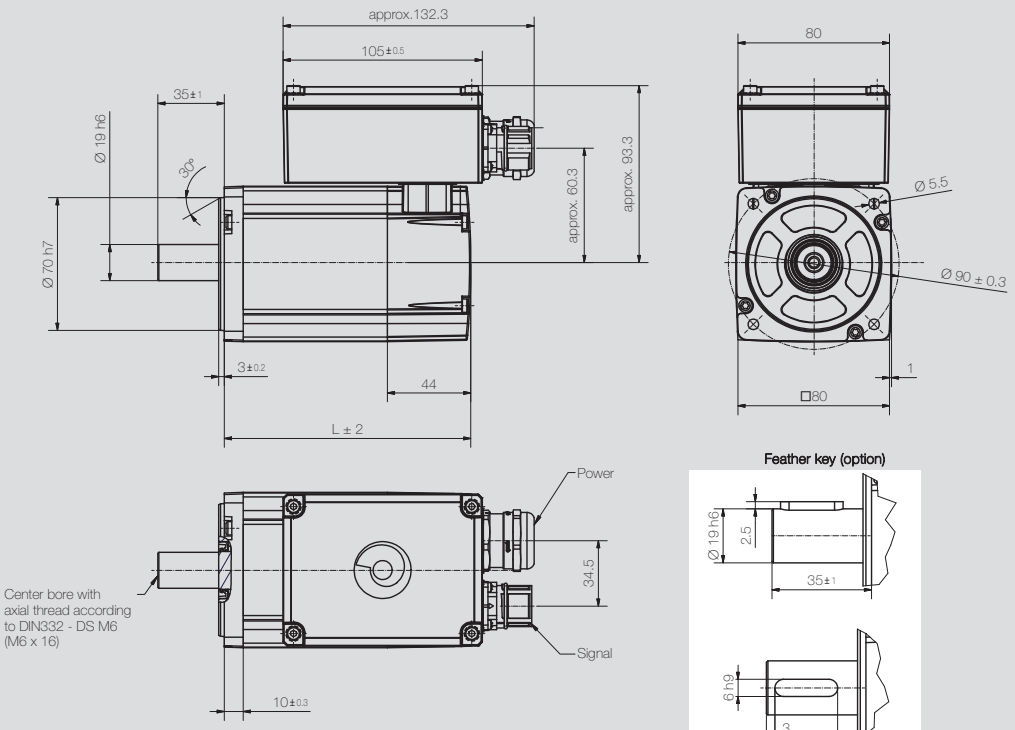


HMD08-024-048-30-*



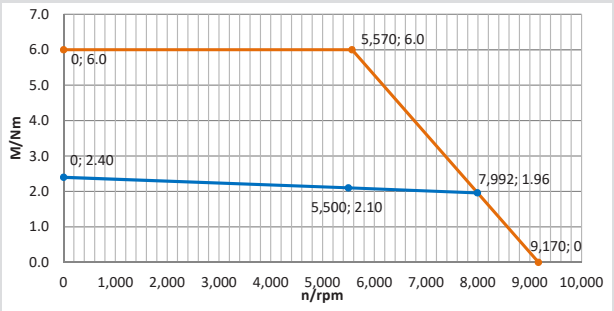
[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions



Motor	L [mm] without Brake	with Brake
HMD08-024	130 mm	178.5 mm

HMD08-024-048-55-*



HMD08-024

320 / 560 V

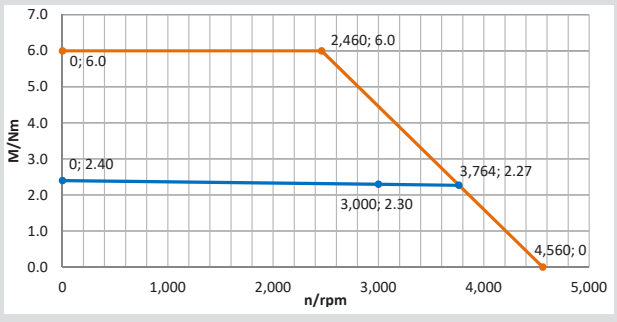
Specifications

		HMD08-024			
Rated speed [rpm]	n_n	3,000	5,500	3,000	5,500
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	165	167	291	285
Rated power [W]	P_n	720	1,210	720	1,210
Rated torque [Nm]	M_n	2.3	2.1	2.3	2.1
Rated current per phase [A_{rms}]	I_n	3.3	5.4	1.9	3.1
Stall torque [Nm]	**M_0**	**2.4**	**2.4**	**2.4**	**2.4**
Stall current per phase [A_{rms}]	I_0	3.4	5.6	2.0	3.4
Peak torque [Nm]	M_{max}	6.0	6.0	6.0	6.0
Peak current [A_{rms}]	I_{max}	8.5	14.0	4.9	8.5
Maximum speed [rpm]	n_{max}	4,560	7,800	4,500	7,980
Voltage constant at 1,000 rpm [V_{rms}]	k_e	46.2	27.0	82.0	46.2
Torque constant [Nm / A_{rms}]	k_t	0.7	0.39	1.24	0.68
Winding resistance (2 phases) at 20 °C [Ω]	R_{pp}	6.3	2.2	19.8	6.3
Winding inductance (2 phases) [mH]	L_{pp}	14.4	5.0	45.7	14.4
Electrical time constant [ms]	T_{el}	2.3	2.3	2.3	2.3
Thermal time constant [min]	T_{th}	30	30	30	30
Moment of inertia rotor [kg-cm²]	J	8.00E-01	8.00E-01	8.00E-01	8.00E-01
Weight of motor [kg]	m	2.5	2.5	2.5	2.5

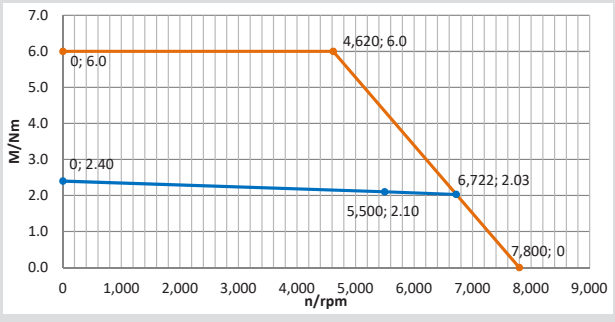
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

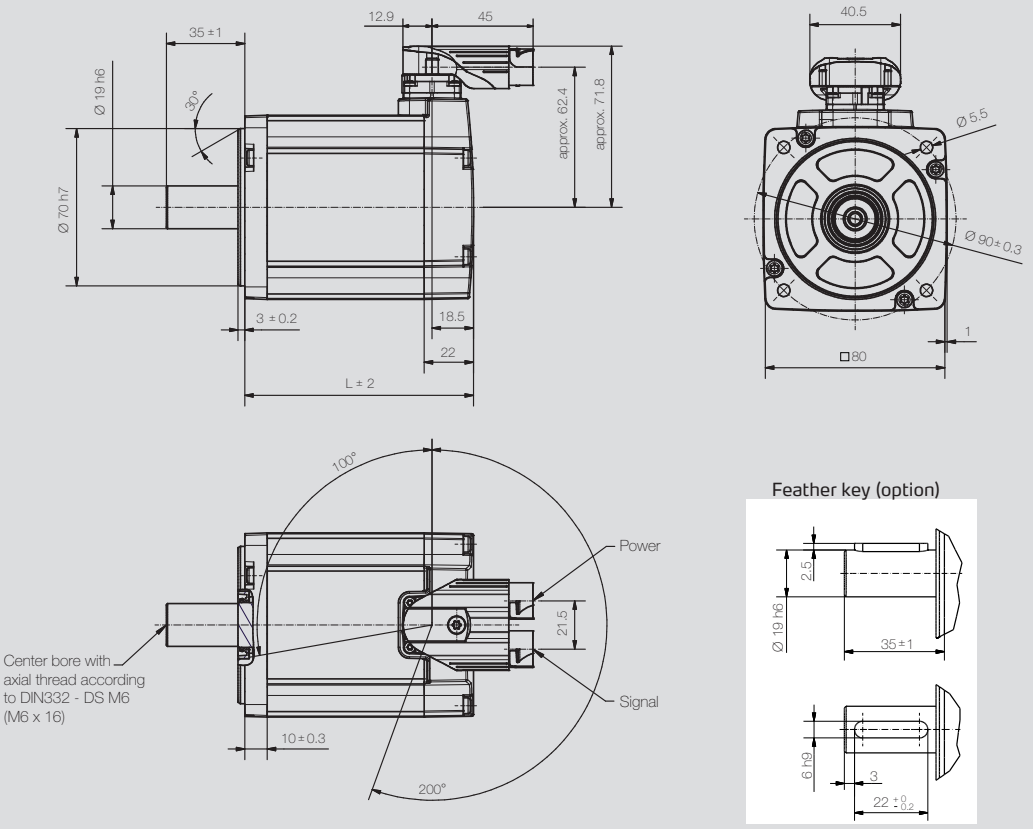
HMD08-024-320-30-*



HMD08-024-320-55-*



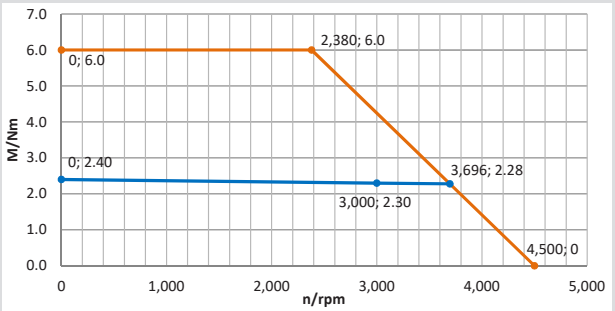
Dimensions



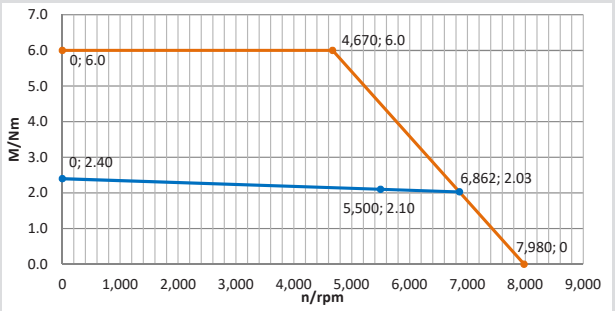
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD08-024	108 mm	156.5 mm	130 mm	178.5 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD08-024-560-30-*



HMD08-024-560-55-*



HMD08-032

24 / 48 V

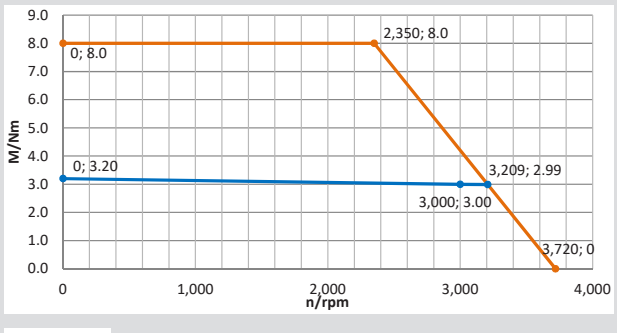
Specifications

		HMD08-032		
Rated speed [rpm]	n_n	3,000	3,000	5,500
Number of pole pairs		5	5	5
Wiring of the motor winding		Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	24	48	48
Rated voltage motor [V_{rms}]	U_{mot}	13.8	26.0	24.2
Rated power [W] [1)]	P_n	940	940	1,500
Rated torque [Nm]	M_n	3.0	3.0	2.6
Rated current per phase [A_{rms}]	I_n	48.7	25.9	44.0
Stall torque [Nm]	**M_0**	**3.2**	**3.2**	**3.2**
Stall current per phase [A_{rms}]	I_0	50.0	26.2	50.0
Peak torque [Nm]	M_{max}	8.0	8.0	8.0
Peak current [A_{rms}]	I_{max}	125.0	65.5	125.0
Maximum speed [rpm]	n_{max}	3,720	4,000	7,610
Voltage constant at 1,000 rpm [V_{rms}]	k_e	4.1	7.8	4.1
Torque constant [Nm / A_{rms}]	k_t	0.06	0.12	0.06
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.024	0.087	0.024
Winding inductance (2 phases) [mH]	L_{p-p}	0.068	0.245	0.068
Electrical time constant [ms]	t_{el}	2.8	2.8	2.8
Thermal time constant [min]	t_{th}	30	30	30
Moment of inertia rotor [kg-cm²]	J	1.13E+00	1.13E+00	1.13E+00
Weight of motor [kg]	m	2.9	2.9	2.9

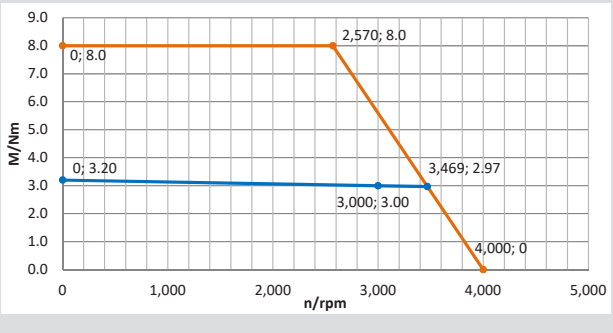
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

HMD08-032-024-30-*

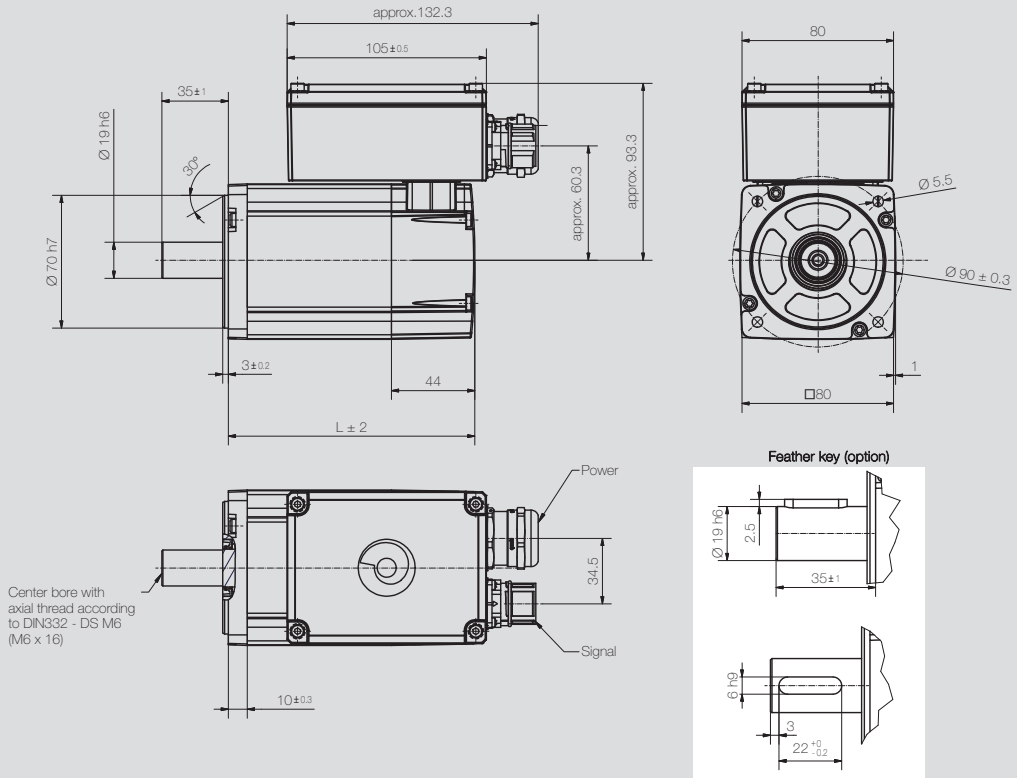


HMD08-032-048-30-*



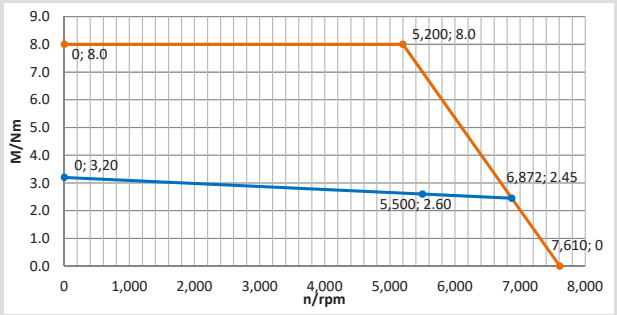
[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions



	L [mm]	
Motor	without Brake	with Brake
HMD08-032	145 mm	193.5 mm

HMD08-032-048-55-*



HMD08-032

320 / 560 V

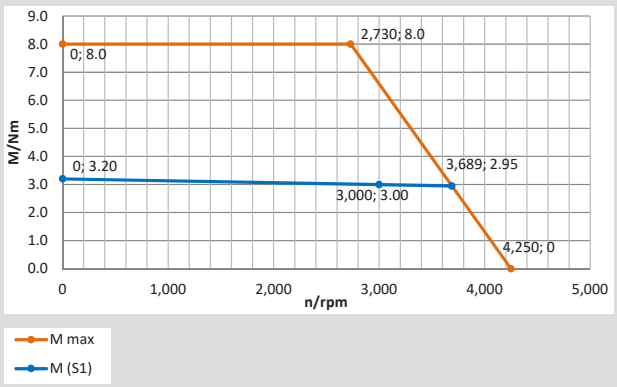
Specifications

		HMD08-032			
Rated speed [rpm]	n_n	3,000	5,500	3,000	5,500
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	166	167	305	294
Rated power [W]	P_n	940	1,500	940	1,500
Rated torque [Nm]	M_n	3.0	2.6	3.0	2.6
Rated current per phase [A_{rms}]	I_n	4.1	6.4	2.1	3.6
Stall torque [Nm]	**M_0**	**3.2**	**3.2**	**3.2**	**3.2**
Stall current per phase [A_{rms}]	I_0	4.2	7.1	2.2	4.2
Peak torque [Nm]	M_{max}	8.0	8.0	8.0	8.0
Peak current [A_{rms}]	I_{max}	10.4	17.8	5.5	9.5
Maximum speed [rpm]	n_{max}	4,250	7,440	4,010	7,430
Voltage constant at 1,000 rpm [V_{rms}]	k_e	49.6	28.3	91.9	49.6
Torque constant [Nm / A_{rms}]	k_t	0.73	0.41	1.43	0.73
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	3.50	1.15	12.0	3.5
Winding inductance (2 phases) [mH]	L_{p-p}	10.0	3.3	34.4	10.0
Electrical time constant [ms]	t_{el}	2.9	2.9	2.8	2.9
Thermal time constant [min]	t_{th}	30	30	30	30
Moment of inertia rotor [kg-cm²]	J	1.13E+00	1.13E+00	1.13E+00	1.13E+00
Weight of motor [kg]	m	2.9	2.9	2.9	2.9

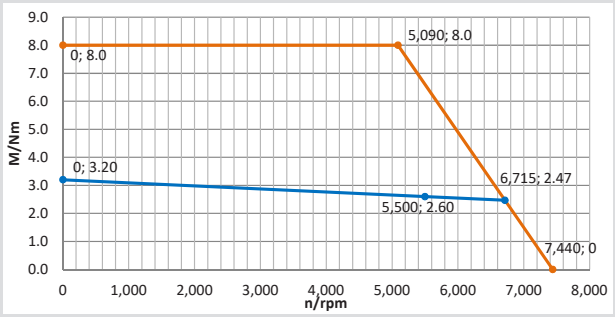
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

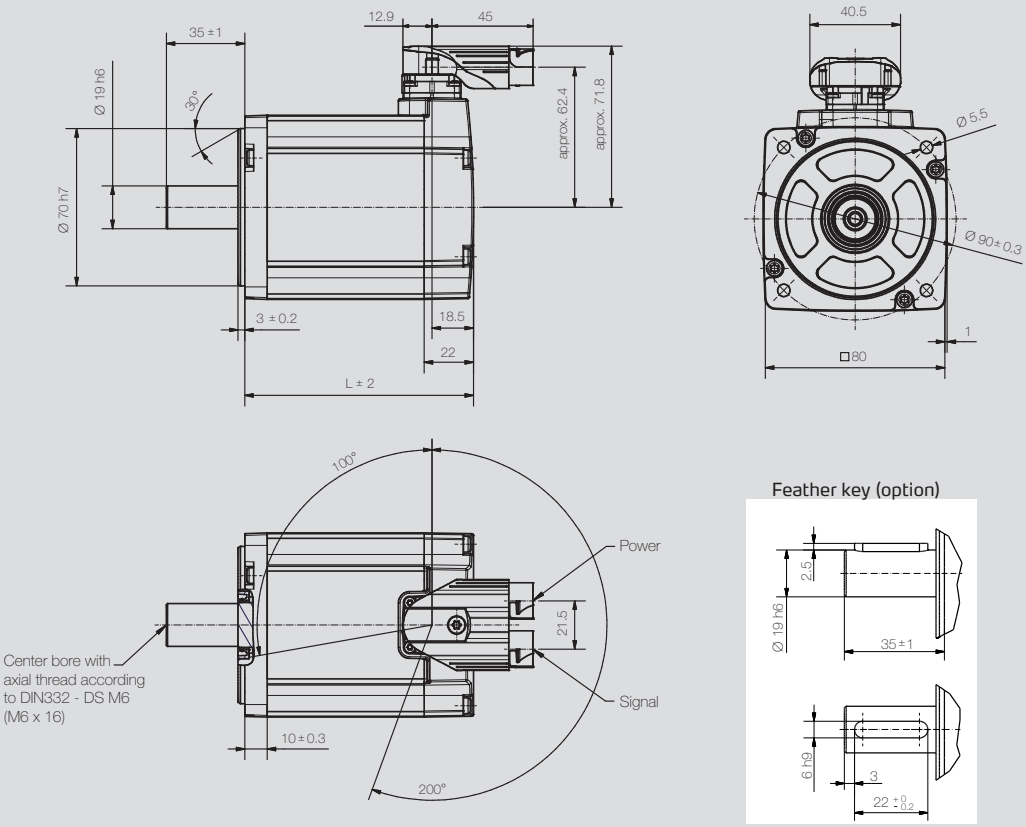
HMD08-032-320-30-*



HMD08-032-320-55-*



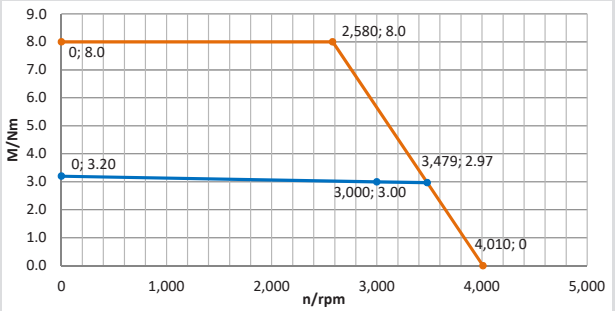
Dimensions



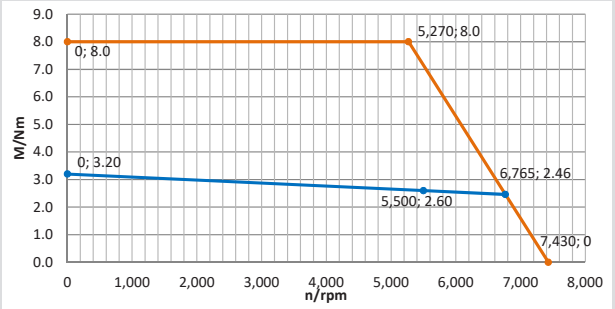
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD08-032	123 mm	171.5 mm	145 mm	193.5 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx,HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD08-032-560-30-*



HMD08-032-560-55-*



HMD08-042

24 / 48 V

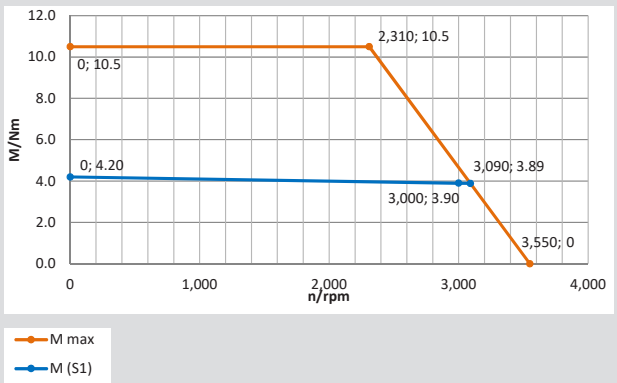
Specifications

		HMD08-042		
Rated speed [rpm]	n_n	3,000	3,000	5,500
Number of pole pairs		5	5	5
Wiring of the motor winding		Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	24	48	48
Rated voltage motor [V_{rms}]	U_{mot}	14.6	27.1	25.8
Rated power [W] [1]	P_n	1,225	1,225	1,950
Rated torque [Nm]	M_n	3.9	3.9	3.4
Rated current per phase [A_{rms}]	I_n	57.6	30.8	52.3
Stall torque [Nm]	**M_0**	**4.2**	**4.2**	**4.2**
Stall current per phase [A_{rms}]	I_0	60.8	33.0	60.8
Peak torque [Nm]	M_{max}	10.5	10.5	10.5
Peak current [A_{rms}]	I_{max}	146.0	82.5	152.0
Maximum speed [rpm]	n_{max}	3,550	3,850	7,250
Voltage constant at 1,000 rpm [V_{rms}]	k_e	4.3	8.1	4.3
Torque constant [Nm / A_{rms}]	k_t	0.07	0.13	0.07
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.018	0.064	0.018
Winding inductance (2 phases) [mH]	L_{p-p}	0.06	0.204	0.06
Electrical time constant [ms]	t_{el}	3.3	3.2	3.3
Thermal time constant [min]	t_{th}	30	30	30
Moment of inertia rotor [kg-cm²]	J	1.46E+00	1.46E+00	1.46E+00
Weight of motor [kg]	m	3.3	3.3	3.3

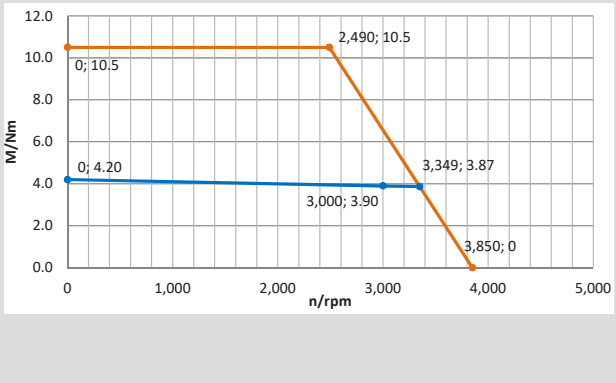
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

HMD08-042-024-30-*

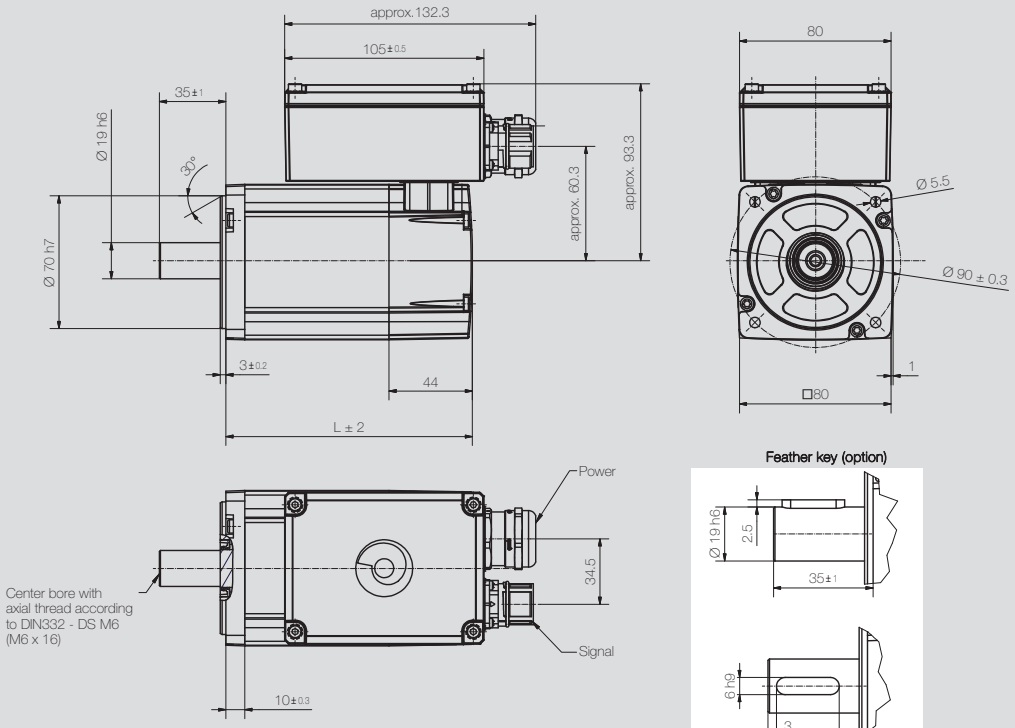


HMD08-042-048-30-*



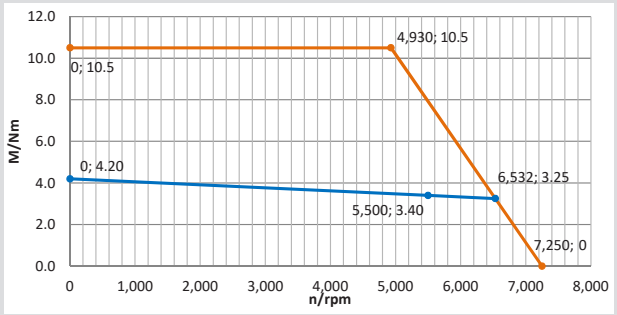
[1] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values

Dimensions



	L [mm]	
Motor	without Brake	with Brake
HMD08-042	160 mm	208.5 mm

HMD08-042-048-55-*



HMD08-042

320 / 560 V

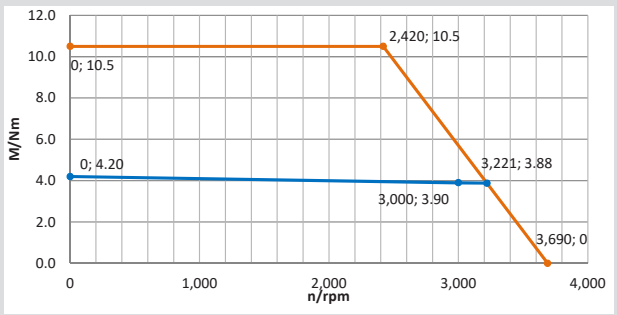
Specifications

		HMD08-042			
Rated speed [rpm]	n_n	3,000	5,500	3,000	5,500
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	181	181	330	320
Rated power [W]	P_n	1,225	1,950	1,225	1,950
Rated torque [Nm]	M_n	3.9	3.4	3.9	3.4
Rated current per phase [A_{rms}]	I_n	4.6	7.4	2.6	4.1
Stall torque [Nm]	**M_0**	**4.2**	**4.2**	**4.2**	**4.2**
Stall current per phase [A_{rms}]	I_0	5.0	8.5	2.7	4.5
Peak torque [Nm]	M_{max}	10.5	10.5	10.5	10.5
Peak current [A_{rms}]	I_{max}	12.5	21.3	6.8	11.3
Maximum speed [rpm]	n_{max}	3,690	6,770	3,660	6,460
Voltage constant at 1,000 rpm [V_{rms}]	k_e	57.1	31.1	100.8	57.1
Torque constant [Nm / A_{rms}]	k_t	0.85	0.46	1.5	0.83
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	3.0	0.94	9.6	3.0
Winding inductance (2 phases) [mH]	L_{p-p}	9.0	2.8	29.2	9.0
Electrical time constant [ms]	t_{el}	3.0	3.0	3.0	3.0
Thermal time constant [min]	t_{th}	30	30	30	30
Moment of inertia rotor [kg-cm²]	J	1.46E+00	1.46E+00	1.46E+00	1.46E+00
Weight of motor [kg]	m	3.3	3.3	3.3	3.3

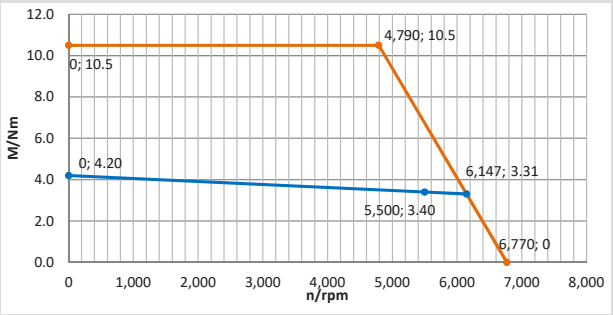
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

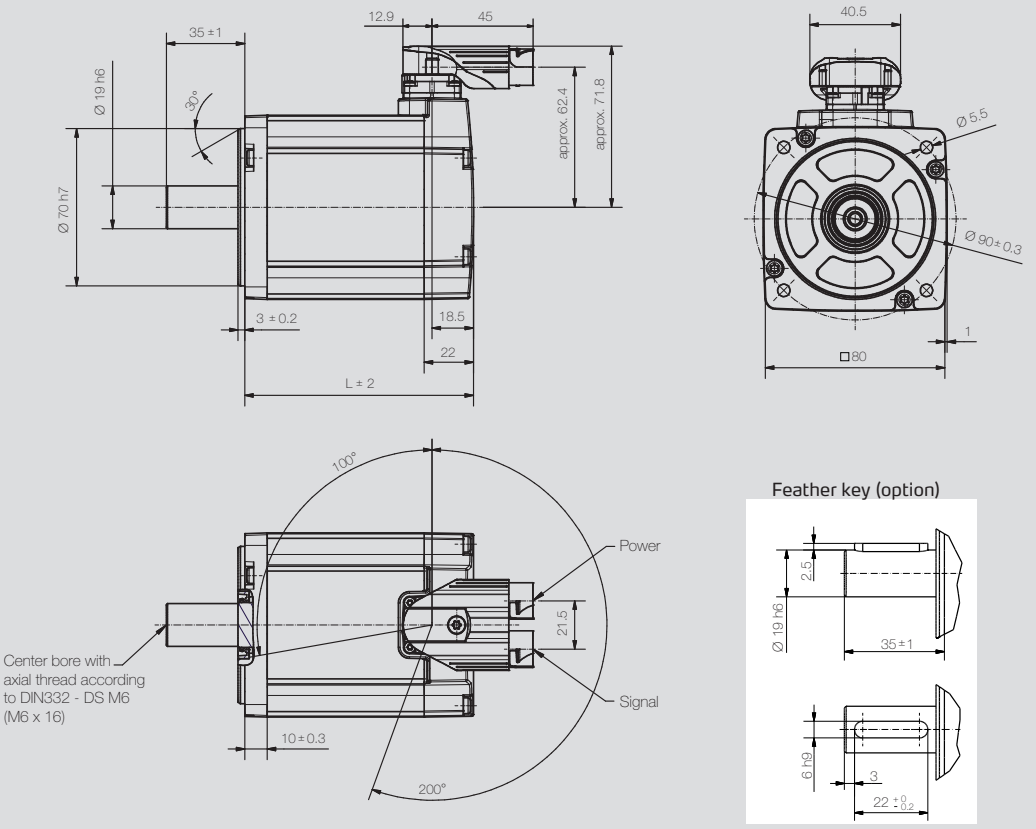
HMD08-042-320-30-*



HMD08-042-320-55-*



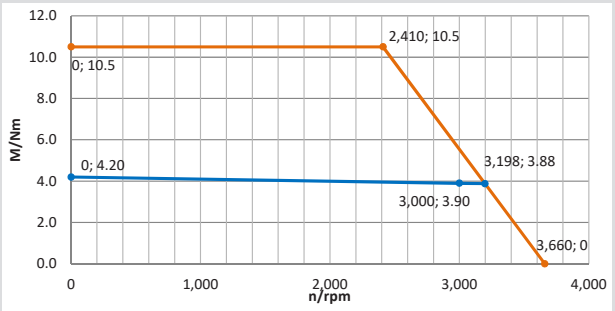
Dimensions



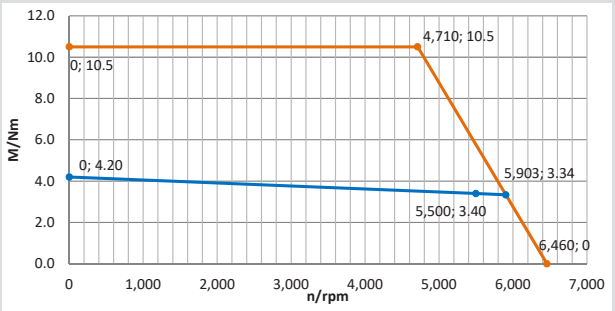
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD08-042	138 mm	186.5 mm	160 mm	208.5 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD08-042-560-30-*



HMD08-042-560-55-*



HMD08-057

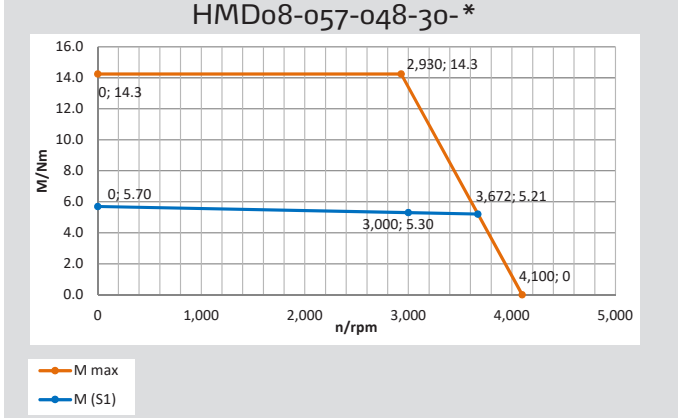
24 / 48 V

Specifications

		HMD08-057
Rated speed [rpm]	n_n	3,000
Number of pole pairs		5
Wiring of the motor winding		Y
DC bus voltage [V_{DC}]	U_{bus}	48
Rated voltage motor [V_{rms}]	U_{mot}	24.7
Rated power [W] [1)]	P_n	1,665
Rated torque [Nm]	M_n	5.3
Rated current per phase [A_{rms}]	I_n	45.8
Stall torque [Nm]	**M_0**	**5.7**
Stall current per phase [A_{rms}]	I_0	48.0
Peak torque [Nm]	M_{max}	14.3
Peak current [A_{rms}]	I_{max}	120.0
Maximum speed [rpm]	n_{max}	4,100
Voltage constant at 1,000 rpm [V_{rms}]	k_e	7.6
Torque constant [Nm / A_{rms}]	k_t	0.12
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.034
Winding inductance (2 phases) [mH]	L_{p-p}	0.11
Electrical time constant [ms]	t_{el}	3.2
Thermal time constant [min]	t_{th}	30
Moment of inertia rotor [kg-cm²]	J	2.12E+00
Weight of motor [kg]	m	4.4

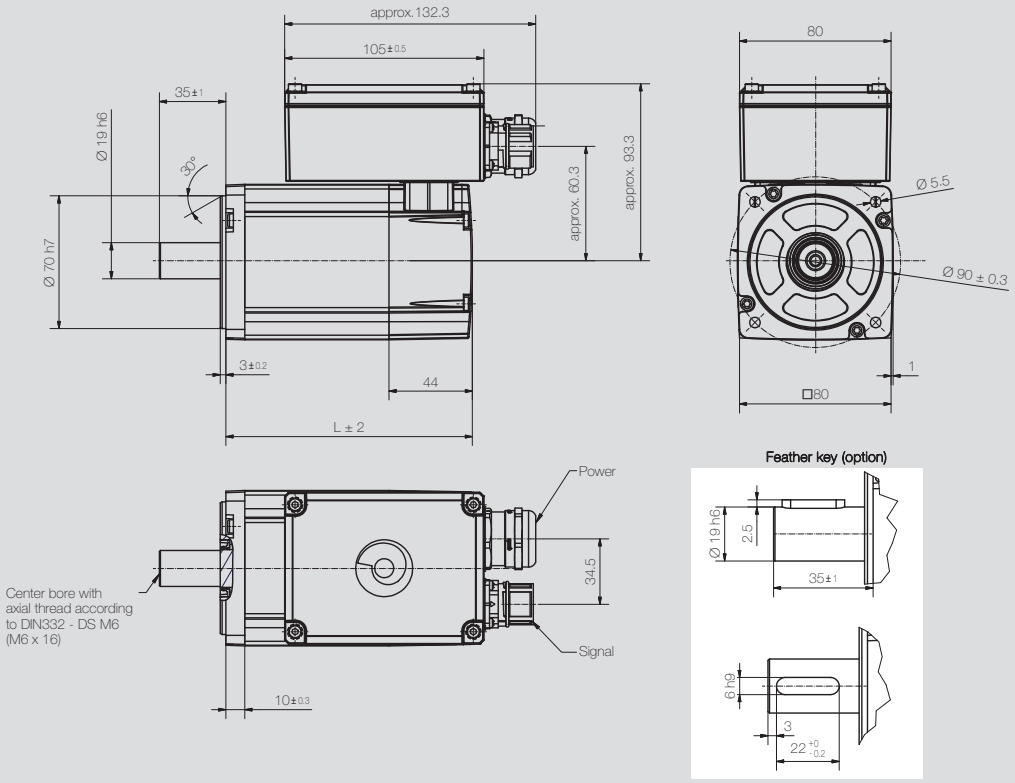
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance



[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions



Motor	L [mm] *with encoder categorie 2** without Brake	with Brake
HMD08-057	190 mm	238.5 mm

HMD08-057

320 / 560 V

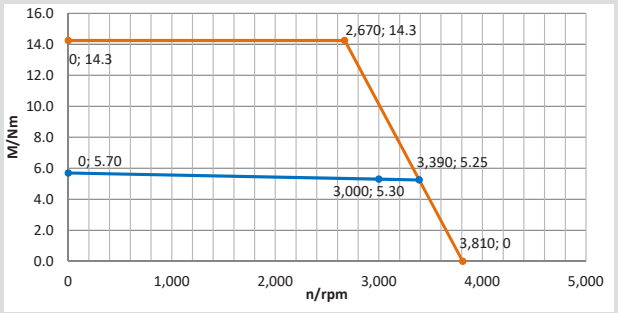
Specifications

		HMD08-057			
Rated speed [rpm]	n_n	3,000	5,500	3,000	5,500
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	179	185	334	317
Rated power [W]	P_n	1,665	2,480	1,665	2,480
Rated torque [Nm]	M_n	5.3	4.3	5.3	4.3
Rated current per phase [A_{rms}]	I_n	6.3	8.9	3.4	5.3
Stall torque [Nm]	**M_0**	**5.7**	**5.7**	**5.7**	**5.7**
Stall current per phase [A_{rms}]	I_0	6.6	11.4	3.6	6.6
Peak torque [Nm]	M_{max}	14.3	14.3	14.3	14.3
Peak current [A_{rms}]	I_{max}	16.5	28.5	9.0	16.5
Maximum speed [rpm]	n_{max}	3,810	6,360	3,580	6,670
Voltage constant at 1,000 rpm [V_{rms}]	k_e	55.3	33.1	103.0	55.3
Torque constant [Nm / A_{rms}]	k_t	0.84	0.48	1.56	0.81
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	1.80	0.6	6.2	1.8
Winding inductance (2 phases) [mH]	L_{p-p}	6.0	2.0	20.7	6.0
Electrical time constant [ms]	t_{el}	3.3	3.3	3.2	3.3
Thermal time constant [min]	t_{th}	30	30	30	30
Moment of inertia rotor [kg-cm²]	J	2.12E+00	2.12E+00	2.12E+00	2.12E+00
Weight of motor [kg]	m	4.4	4.4	4.4	4.4

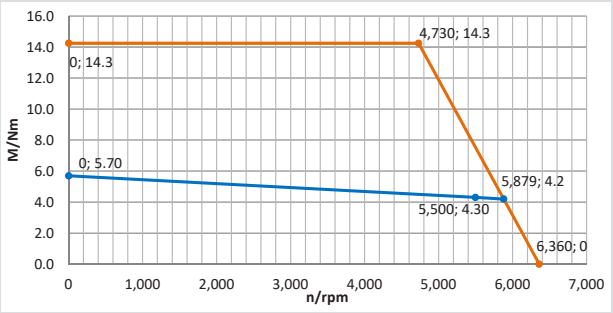
For standstill / rated current greater than 30 A, observe connection technology (Page 76) and encoder selection (Page 74)!
Other voltage variants available on request.

Performance

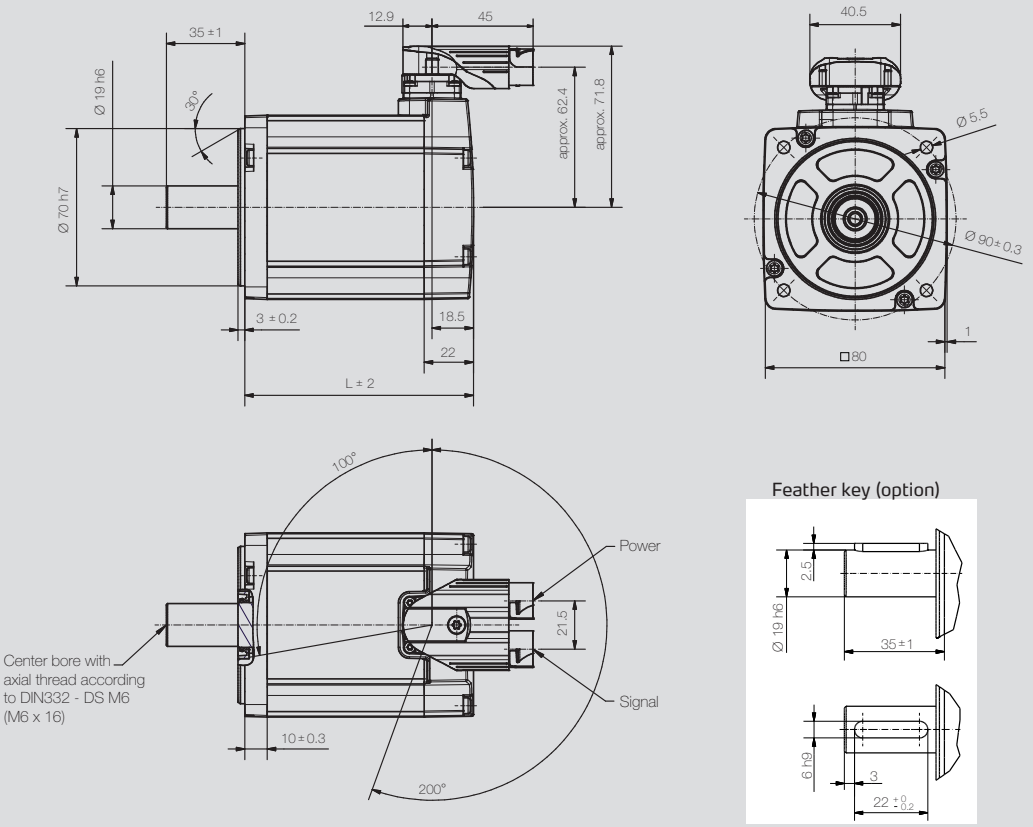
HMD08-057-320-30-*



HMD08-057-320-55-*



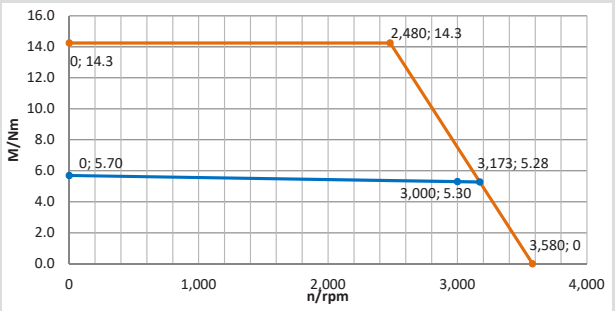
Dimensions



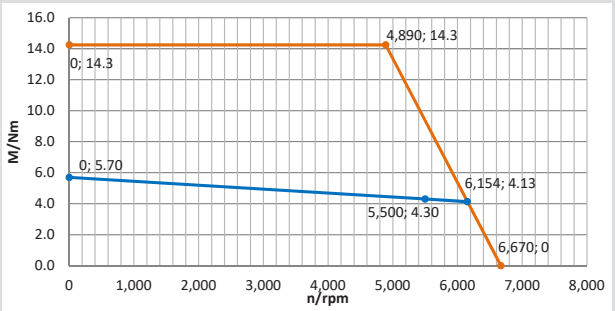
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD08-057	168 mm	216.5 mm	190 mm	238.5 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD08-057-560-30-*



HMD08-057-560-55-*



HMD10-039

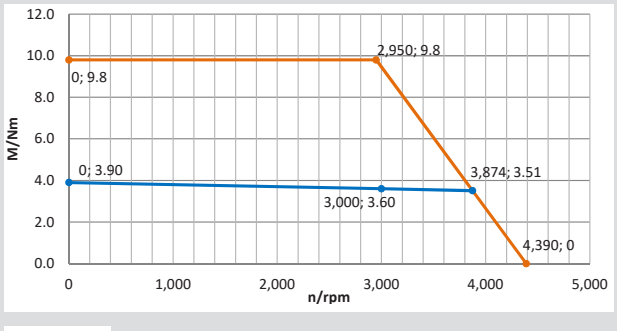
48 V

Specifications

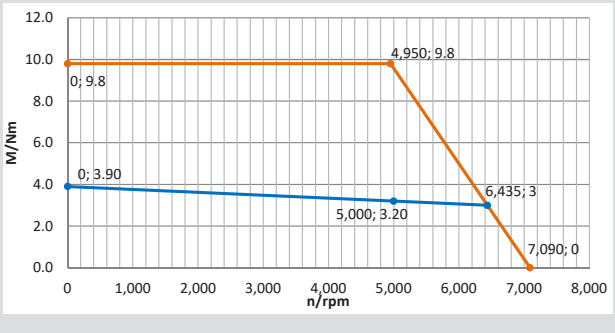
		HMD10-039	
Rated speed [rpm]	n_n	3,000	5,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	48	48
Rated voltage motor [V_{rms}]	U_{mot}	23.5	23.4
Rated power [W] [1]	P_n	1,130	1,675
Rated torque [Nm]	M_n	3.6	3.2
Rated current per phase [A_{rms}]	I_n	32.9	48.5
Stall torque [Nm]	**M_0**	**3.9**	**3.9**
Stall current per phase [A_{rms}]	I_0	34.6	56.0
Peak torque [Nm]	M_{max}	9.8	9.8
Peak current [A_{rms}]	I_{max}	86.5	140.0
Maximum speed [rpm]	n_{max}	4,390	7,090
Voltage constant at 1,000 rpm [V_{rms}]	k_e	7.1	4.4
Torque constant [Nm / A_{rms}]	k_t	0.11	0.07
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.056	0.021
Winding inductance (2 phases) [mH]	L_{p-p}	0.16	0.062
Electrical time constant [ms]	t_{el}	2.9	3.0
Thermal time constant [min]	t_{th}	30	30
Moment of inertia rotor [kg-cm²]	J	1.94E+00	1.94E+00
Weight of motor [kg]	m	4.5	4.5

Performance

HMD10-039-048-30-*

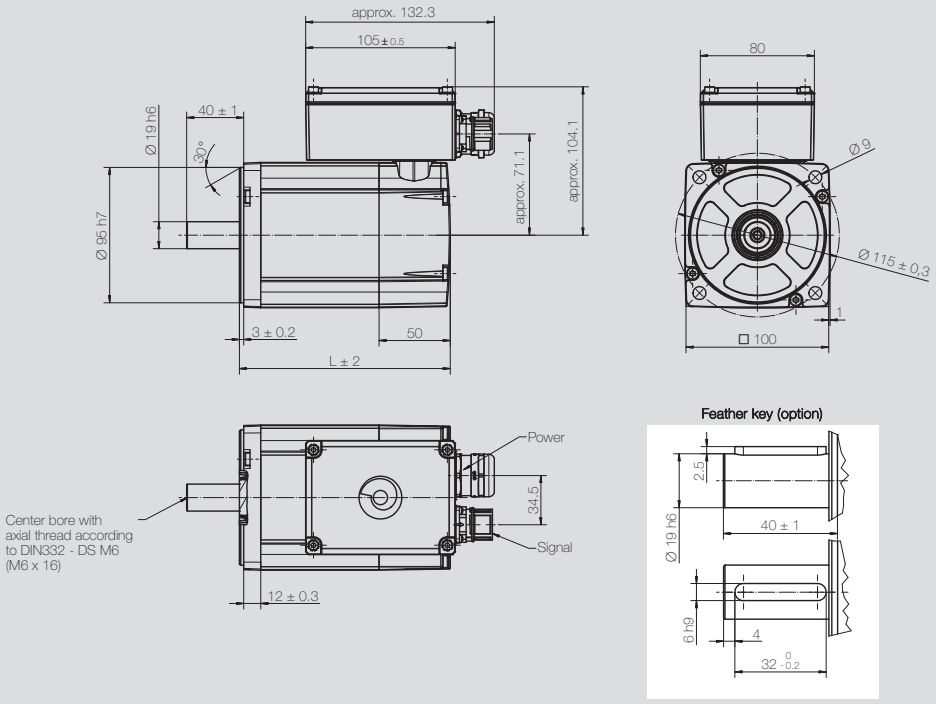


HMD10-039-048-50-*



[1] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions



	L [mm]	
Motor	without Brake	with Brake
HMD10-039	145 mm	192 mm

HMD10-039

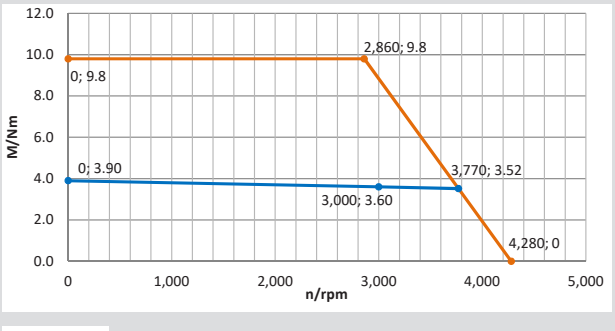
320 / 560 V

Specifications

		HMD10-039			
Rated speed [rpm]	n_n	3,000	5,000	3,000	5,000
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	163	162	289	263
Rated power [W]	P_n	1,130	1,675	1,130	1,675
Rated torque [Nm]	M_n	3.6	3.2	3.6	3.2
Rated current per phase [A_{rms}]	I_n	4.7	7.0	2.7	4.3
Stall torque [Nm]	**M_0**	**3.9**	**3.9**	**3.9**	**3.9**
Stall current per phase [A_{rms}]	I_0	5.0	8.2	2.8	5.0
Peak torque [Nm]	M_{max}	9.8	9.8	9.8	9.8
Peak current [A_{rms}]	I_{max}	12.5	20.5	7.0	12.5
Maximum speed [rpm]	n_{max}	4,280	6,860	4,190	7,490
Voltage constant at 1,000 rpm [V_{rms}]	k_e	49.2	30.7	88.0	49.2
Torque constant [Nm / A_{rms}]	k_t	0.77	0.46	1.33	0.74
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	2.6	1.02	8.4	2.6
Winding inductance (2 phases) [mH]	L_{p-p}	7.8	2.9	24.4	7.8
Electrical time constant [ms]	t_{el}	3.0	2.9	2.9	3.0
Thermal time constant [min]	t_{th}	30	30	30	30
Moment of inertia rotor [kg-cm²]	J	1.94E+00	1.94E+00	1.94E+00	1.94E+00
Weight of motor [kg]	m	4.5	4.5	4.5	4.5

Performance

HMD10-039-320-30-*



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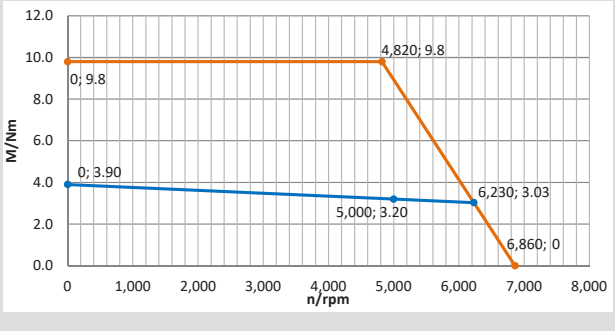
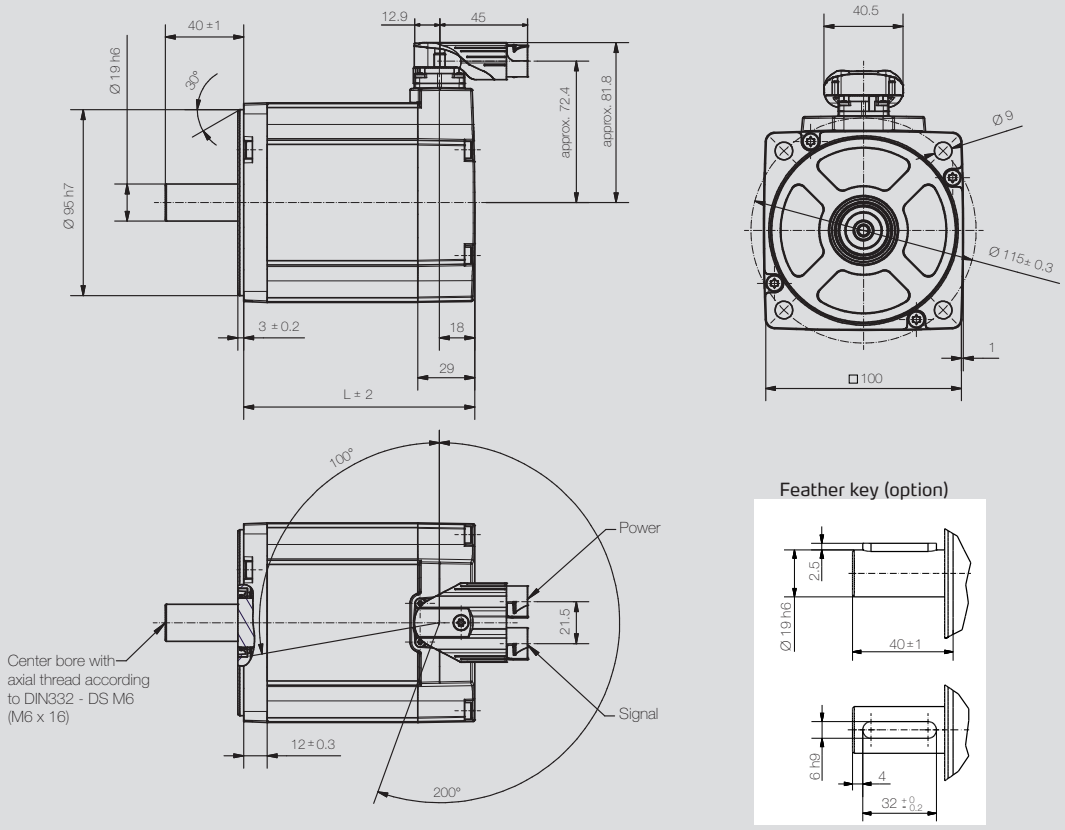


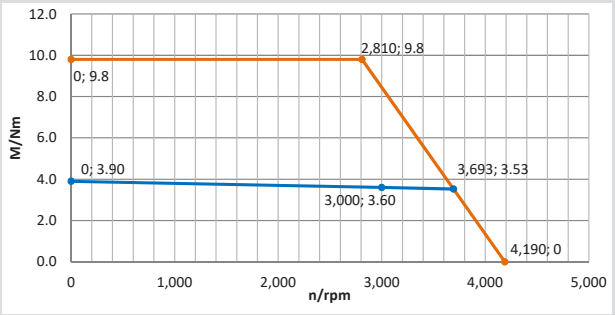
Dimensions



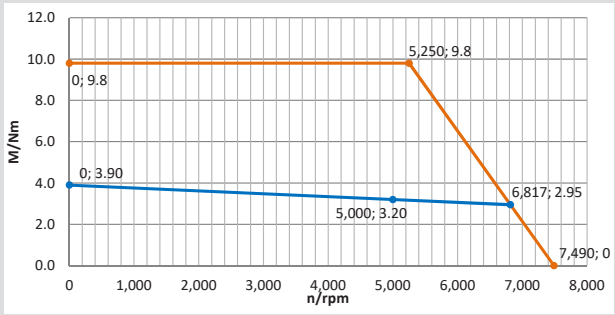
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD10-039	124 mm	171 mm	145 mm	192 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD10-039-560-30-*



HMD10-039-560-50-*



HMD10-057

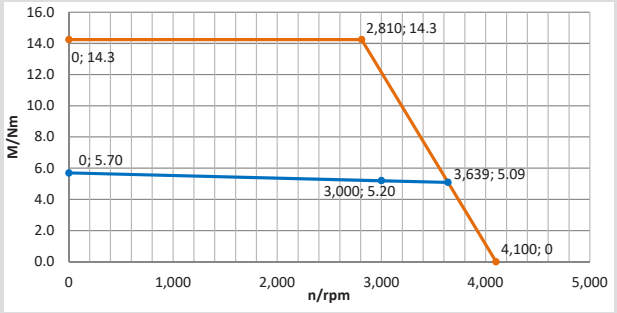
48 V

Specifications

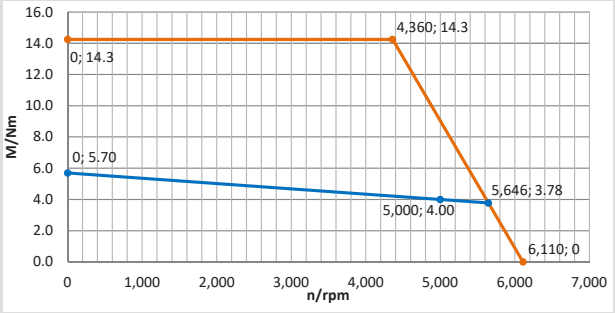
		HMD10-057	
Rated speed [rpm]	n_n	3,000	5,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	48	48
Rated voltage motor [V_{rms}]	U_{mot}	24.9	26.5
Rated power [W] [1]	P_n	1,635	2,095
Rated torque [Nm]	M_n	5.2	4.0
Rated current per phase [A_{rms}]	I_n	44.4	53.3
Stall torque [Nm]	**M_0**	**5.7**	**5.7**
Stall current per phase [A_{rms}]	I_0	47.1	70.6
Peak torque [Nm]	M_{max}	14.3	14.3
Peak current [A_{rms}]	I_{max}	117.8	176.5
Maximum speed [rpm]	n_{max}	4,100	6,110
Voltage constant at 1,000 rpm [V_{rms}]	k_e	7.6	5.1
Torque constant [Nm / A_{rms}]	k_t	0.12	0.08
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.04	0.017
Winding inductance (2 phases) [mH]	L_{p-p}	0.12	0.054
Electrical time constant [ms]	t_{el}	3.0	3.2
Thermal time constant [min]	t_{th}	30	30
Moment of inertia rotor [kg-cm²]	J	2.75E+00	2.75E+00
Weight of motor [kg]	m	5.0	5.0

Performance

HMD10-057-048-30-*

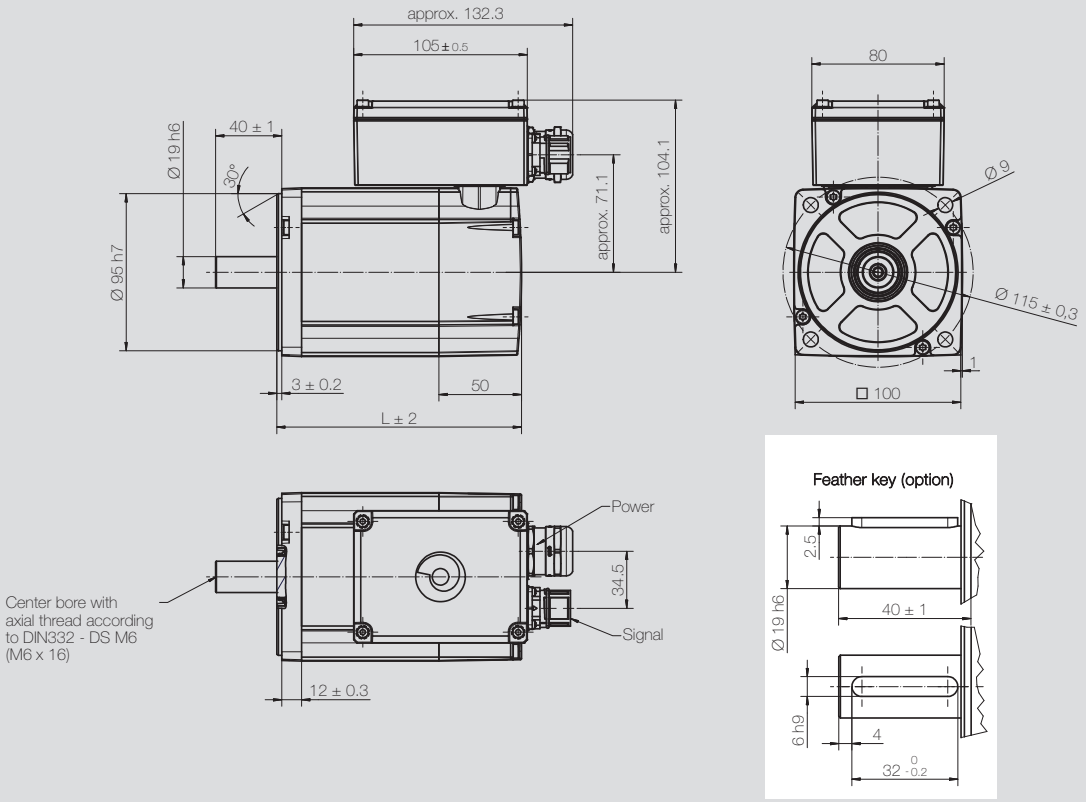


HMD10-057-048-50-*



[1] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions



Motor	L [mm] without Brake	L [mm] with Brake
HMD10-057	160 mm	207 mm

HMD10-057

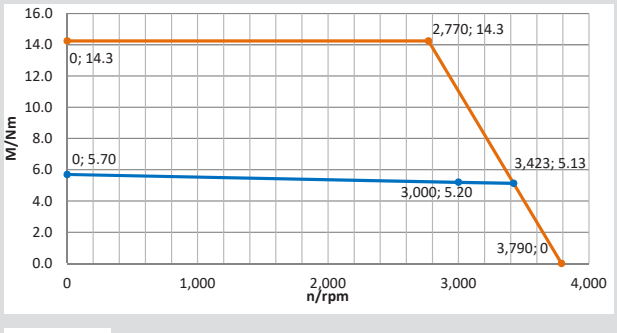
320 / 560 V

Specifications

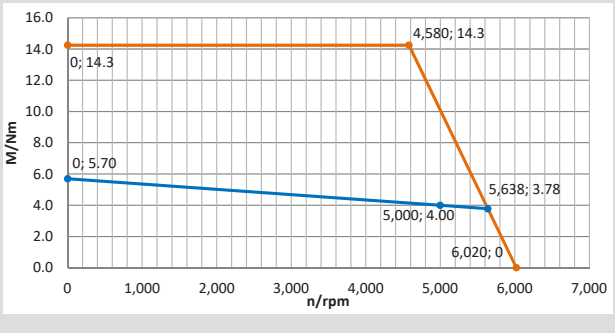
		HMD10-057			
Rated speed [rpm]	n_n	3,000	5,000	3,000	5,000
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	177	182	323	284
Rated power [W]	P_n	1,635	2,095	1,635	2,095
Rated torque [Nm]	M_n	5.2	4.0	5.2	4.0
Rated current per phase [A_{rms}]	I_n	6.1	7.6	3.4	4.8
Stall torque [Nm]	**M_0**	**5.7**	**5.7**	**5.7**	**5.7**
Stall current per phase [A_{rms}]	I_0	6.5	10.2	3.6	6.5
Peak torque [Nm]	M_{max}	14.3	14.3	14.3	14.3
Peak current [A_{rms}]	I_{max}	16.3	25.5	9.0	16.3
Maximum speed [rpm]	n_{max}	3,790	6,020	3,650	6,630
Voltage constant at 1,000 rpm [V_{rms}]	k_e	55.6	35.0	101.1	55.6
Torque constant [Nm / A_{rms}]	k_t	0.85	0.53	1.53	0.83
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	1.72	0.70	5.6	1.72
Winding inductance (2 phases) [mH]	L_{p-p}	5.5	2.2	18.2	5.5
Electrical time constant [ms]	t_{el}	3.2	3.1	3.3	3.2
Thermal time constant [min]	t_{th}	30	30	30	30
Moment of inertia rotor [kg-cm²]	J	2.75E+00	2.75E+00	2.75E+00	2.75E+00
Weight of motor [kg]	m	5.0	5.0	5.0	5.0

Performance

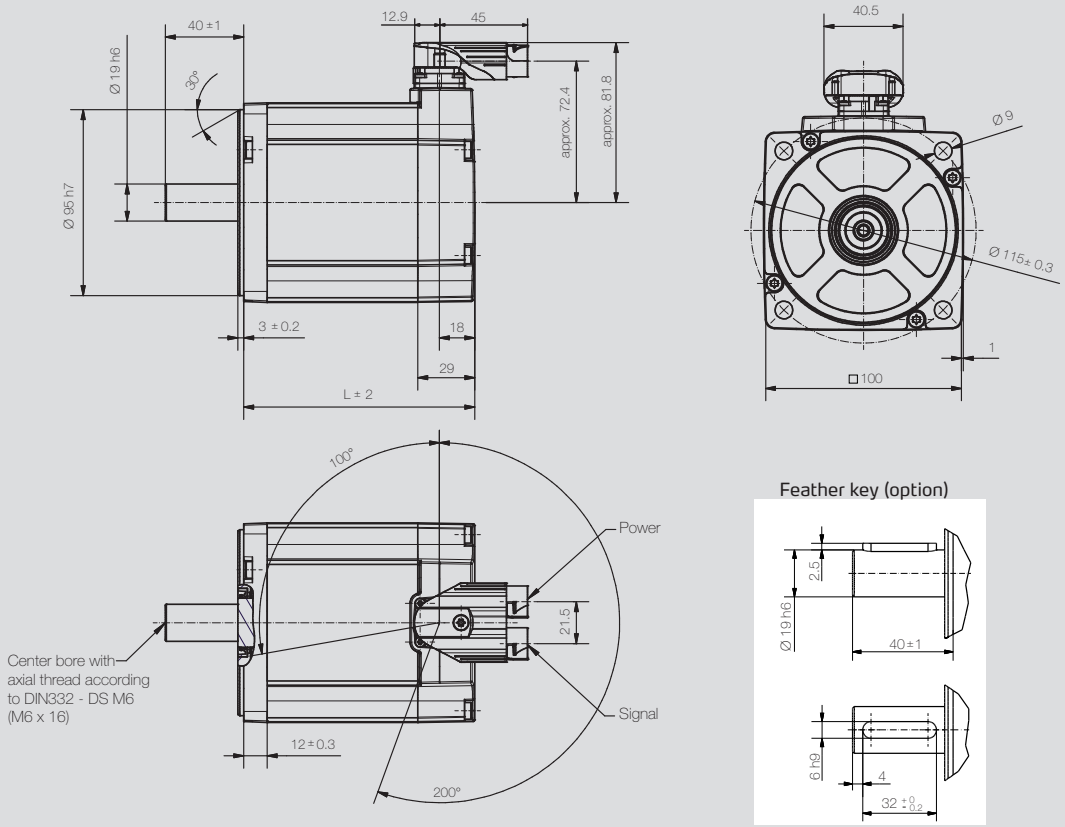
HMD10-057-320-30-*



HMD10-057-320-50-*



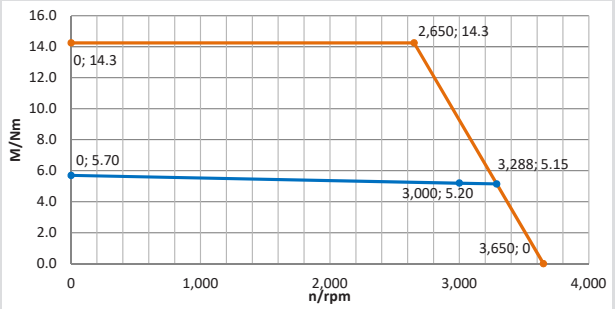
Dimensions



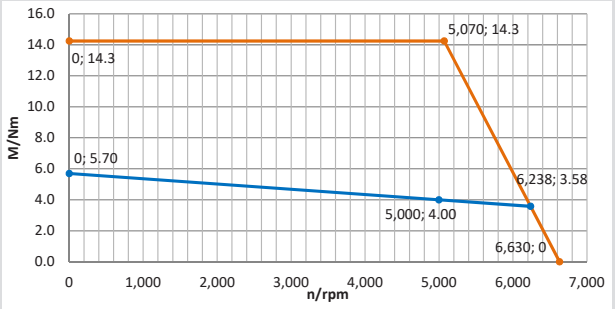
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD10-057	139 mm	186 mm	160 mm	207 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD10-057-560-30-*



HMD10-057-560-50-*



HMD10-076

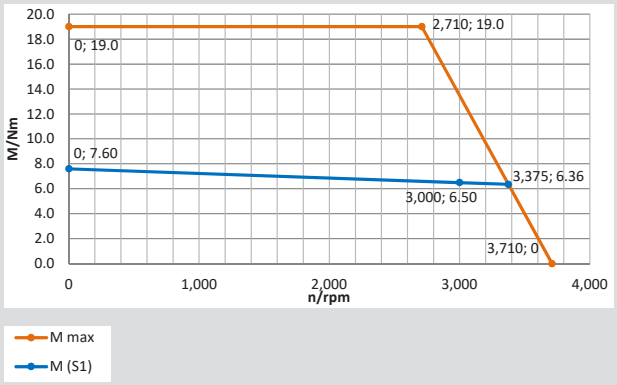
48 V

Specifications

		HMD10-076
Rated speed [rpm]	n_n	3,000
Number of pole pairs		5
Wiring of the motor winding		Y
DC bus voltage [V_{DC}]	U_{bus}	48
Rated voltage motor [V_{rms}]	U_{mot}	26.6
Rated power [W] [1)]	P_n	2,000
Rated torque [Nm]	M_n	6.5
Rated current per phase [A_{rms}]	I_n	50.3
Stall torque [Nm]	**M_0**	**7.6**
Stall current per phase [A_{rms}]	I_0	57.7
Peak torque [Nm]	M_{max}	19.0
Peak current [A_{rms}]	I_{max}	144.3
Maximum speed [rpm]	n_{max}	3,710
Voltage constant at 1,000 rpm [V_{rms}]	k_e	8.4
Torque constant [Nm / A_{rms}]	k_t	0.13
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.025
Winding inductance (2 phases) [mH]	L_{p-p}	0.098
Electrical time constant [ms]	t_{el}	3.8
Thermal time constant [min]	t_{th}	35
Moment of inertia rotor [kg-cm²]	J	3.57E+00
Weight of motor [kg]	m	5.5

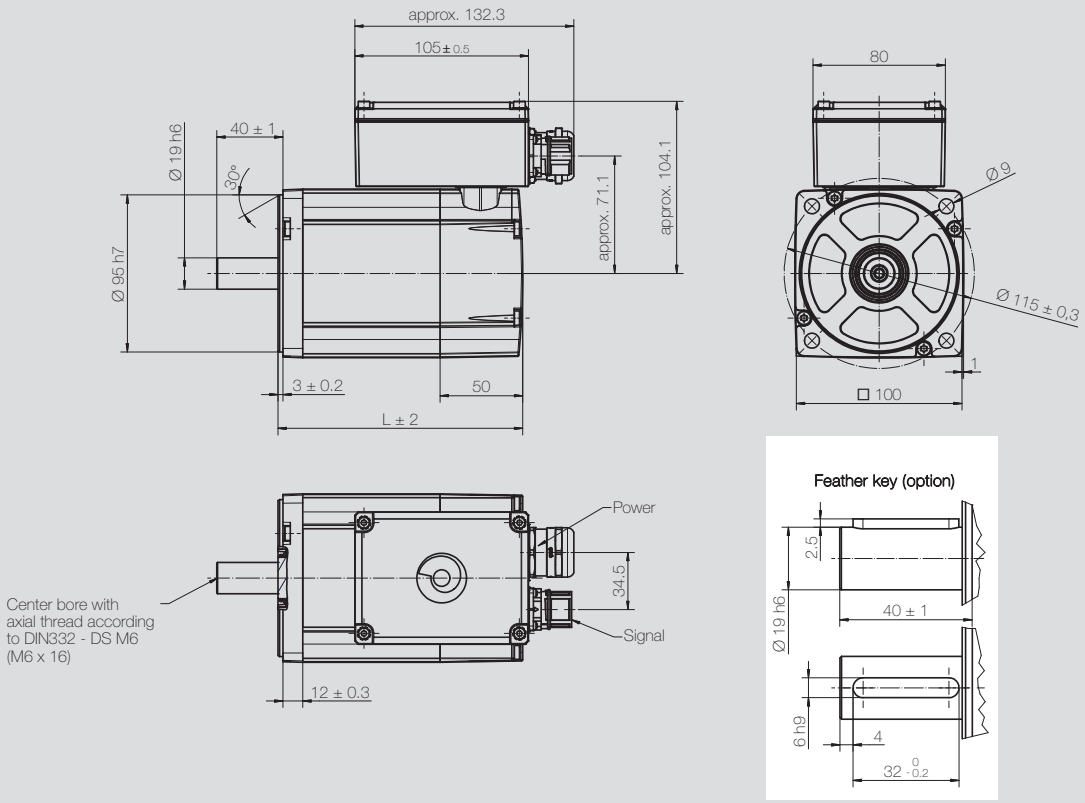
Performance

HMD10-076-048-30-*



[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions



	L [mm]	
Motor	without Brake	with Brake
HMD10-076	175 mm	222 mm

HMD10-076

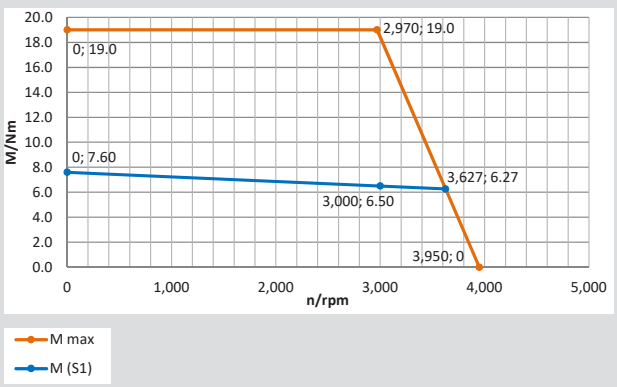
320 / 560 V

Specifications

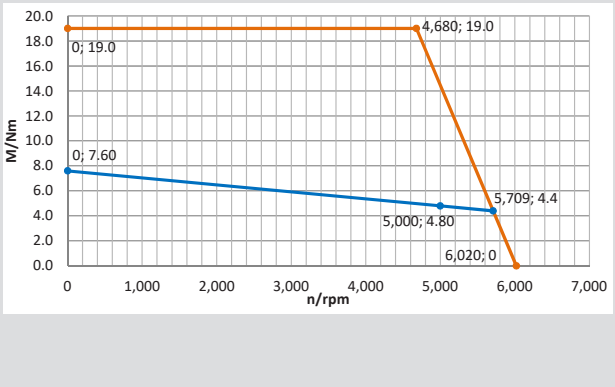
		HMD10-076			
Rated speed [rpm]	n_n	3,000	5,000	3,000	5,000
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	166	176	315	268
Rated power [W]	P_n	2,000	2,500	2,000	2,500
Rated torque [Nm]	M_n	6.5	4.8	6.5	4.8
Rated current per phase [A_{rms}]	I_n	8.0	9.4	4.3	6.3
Stall torque [Nm]	**M_0**	**7.6**	**7.6**	**7.6**	**7.6**
Stall current per phase [A_{rms}]	I_0	9.1	13.5	4.9	9.1
Peak torque [Nm]	M_{max}	19.0	19.0	19.0	19.0
Peak current [A_{rms}]	I_{max}	22.8	33.8	12.3	22.8
Maximum speed [rpm]	n_{max}	3,950	6,020	3,720	6,920
Voltage constant at 1,000 rpm [V_{rms}]	k_e	53.3	35.0	99.0	53.3
Torque constant [Nm / A_{rms}]	k_t	0.81	0.51	1.51	0.76
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	1.03	0.44	3.4	1.03
Winding inductance (2 phases) [mH]	L_{p-p}	3.64	1.6	13.0	3.64
Electrical time constant [ms]	t_{el}	3.6	3.6	3.8	3.6
Thermal time constant [min]	t_{th}	35	35	35	35
Moment of inertia rotor [kg-cm²]	J	3.57E+00	3.57E+00	3.57E+00	3.57E+00
Weight of motor [kg]	m	5.5	5.5	5.5	5.5

Performance

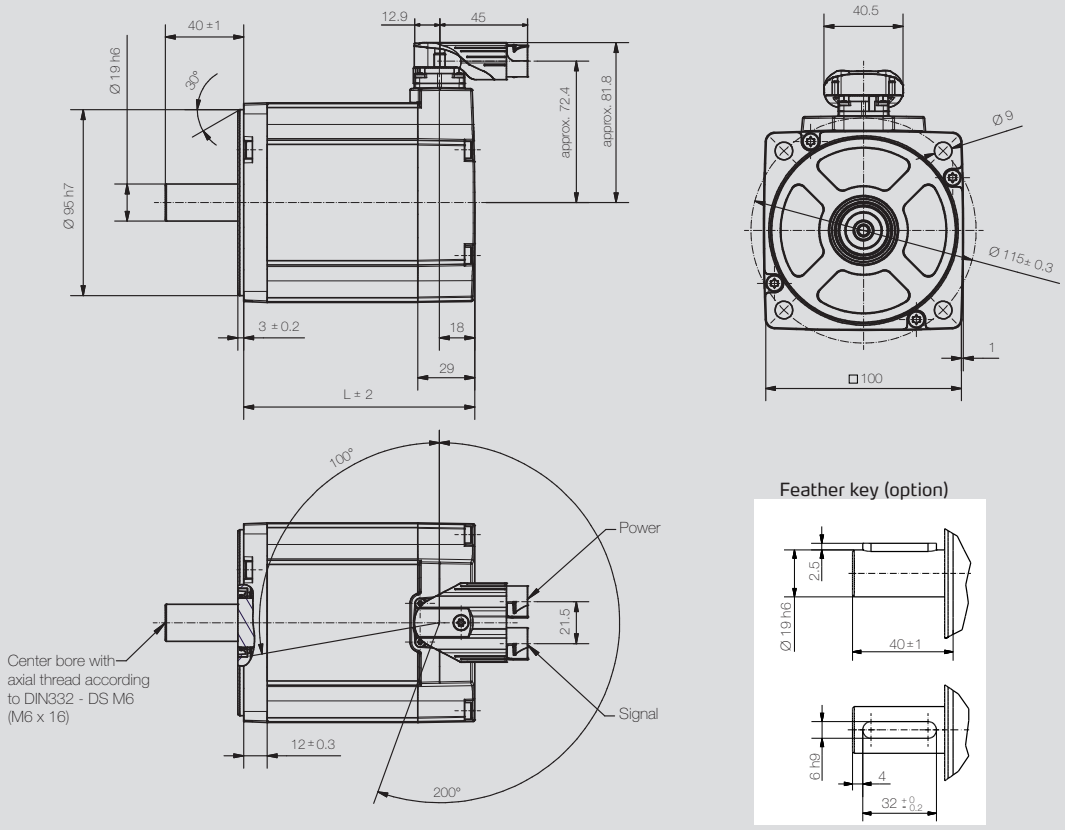
HMD10-076-320-30-*



HMD10-076-320-50-*



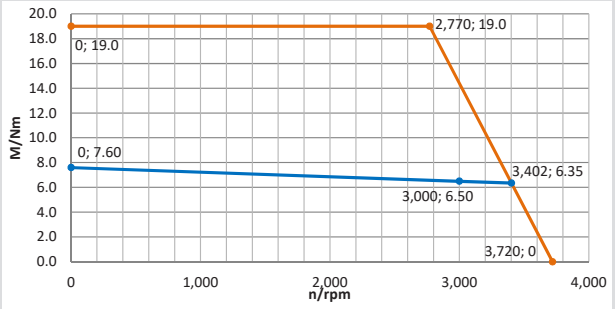
Dimensions



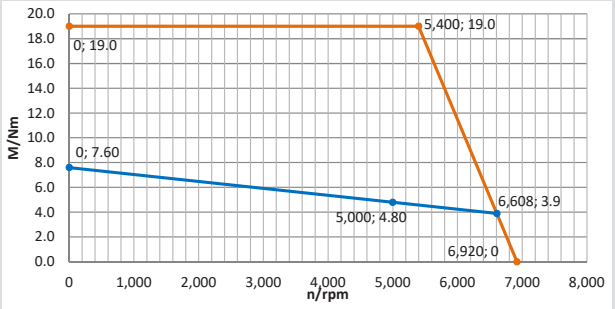
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD10-076	154 mm	201 mm	175 mm	222 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD10-076-560-30-*



HMD10-076-560-50-*



HMD10-105

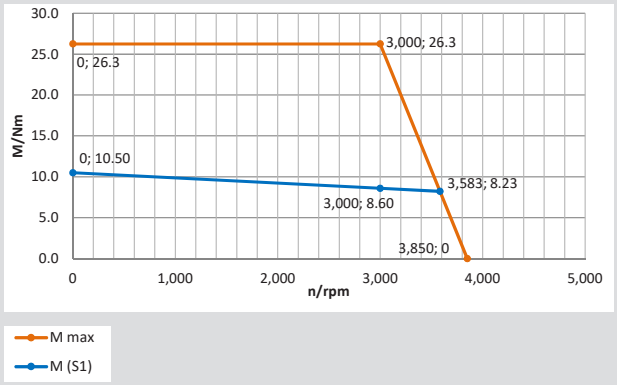
48 V

Specifications

		HMD10-105
Rated speed [rpm]	n_n	3,000
Number of pole pairs		5
Wiring of the motor winding		Y
DC bus voltage [V_{DC}]	U_{bus}	48
Rated voltage motor [V_{rms}]	U_{mot}	25
Rated power [W] [1)]	P_n	2,700
Rated torque [Nm]	M_n	8.6
Rated current per phase [A_{rms}]	I_n	70.6
Stall torque [Nm]	**M_0**	**10.5**
Stall current per phase [A_{rms}]	I_0	82.3
Peak torque [Nm]	M_{max}	26.3
Peak current [A_{rms}]	I_{max}	205.8
Maximum speed [rpm]	n_{max}	3,850
Voltage constant at 1,000 rpm [V_{rms}]	k_e	8.1
Torque constant [Nm / A_{rms}]	k_t	0.12
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.014
Winding inductance (2 phases) [mH]	L_{p-p}	0.057
Electrical time constant [ms]	t_{el}	4.07
Thermal time constant [min]	t_{th}	35
Moment of inertia rotor [kg-cm²]	J	5.21E+00
Weight of motor [kg]	m	6.5

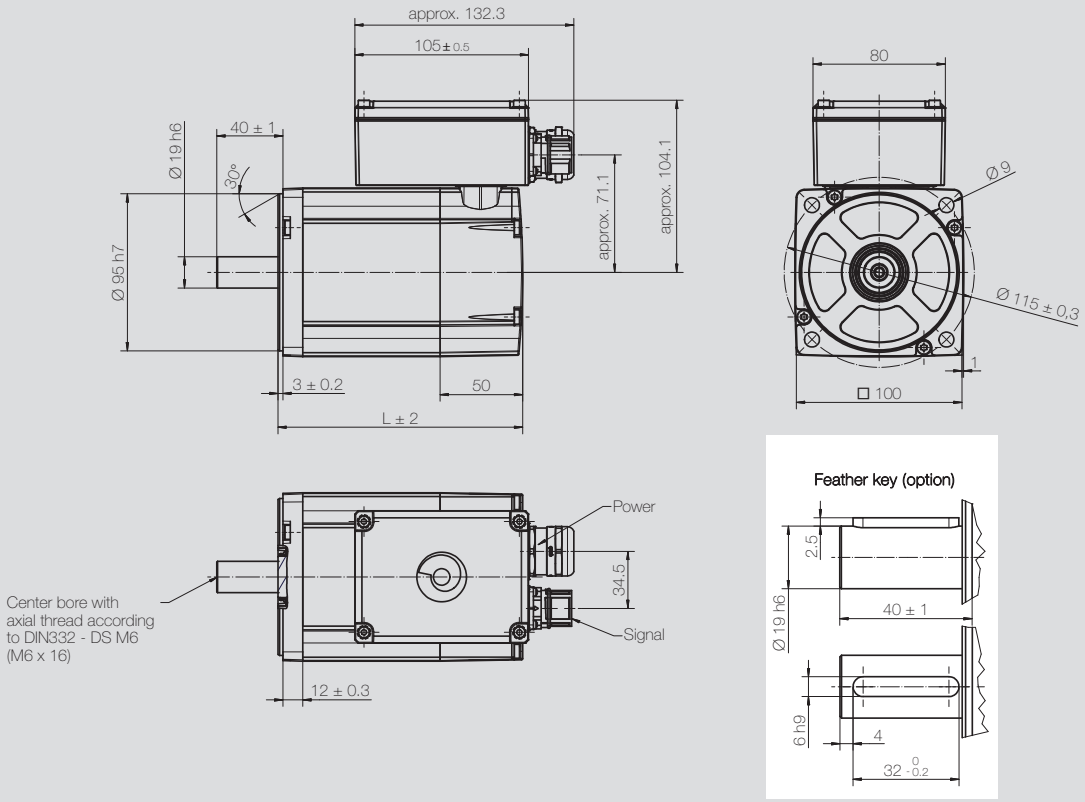
Performance

HMD10-105-048-30-*



[1)] For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values.

Dimensions



	L [mm]	
Motor	without Brake	with Brake
HMD10-105	205 mm	252 mm

HMD10-105

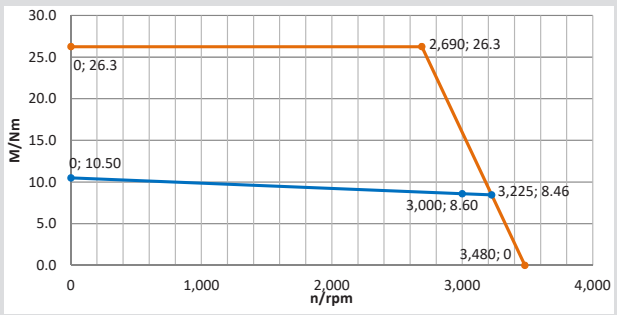
320 / 560 V

Specifications

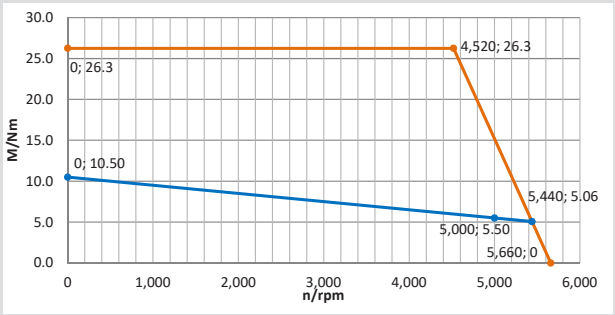
		HMD10-105			
Rated speed [rpm]	n_n	3,000	5,000	3,000	5,000
Number of pole pairs		5	5	5	5
Wiring of the motor winding		Y	Y	Y	Y
DC bus voltage [V_{DC}]	U_{bus}	320	320	560	560
Rated voltage motor [V_{rms}]	U_{mot}	186	184	321	299
Rated power [W]	P_n	2,700	2,900	2,700	2,900
Rated torque [Nm]	M_n	8.6	5.5	8.6	5.5
Rated current per phase [A_{rms}]	I_n	9.5	10.6	5.5	6.5
Stall torque [Nm]	**M_0**	**10.5**	**10.5**	**10.5**	**10.5**
Stall current per phase [A_{rms}]	I_0	11.0	18.0	6.4	11.0
Peak torque [Nm]	M_{max}	26.3	26.3	26.3	26.3
Peak current [A_{rms}]	I_{max}	27.5	45.0	16.0	27.5
Maximum speed [rpm]	n_{max}	3,480	5,660	3,520	6,090
Voltage constant at 1,000 rpm [V_{rms}]	k_e	60.5	37.2	104.8	60.5
Torque constant [Nm / A_{rms}]	k_t	0.91	0.52	1.56	0.85
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.77	0.29	2.3	0.77
Winding inductance (2 phases) [mH]	L_{p-p}	3.2	1.2	9.4	3.2
Electrical time constant [ms]	t_{el}	4.2	4.1	4.1	4.2
Thermal time constant [min]	t_{th}	35	35	35	35
Moment of inertia rotor [kg-cm²]	J	5.21E+00	5.21E+00	5.21E+00	5.21E+00
Weight of motor [kg]	m	6.5	6.5	6.5	6.5

Performance

HMD10-105-320-30-*



HMD10-105-320-50-*



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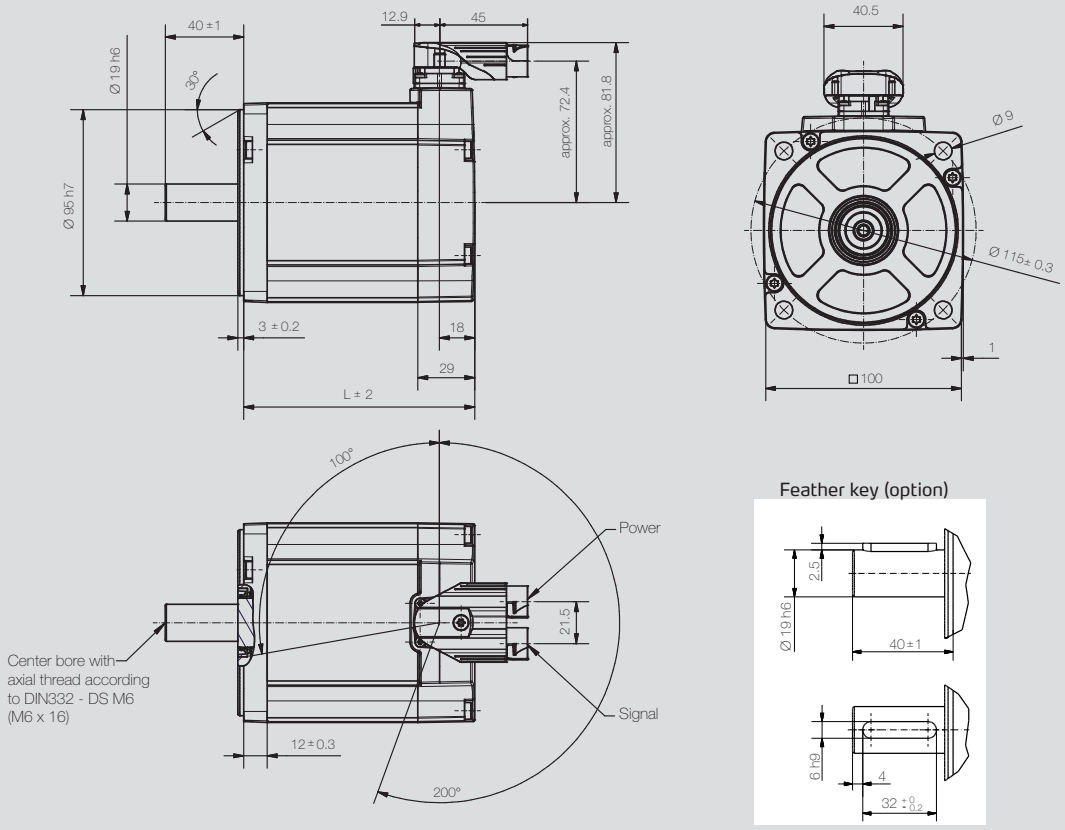
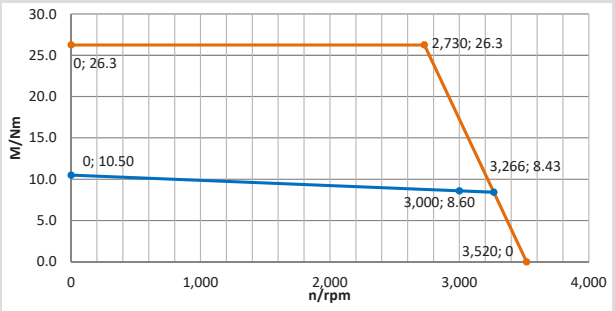


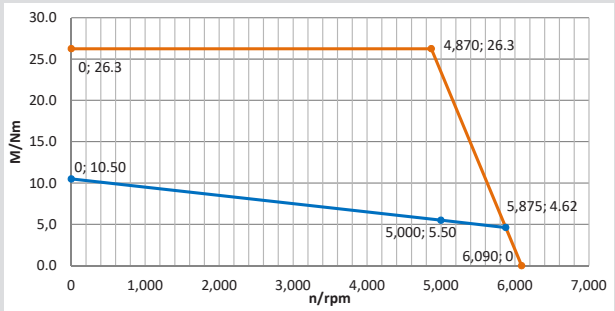
Motor	L [mm] *with encoder categorie 1** without Brake	L [mm] *with encoder categorie 1** with Brake	L [mm] *with encoder categorie 2** without Brake	L [mm] *with encoder categorie 2** with Brake
HMD10-105	184 mm	231 mm	205 mm	252 mm

** Encoder categorie 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16; only for variants with U_{bus} = 320/560 VDC*
Encoder categorie 2: Remaining encoders

HMD10-105-560-30-*



HMD10-105-560-50-*



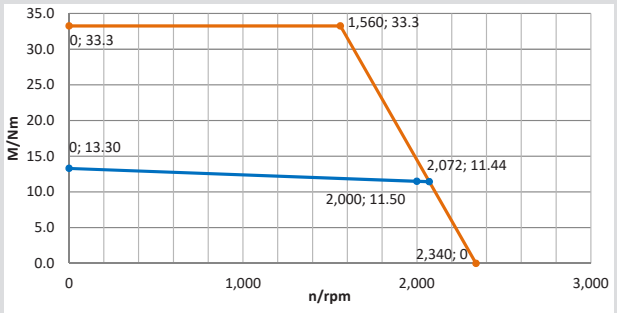
HMD13-133

Specifications

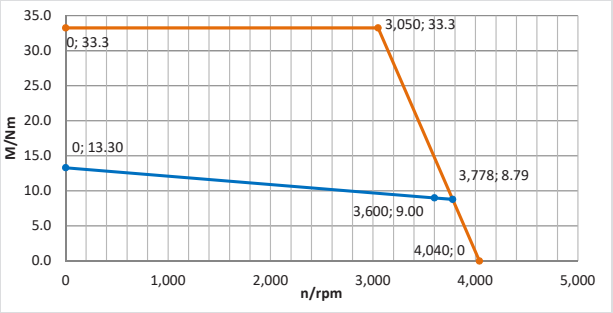
		HMD13-133	
Rated speed [rpm]	n_n	2,000	3,600
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	326	331
Rated power [W]	P_n	2,400	3,400
Rated torque [Nm]	M_n	11.5	9.0
Rated current per phase [A_{rms}]	I_n	4.8	6.3
Stall torque [Nm]	**M_0**	**13.3**	**13.3**
Stall current per phase [A_{rms}]	I_0	5.5	9.3
Peak torque [Nm]	M_{max}	33.3	33.3
Peak current [A_{rms}]	I_{max}	13.8	23.1
Maximum speed [rpm]	n_{max}	2,340	4,040
Voltage constant at 1,000 rpm [V_{rms}]	k_e	157.7	91.2
Torque constant [Nm / A_{rms}]	k_t	2.42	1.43
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	2.67	0.812
Winding inductance (2 phases) [mH]	L_{p-p}	25.04	6.96
Electrical time constant [ms]	t_{el}	9.4	8.6
Thermal time constant [min]	t_{th}	42	42
Moment of inertia rotor [kg-cm²]	J	8.21E+00	8.21E+00
Weight of motor [kg]	m	8.4	8.4

Performance

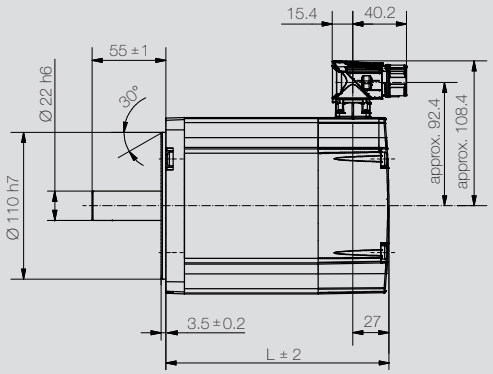
HMD13-133-560-20-*

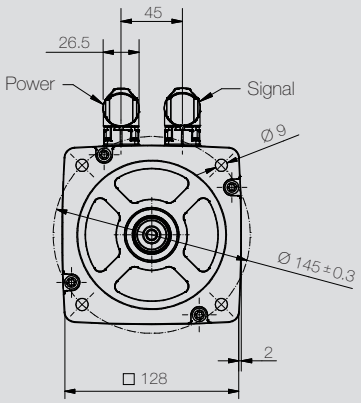


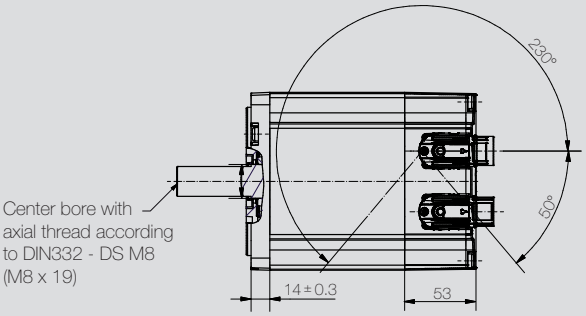
HMD13-133-560-36-*



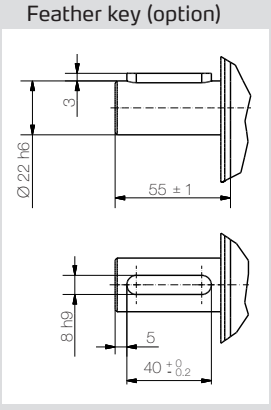
Dimensions







Feather key (option)



L [mm]	
without Brake	with Brake
185 mm	223 mm

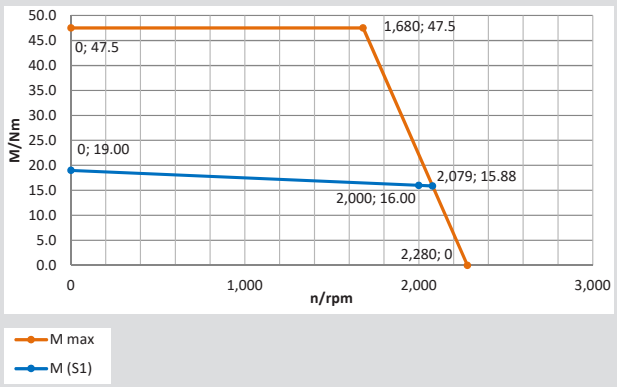
HMD13-190

Specifications

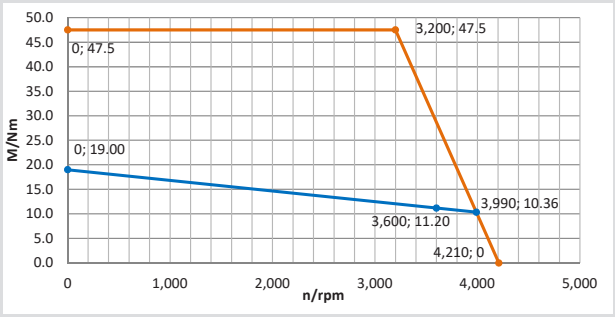
		HMD13-190	
Rated speed [rpm]	n_n	2,000	3,600
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	330	316
Rated power [W]	P_n	3,350	4,200
Rated torque [Nm]	M_n	16.0	11.2
Rated current per phase [A_{rms}]	I_n	6.3	8.2
Stall torque [Nm]	**M_0**	**19.0**	**19.0**
Stall current per phase [A_{rms}]	I_0	7.5	13.7
Peak torque [Nm]	M_{max}	47.5	47.5
Peak current [A_{rms}]	I_{max}	18.8	34.3
Maximum speed [rpm]	n_{max}	2,280	4,210
Voltage constant at 1,000 rpm [V_{rms}]	k_e	161.9	87.5
Torque constant [Nm / A_{rms}]	k_t	2.54	1.37
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	1.50	0.440
Winding inductance (2 phases) [mH]	L_{p-p}	15.25	4.5
Electrical time constant [ms]	t_{el}	10.3	10.2
Thermal time constant [min]	t_{th}	49	49
Moment of inertia rotor [kg-cm²]	J	1.20E+01	1.20E+01
Weight of motor [kg]	m	11.0	11.0

Performance

HMD13-190-560-20-*



HMD13-190-560-36-*



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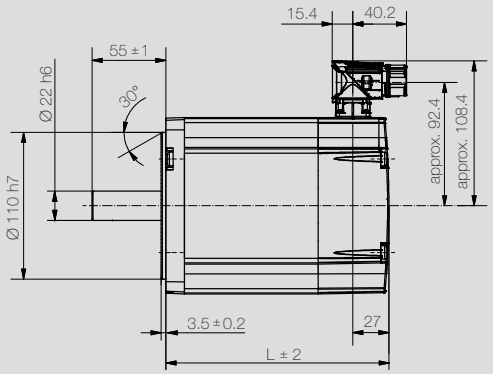
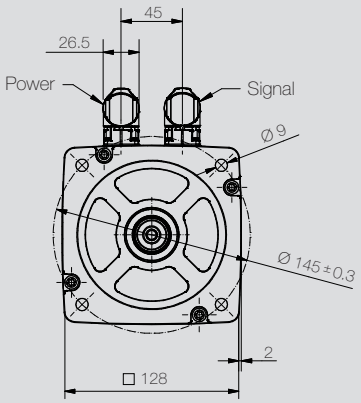
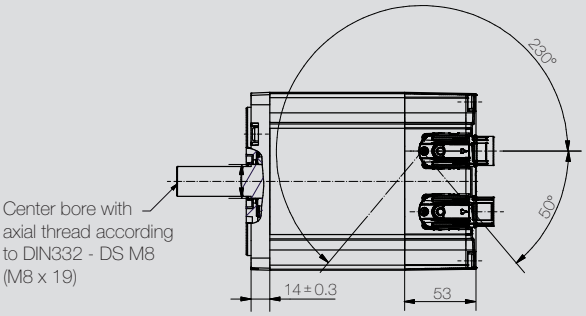
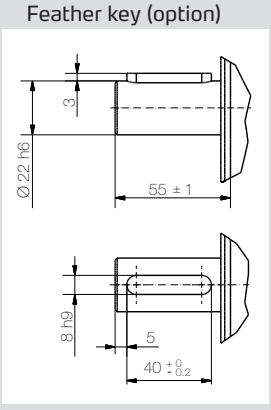






Feather key (option)



L [mm]	
without Brake	with Brake
215 mm	253 mm

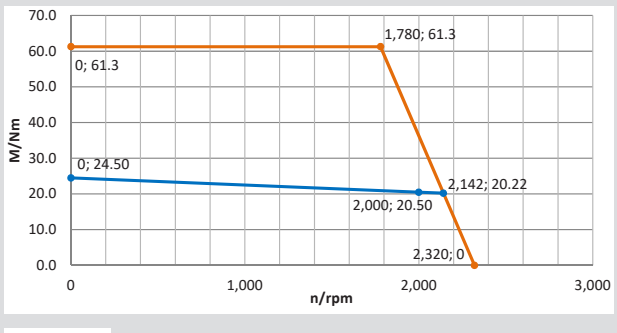
HMD13-245

Specifications

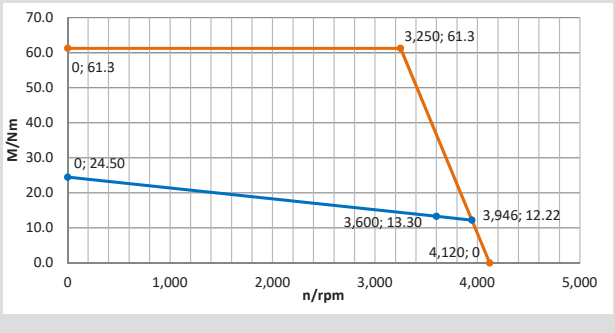
		HMD13-245	
Rated speed [rpm]	n_n	2,000	3,600
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	327	322
Rated power [W]	P_n	4,300	5,000
Rated torque [Nm]	M_n	20.5	13.3
Rated current per phase [A_{rms}]	I_n	8.2	9.6
Stall torque [Nm]	**M_0**	**24.5**	**24.5**
Stall current per phase [A_{rms}]	I_0	9.7	17.1
Peak torque [Nm]	M_{max}	61.3	61.3
Peak current [A_{rms}]	I_{max}	24.3	42.8
Maximum speed [rpm]	n_{max}	2,320	4,120
Voltage constant at 1,000 rpm [V_{rms}]	k_e	158.7	89.5
Torque constant [Nm / A_{rms}]	k_t	2.50	1.39
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	1.08	0.340
Winding inductance (2 phases) [mH]	L_{p-p}	10.59	3.33
Electrical time constant [ms]	t_{el}	9.8	9.7
Thermal time constant [min]	t_{th}	49	49
Moment of inertia rotor [kg-cm²]	J	1.58E+01	1.58E+01
Weight of motor [kg]	m	13.5	13.5

Performance

HMD13-245-560-20-*



HMD13-245-560-36-*



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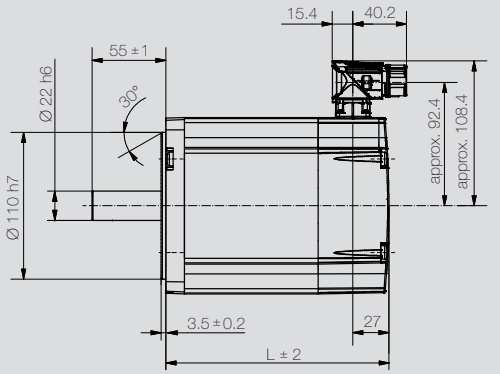

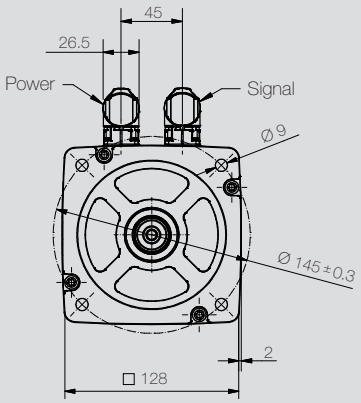

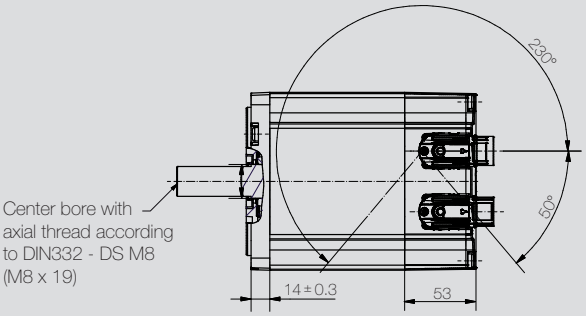

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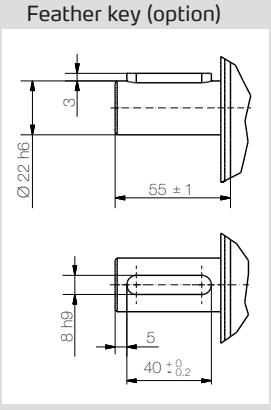


L [mm]	
without Brake	with Brake
245 mm	306 mm

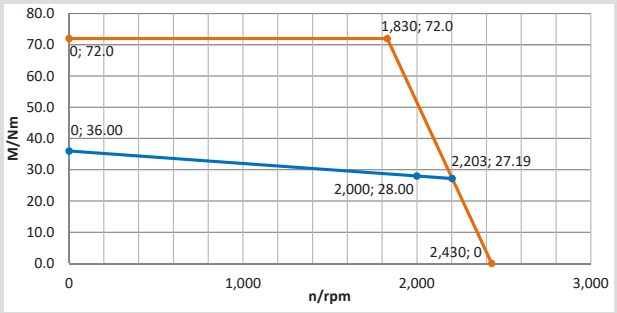
HMD15-036

Specifications

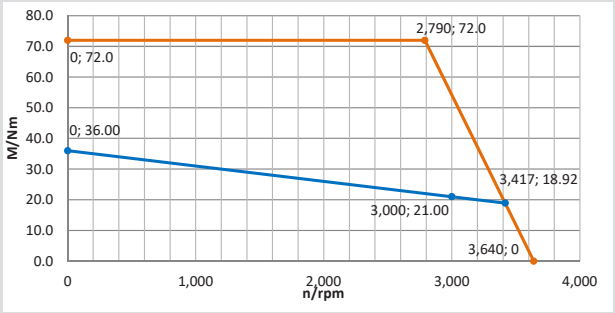
		HMD15-036	
Rated speed [rpm]	n_n	2,000	3,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	314	307
Rated power [W]	P_n	5,850	6,600
Rated torque [Nm]	M_n	28.0	21.0
Rated current per phase [A_{rms}]	I_n	11.7	13.2
Stall torque [Nm]	**M_0**	**36.0**	**36.0**
Stall current per phase [A_{rms}]	I_0	15.1	22.6
Peak torque [Nm]	M_{max}	72.0	72.0
Peak current [A_{rms}]	I_{max}	30.2	45.2
Maximum speed [rpm]	n_{max}	2,430	3,640
Voltage constant at 1,000 rpm [V_{rms}]	k_e	152.0	101.4
Torque constant [Nm / A_{rms}]	k_t	2.39	1.59
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.560	0.250
Winding inductance (2 phases) [mH]	L_{p-p}	8.9	3.94
Electrical time constant [ms]	t_{el}	15.9	15.8
Thermal time constant [min]	t_{th}	45	45
Moment of inertia rotor [kg-cm²]	J	3.87E+01	3.87E+01
Weight of motor [kg]	m	19.0	19.0

Performance

HMD15-036-560-20-*



HMD15-036-560-30-*



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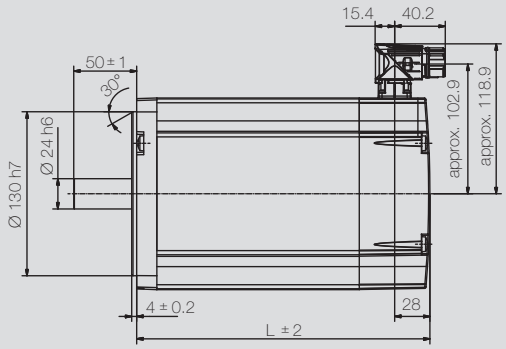
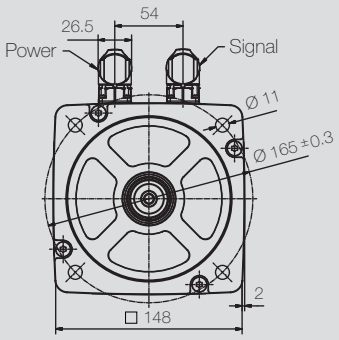
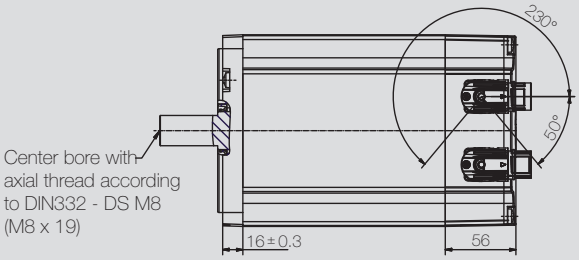
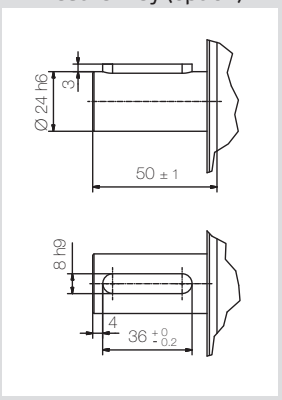






Feather key (option)



Motor	L [mm] without Brake	L [mm] with Brake
HMD15-036	260 mm	311 mm

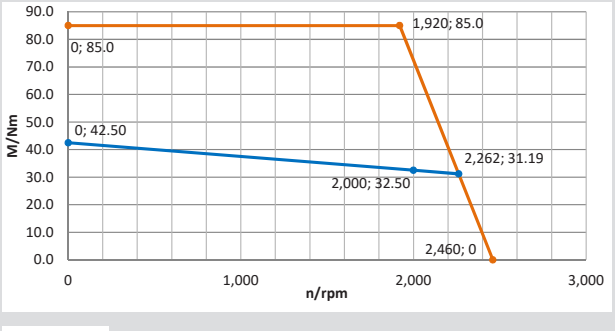
HMD15-043

Specifications

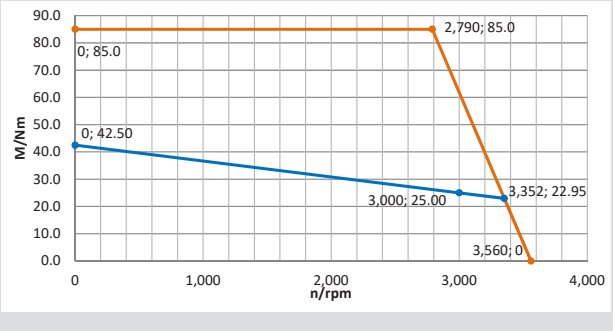
		HMD15-043	
Rated speed [rpm]	n_n	2,000	3,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	307	313
Rated power [W]	P_n	6,800	7,850
Rated torque [Nm]	M_n	32.5	25.0
Rated current per phase [A_{rms}]	I_n	13.8	15.3
Stall torque [Nm]	**M_0**	**42.5**	**42.5**
Stall current per phase [A_{rms}]	I_0	18.0	26.0
Peak torque [Nm]	M_{max}	85.0	85.0
Peak current [A_{rms}]	I_{max}	36.0	52.0
Maximum speed [rpm]	n_{max}	2,460	3,560
Voltage constant at 1,000 rpm [V_{rms}]	k_e	149.8	103.7
Torque constant [Nm / A_{rms}]	k_t	2.36	1.63
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.41	0.2
Winding inductance (2 phases) [mH]	L_{p-p}	6.8	3.3
Electrical time constant [ms]	t_{el}	16.6	16.5
Thermal time constant [min]	t_{th}	50	50
Moment of inertia rotor [kg-cm²]	J	4.82E+01	4.82E+01
Weight of motor [kg]	m	23.0	23.0

Performance

HMD15-043-560-20-*



HMD15-043-560-30-*



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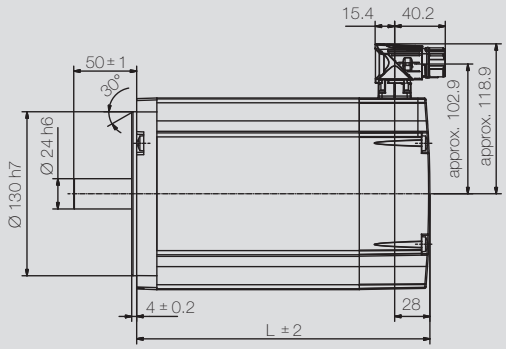

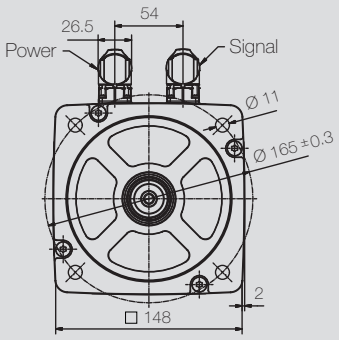

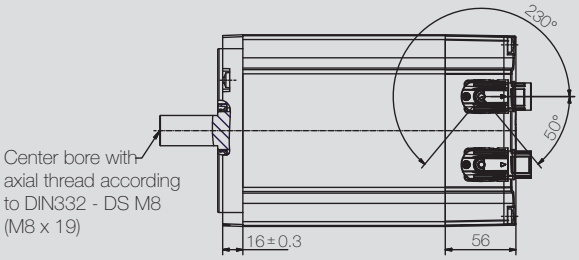

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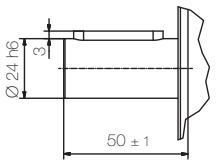
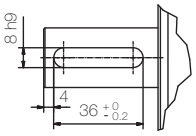




Motor	L [mm] without Brake	L [mm] with Brake
HMD15-043	290 mm	341 mm

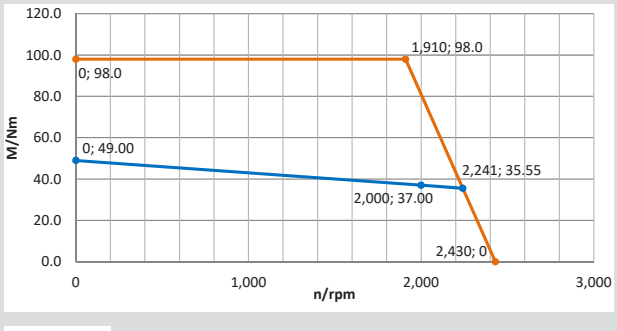
HMD15-049

Specifications

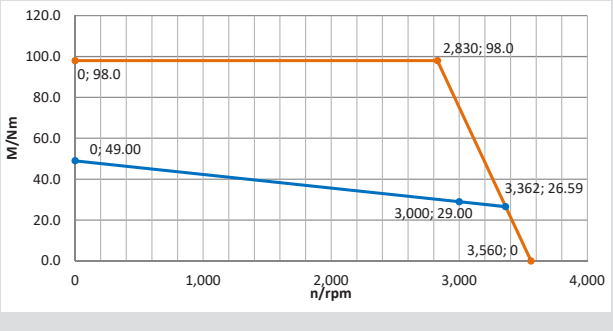
		HMD15-049	
Rated speed [rpm]	n_n	2,000	3,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	311	313
Rated power [W]	P_n	7,750	9,110
Rated torque [Nm]	M_n	37.0	29.0
Rated current per phase [A_{rms}]	I_n	15.5	17.8
Stall torque [Nm]	**M_0**	**49.0**	**49.0**
Stall current per phase [A_{rms}]	I_0	20.4	30.0
Peak torque [Nm]	M_{max}	98.0	98.0
Peak current [A_{rms}]	I_{max}	40.8	60.0
Maximum speed [rpm]	n_{max}	2,430	3,560
Voltage constant at 1,000 rpm [V_{rms}]	k_e	152.0	103.7
Torque constant [Nm / A_{rms}]	k_t	2.39	1.63
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.348	0.160
Winding inductance (2 phases) [mH]	L_{p-p}	5.93	2.75
Electrical time constant [ms]	t_{el}	17.0	17.2
Thermal time constant [min]	t_{th}	55	55
Moment of inertia rotor [kg-cm²]	J	5.76E+01	5.76E+01
Weight of motor [kg]	m	26.0	26.0

Performance

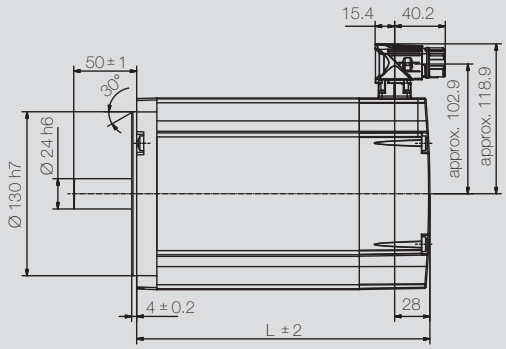
HMD15-049-560-20-*

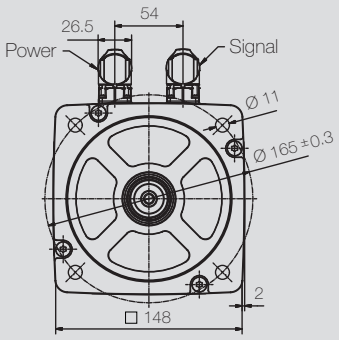


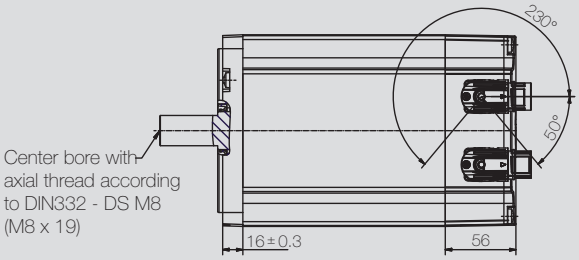
HMD15-049-560-30-*



Dimensions







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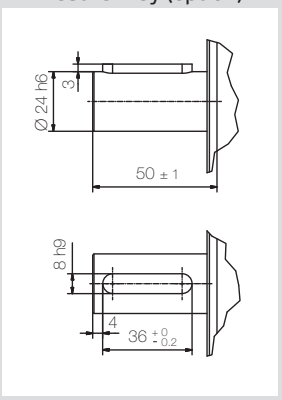


Motor	L [mm] without Brake	L [mm] with Brake
HMD15-049	320 mm	384 mm

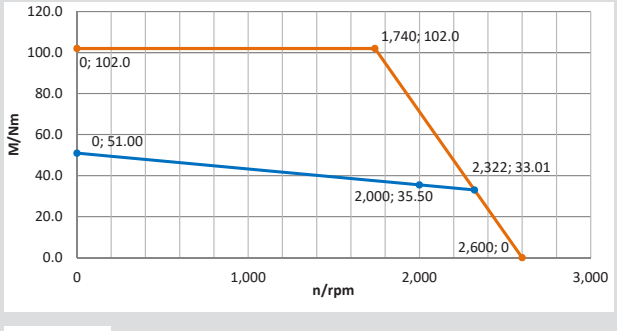
HMD19-051

Specifications

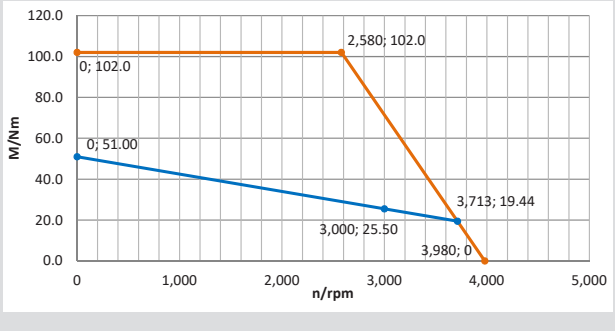
		HMD19-051	
Rated speed [rpm]	n_n	2,000	3,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	284	283
Rated power [W]	P_n	7,435	8,000
Rated torque [Nm]	M_n	35.5	25.5
Rated current per phase [A_{rms}]	I_n	16.6	17.6
Stall torque [Nm]	**M_0**	**51.0**	**51.0**
Stall current per phase [A_{rms}]	I_0	24.5	35.9
Peak torque [Nm]	M_{max}	102.0	102.0
Peak current [A_{rms}]	I_{max}	49.0	71.8
Maximum speed [rpm]	n_{max}	2,600	3,980
Voltage constant at 1,000 rpm [V_{rms}]	k_e	141.8	92.7
Torque constant [Nm / A_{rms}]	k_t	2.14	1.45
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.175	0.081
Winding inductance (2 phases) [mH]	L_{p-p}	6.88	3.28
Electrical time constant [ms]	t_{el}	78.2	40.5
Thermal time constant [min]	t_{th}	60	60
Moment of inertia rotor [kg-cm²]	J	7.42E+01	7.42E+01
Weight of motor [kg]	m	35.0	35.0

Performance

HMD19-051-560-20-*



HMD19-051-560-30-*



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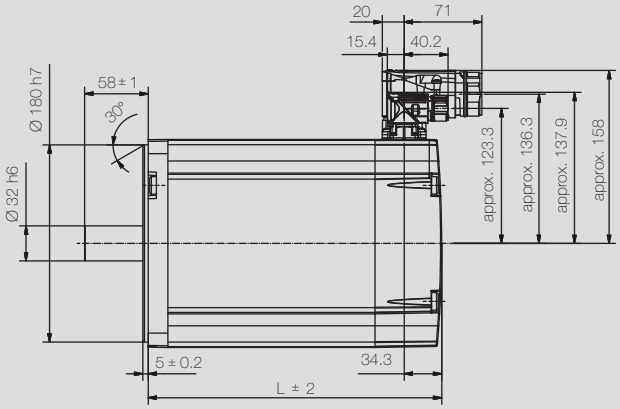

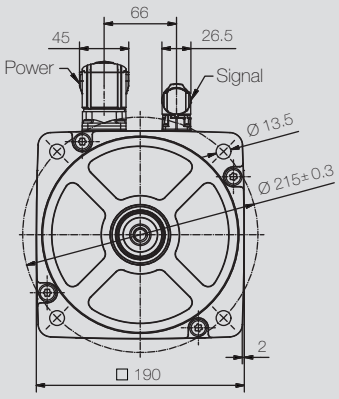

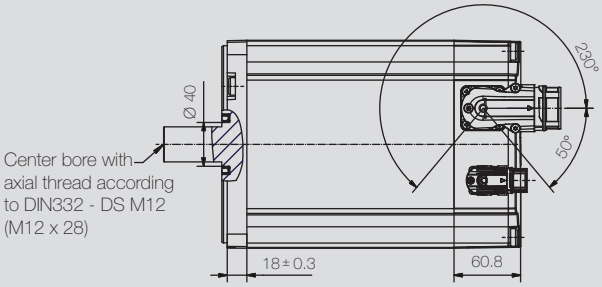

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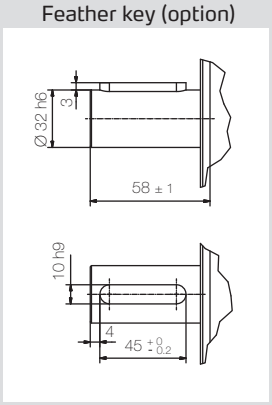


Motor	L [mm] without Brake	L [mm] with Brake
HMD19-051	283 mm	336 mm

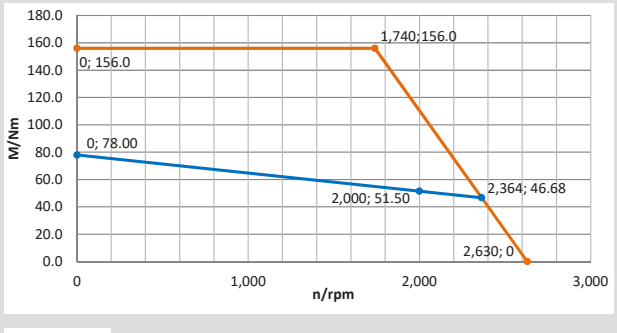
HMD19-078

Specifications

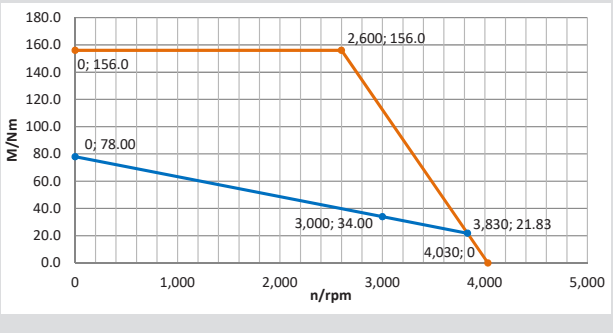
		HMD19-078	
Rated speed [rpm]	n_n	2,000	3,000
Number of pole pairs		5	5
Wiring of the motor winding		Y	Y
DC bus voltage [V_{DC}]	U_{bus}	560	560
Rated voltage motor [V_{rms}]	U_{mot}	280	273
Rated power [W]	P_n	10,780	10,680
Rated torque [Nm]	M_n	51.5	34.0
Rated current per phase [A_{rms}]	I_n	24.4	24.1
Stall torque [Nm]	**M_0**	**78.0**	**78.0**
Stall current per phase [A_{rms}]	I_0	38.0	56.6
Peak torque [Nm]	M_{max}	156.0	156.0
Peak current [A_{rms}]	I_{max}	76.0	113.2
Maximum speed [rpm]	n_{max}	2,630	4,030
Voltage constant at 1,000 rpm [V_{rms}]	k_e	140.1	91.4
Torque constant [Nm / A_{rms}]	k_t	2.11	1.41
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.104	0.046
Winding inductance (2 phases) [mH]	L_{p-p}	4.50	2.08
Electrical time constant [ms]	t_{el}	42.5	45.2
Thermal time constant [min]	t_{th}	70	70
Moment of inertia rotor [kg-cm²]	J	1.10E+02	1.10E+02
Weight of motor [kg]	m	44.0	44.0

Performance

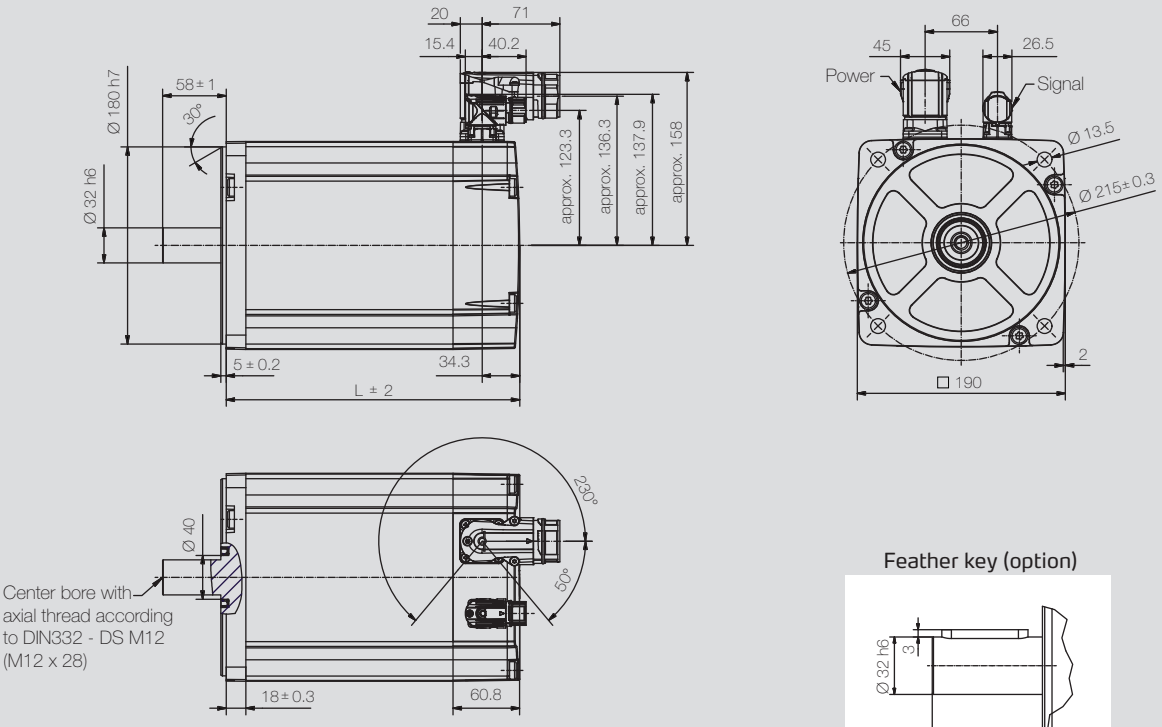
HMD19-078-560-20-*



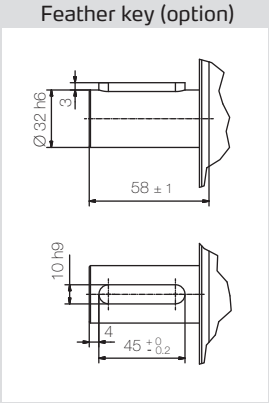
HMD19-078-560-30-*



Dimensions



Feather key (option)



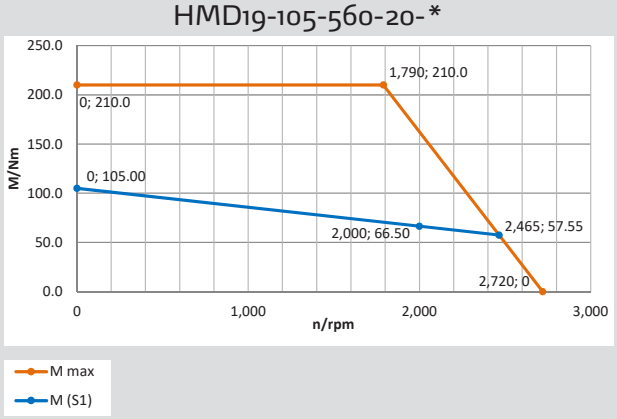
	L [mm]	
Motor	without Brake	with Brake
HMD19-078	343 mm	406 mm

HMD19-105

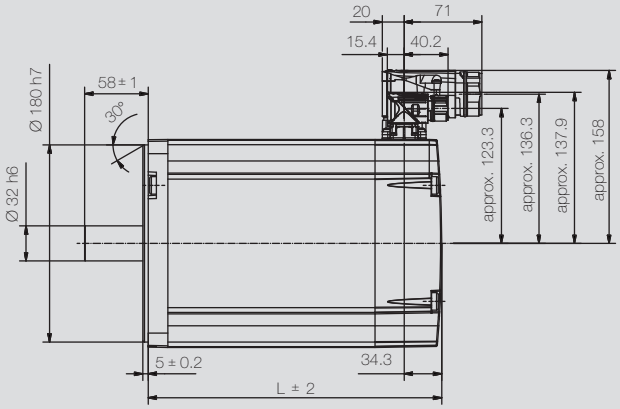
Specifications

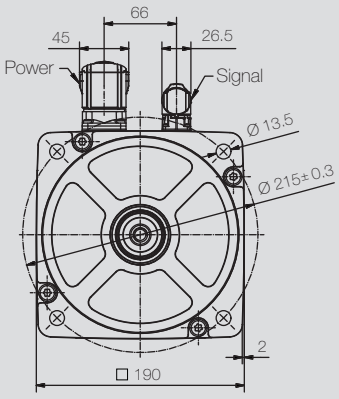
		HMD19-105
Rated speed [rpm]	n_n	2,000
Number of pole pairs		5
Wiring of the motor winding		Y
DC bus voltage [V_{DC}]	U_{bus}	560
Rated voltage motor [V_{rms}]	U_{mot}	271
Rated power [W]	P_n	13,920
Rated torque [Nm]	M_n	66.5
Rated current per phase [A_{rms}]	I_n	32.5
Stall torque [Nm]	**M_0**	**105.0**
Stall current per phase [A_{rms}]	I_0	52.5
Peak torque [Nm]	M_{max}	210.0
Peak current [A_{rms}]	I_{max}	105.0
Maximum speed [rpm]	n_{max}	2,720
Voltage constant at 1,000 rpm [V_{rms}]	k_e	135.5
Torque constant [Nm / A_{rms}]	k_t	2.05
Winding resistance (2 phases) at 20 °C [Ω]	R_{p-p}	0.071
Winding inductance (2 phases) [mH]	L_{p-p}	3.20
Electrical time constant [ms]	t_{el}	44.8
Thermal time constant [min]	t_{th}	80
Moment of inertia rotor [kg-cm²]	J	1.45E+02
Weight of motor [kg]	m	53.0

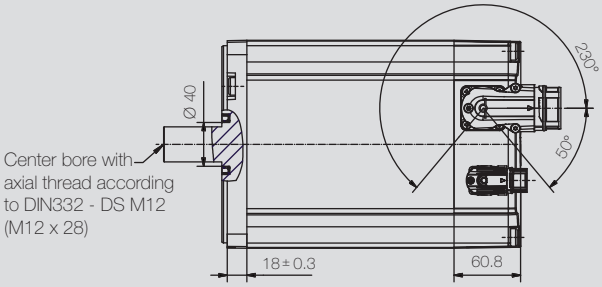
Performance



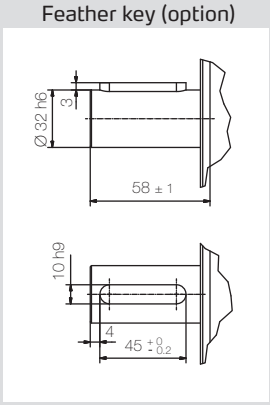
Dimensions







Feather key (option)



Motor	L [mm] without Brake	L [mm] with Brake
HMD19-105	403 mm	466 mm

Configuration options

Feedback options

(Interfaces see page 78 - 87)

As standard, HeiMotion Dynamic motors are supplied with a resolver. As an option, various encoders with different interfaces can be mounted to the series.

Motor model	Resolver*	HES1 (4.5 V pp)	HES1 (1.0 V pp)	HEM1 (1.0 V pp without battery)	HEM1 (1.0 V pp with battery)	HS/M16	HES 3	ECI1118	EQI 1131
HMD06-XXX-024-*	X	X	X	X	X	X	X	X	
HMD06-XXX-048-*	X	X	X	X	X	X	X	X	
HMD06-XXX-320-*	X	X	X	X	X	X	X	X	X
HMD06-XXX-560-*	X	X	X	X	X	X	X	X	X
HMD08-XXX-024-*	X	X	X	X	X	X	X	X	
HMD08-XXX-048-*	X	X	X	X	X	X	X	X	
HMD08-XXX-320-*	X	X	X	X	X	X	X	X	X
HMD08-XXX-560-*	X	X	X	X	X	X	X	X	X
HMD10-XXX-048-*	X	X	X	X	X	X	X	X	
HMD10-XXX-320-*	X	X	X	X	X	X	X	X	X
HMD10-XXX-560-*	X	X	X	X	X	X	X	X	X
HMD13-XXX-560-*	X	X	X	X	X	X	X	X	X
HMD15-XXX-560-*	X	X	X	X	X	X	X		
HMD19-XXX-560-*	X	X	X	X	X	X	X		

Motor model	ECI 1319	EQI 1331	SEK 37	SEL 37	SKS 36*	SKM 36*	SRS 50	SRM 50
HMD06-XXX-024-*			X	X				
HMD06-XXX-048-*			X	X				
HMD06-XXX-320-*			X	X	X	X		
HMD06-XXX-560-*			X	X	X	X		
HMD08-XXX-024-*			X	X				
HMD08-XXX-048-*			X	X				
HMD08-XXX-320-*			X	X	X	X	X	X
HMD08-XXX-560-*			X	X	X	X	X	X
HMD10-XXX-048-*			X	X				
HMD10-XXX-320-*			X	X	X	X	X	X
HMD10-XXX-560-*			X	X	X	X	X	X
HMD13-XXX-560-*			X	X	X	X	X	X
HMD15-XXX-560-*	X	X	X	X	X	X	X	X
HMD19-XXX-560-*	X	X	X	X	X	X	X	X

Motor model	EES 37*	EEM 37*	EKS 36*	EKM 36*	EFS 50	EFM 50	CKS 36
HMD06-XXX-024-*							
HMD06-XXX-048-*							
HMD06-XXX-320-*	X	X	X	X			X
HMD06-XXX-560-*	X	X	X	X			X
HMD08-XXX-024-*							
HMD08-XXX-048-*							
HMD08-XXX-320-*	X	X	X	X	X	X	X
HMD08-XXX-560-*	X	X	X	X	X	X	X
HMD10-XXX-048-*							
HMD10-XXX-320-*	X	X	X	X	X	X	X
HMD10-XXX-560-*	X	X	X	X	X	X	X
HMD13-XXX-560-*	X	X	X	X	X	X	X
HMD15-XXX-560-*	X	X	X	X	X	X	
HMD19-XXX-560-*	X	X	X	X	X	X	

* Also available safely mounted, alternative encoder systems upon request

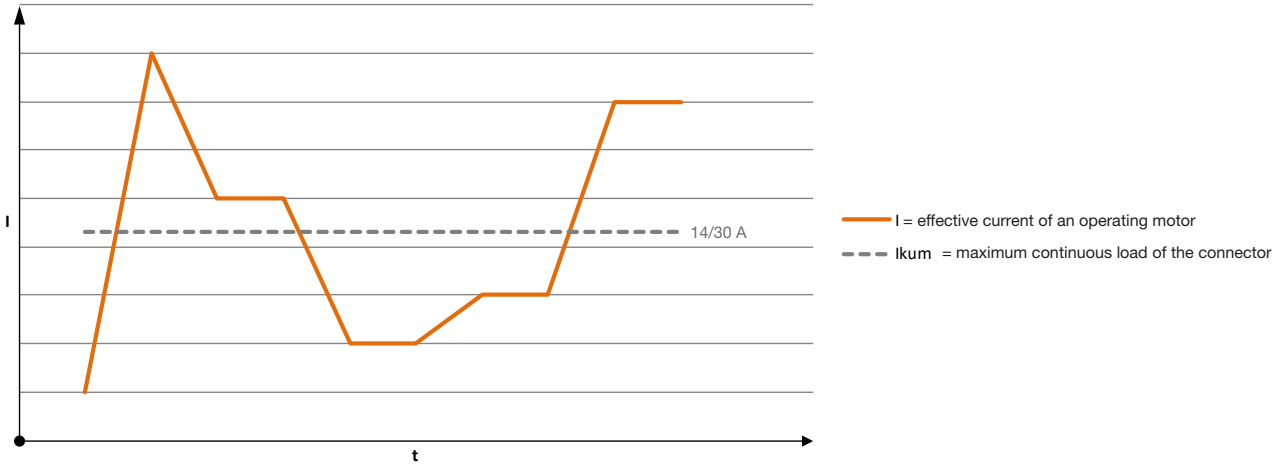
Feedback system overview

Feedback device type	HCD	HCB	HCF	HCJ
Resolver		X	X	X
HIPERFACE® encoder		X		X
HIPERFACE DSL®-encoder		X		X
Incremental encoder		X	X	X
SSI/BiSS-C	X	X	X	X
EnDat encoder		X		X
	p. 100	p. 102	p. 104	p. 106

Connection options

The different variants of the connection options can be found on the following pages (p. 76 und p. 77).

Effective current calculation for connector design



Connection technology

Motor model	M23	M40+M23	Y-Tec	I-Tec	cable outlet 1, 5 m	cable outlet 5 m	terminal box	short version[2]	long version[3]
HMD06-011-024-30	•								•
HMD06-011-048-30	•								•
HMD06-011-048-60	•								•
HMD06-011-320-30	•		•	•	o	o		•	
HMD06-011-320-60	•		•	•	o	o		•	
HMD06-011-560-30	•		•	•	o	o		•	
HMD06-011-560-60	•		•	•	o	o		•	
HMD06-019-048-30	•								•
HMD06-019-320-30	•		•	•	o	o		•	
HMD06-019-320-60	•		•	•	o	o		•	
HMD06-019-560-30	•		•	•	o	o		•	
HMD06-019-560-60	•		•	•	o	o		•	
HMD06-026-048-30	•								•
HMD06-026-048-60	•[1]								•
HMD06-026-320-30	•		•	•	o	o		•	
HMD06-026-320-60	•		•	•	o	o		•	
HMD06-026-560-30	•		•	•	o	o		•	
HMD06-026-560-60	•		•	•	o	o		•	
HMD08-024-024-30	•[1]						o		•
HMD08-024-048-30	•						o		•
HMD08-024-048-55	•[1]						o		•
HMD08-024-320-30	•		•	•	o	o		•	
HMD08-024-320-55	•		•	•	o	o		•	
HMD08-024-560-30	•		•	•	o	o		•	
HMD08-024-560-55	•		•	•	o	o		•	
HMD08-032-024-30	•[1]						o		•
HMD08-032-048-30	•						o		•
HMD08-032-048-55	•[1]						o		•
HMD08-032-320-30	•		•	•	o	o		•	
HMD08-032-320-55	•		•	•	o	o		•	
HMD08-032-560-30	•		•	•	o	o		•	
HMD08-032-560-55	•		•	•	o	o		•	
HMD08-042-024-30							o		•
HMD08-042-048-30	•[1]						o		•
HMD08-042-048-55							o		•
HMD08-042-320-30	•		•	•	o	o		•	
HMD08-042-320-55	•		•	•	o	o		•	
HMD08-042-560-30	•		•	•	o	o		•	
HMD08-042-560-55	•		•	•	o	o		•	
HMD08-057-024-30							o		•
HMD08-057-048-30							o		•
HMD08-057-048-55							o		•
HMD08-057-320-30	•		•	•	o	o		•	
HMD08-057-320-55	•		•	•	o	o		•	
HMD08-057-560-30	•		•	•	o	o		•	
HMD08-057-560-55	•		•	•	o	o		•	
Rated current (Arms)	30.0	72.0	14.0	14.0	upon request	upon request	upon request		

Motor model	M23	M40+M23	Y-Tec	I-Tec	cable outlet 1, 5 m	cable outlet 5 m	terminal box	short version[2]	long version[3]
HMD10-039-048-30	•[1]						o		•
HMD10-039-048-50							o		•
HMD10-039-320-30	•		•	•	o	o		•	
HMD10-039-320-50	•		•	•	o	o		•	
HMD10-039-560-30	•		•	•	o	o		•	
HMD10-039-560-50	•		•	•	o	o		•	
HMD10-057-048-30							o		•
HMD10-057-048-50							o		•
HMD10-057-320-30	•		•	•	o	o		•	
HMD10-057-320-50	•		•	•	o	o		•	
HMD10-057-560-30	•		•	•	o	o		•	
HMD10-057-560-50	•		•	•	o	o		•	
HMD10-076-048-30							o		•
HMD10-076-320-30	•		•	•	o	o		•	
HMD10-076-320-50	•		•	•	o	o		•	
HMD10-076-560-30	•		•	•	o	o		•	
HMD10-076-560-50	•		•	•	o	o		•	
HMD10-105-048-30							o		•
HMD10-105-320-30	•		•	•	o	o		•	
HMD10-105-320-50	•				o	o		•	
HMD10-105-560-30	•		•	•	o	o		•	
HMD10-105-560-50	•		•	•	o	o		•	
HMD13-133-560-20	•		•	•	o	o			
HMD13-133-560-36	•		•	•	o	o			
HMD13-190-560-20	•		•	•	o	o			
HMD13-190-560-36	•		•	•	o	o			
HMD13-245-560-20	•		•	•	o	o			
HMD13-245-560-36	•		•	•	o	o			
HMD15-036-560-20	•								
HMD15-036-560-30	•								
HMD15-043-560-20	•								
HMD15-043-560-30	•								
HMD15-049-560-20	•								
HMD15-049-560-30	•								
HMD19-051-560-20	•								
HMD19-051-560-30		•							
HMD19-078-560-20		•							
HMD19-078-560-30		•							
HMD19-105-560-20		•							
Rated current (Arms)	30.0	72.0	14.0	14.0	upon request	upon request	upon request		

• Available as standard
o Only upon request
Other combinations may be possible on request
[1] Rated and/or standstill current of the motor greater than the rated current of the connection technology. When using this connection method, derating of the motor must be accepted.
[2] Available for encoder category 1: Resolver, ECI1118, SEK/SEL37, HESx/HEMx, HS/M16
[3] Available for encoder category 2: Remaining encoders

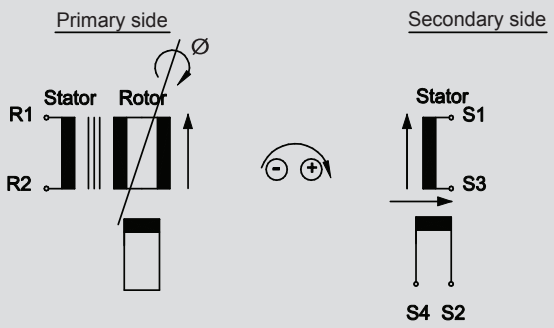
Standard Resolver

Specifications	RE-15
Number of pole pairs	1
Input frequency	10 kHz
Input voltage	7 V_{rms}
Maximum current input	50 mA
Transformation ratio	0.5 ± 10 %
Phase shift (nominal)	3 ± 3°
Ohmic resistance (at 25 °C)	
Stator winding	70 ± 10 %
Rotor winding	24 ± 10 %
Impedances	
Zro (no-load impedance rotor)	typ. 86 j 120
Zrs (short-circuit impedance rotor)	typ. 70 j 105
Zso (no-load impedance stator)	typ. 140 j 273
Zss (short-circuit impedance stator)	typ. 122 j 244
Maximum residual voltage	30 mV
Maximum electrical error	± 10'
Weight	77 g
Protection class	IP20
Insulation class	F
Insulation test housing / winding	500 V_{AC} / 50 Hz / 1 s
Moment of inertia rotor	15 g-cm²

Environmental

Working environment	IE 32 according to EN 60721-3-3
Operating temperature	- 55 °C to 155 °C
Vibration according to EN 60068-2-6	100 m/s² 10 - 150 Hz
Impact strength	400 m/s² 6 ms
Maximum operating speed	20,000 rpm

Dimensions



Safety norms

Safety Integrity Level	SIL 2 (EN 61800-5-2 / EN 62061)
Category	3 (EN ISO 13849-1)
Performance Level	PL d (EN ISO 13849-1)

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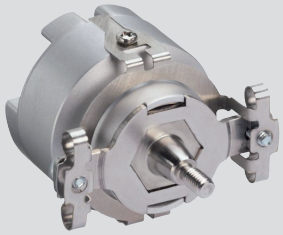
Option Incremental encoder

Optical sensing encoder

CKS36

(Incremental encoder)



Specifications:

- Resolution 2,048 pulses per revolution
- Commutation signals for 3 pole pairs
- Index pulse 90°

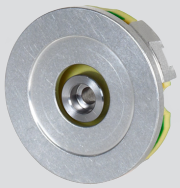
Specifications according to DIN 32878		**CKS36**
Number of lines per revolution		2,048
Commutation signals		3 pole pairs
Measurement step		90° / number of lines
Reference signal	Number Position	1 90° electrical, logically linked with A and B
Error limits	„binary“ number of lines „non-binary“ number of lines	± 0.09° ± 0.13°
Measurement step deviation	„binary“ number of lines „non-binary“ number of lines	± 0.035° ± 0.07°
Maximum output frequency	TTL/RS 422	400 kHz
Resistance	to shocks to vibration	100 g (6 ms) 50 g (10 … 2,000 Hz)
Operating voltage range		5 V ± 10 %
Maximum operating current without load		60 mA
Interface signals	Incremental and commutation signals Parameterization interface	according to EIA 422 IIC-Bus

Option absolute encoders

Inductive sensing encoder EnDat 2.2

ECI1118

(Single-turn encoder)



Specifications:

- Inductive encoder system without integral bearing
- Purely serial EnDat 2.2 interface
- For machines with high demands on dynamics and robustness
- High system accuracy
- Digital data transmission
- Electronic type plate

EnDat 2.2

EQI1131

(Multi-turn encoder)

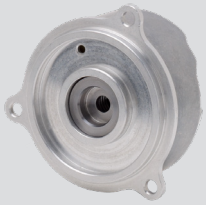
Specifications:

- Inductive encoder system without integral bearing
- Multiturn function via gearbox
- Purely serial EnDat 2.2 interface
- For machines with high demands on dynamics and robustness
- High system accuracy
- Digital data transmission
- Electronic type plate

EnDat 2.2

ECI1319 / EQI1331

(Single-/ Multi-turn encoder)



Specifications:

- Inductive encoder system without integral bearing
- Multiturn function via gearbox
- Purely serial EnDat 2.2 interface
- For machines with high demands on dynamics and robustness
- High system accuracy
- Digital data transmission
- Electronic type plate

EnDat 2.2

Specifications	ECI1118	EQI1131	ECI1319	EQI1331
Encoder type	inductive	inductive	inductive	inductive
Position values / revolution	262,144 18 bit	524,288 19 bit	524,288 19 bit	524,288 19 bit
Revolutions	-	4,096 12 bit	-	4,096 12 bit
Calculation time t_{cal}	≤ 6 µs	≤ 5 µs	≤ 5 µs	≤ 5 µs
Clock frequency	≤ 8 MHz	≤ 16 MHz	≤ 16 MHz	≤ 16 MHz
System accuracy	± 120"	± 120"	± 65"	± 65"
Maximum operating temperature	+ 115 °C - 20 °C	+ 110 °C - 40 °C	+ 115 °C - 40 °C	+ 115 °C - 40 °C
Mechanically permissible speed	15,000 rpm	12,000 rpm	15,000 rpm	12,000 rpm
Voltage supply	3.6 - 14 V_{DC}	3.6 - 14 V_{DC}	3.6 - 14 V_{DC}	3.6 - 14 V_{DC}
Max. power consumption	520 - 600 mW	700 - 850 mW	650 - 700 mW	750 - 850 mW
Currect consumption (typical) at 5 V	80 mA	115 mA	95 mA	115 mA
Multiturn	-	gearbox	-	gearbox
Vibration 55 Hz to 2,000 Hz Shock 6 ms	≤ 300 m/s² ≤ 1.000 m/s²	≤ 400 m/s² ≤ 2.000 m/s²		
Digital interface	EnDat 2.2	EnDat 2.2	EnDat 2.2	EnDat 2.2

Option absolute encoders

Capacitive sensing encoder - HIPERFACE®

SEK / SEL37

(Single-/ Multi-turn encoder)

Specifications:

- 16 sin/cos periods per revolution
- Absolute position with a resolution of 512 steps per revolution
- Measuring of 4,096 revolutions (multi-turn)
- Programming of the position value
- HIPERFACE®-interface
- Electronic type label

Optical sensing encoder - HIPERFACE®

SKS / SKM36

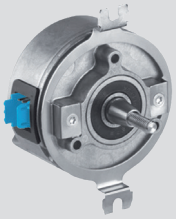
(Single-/ Multi-turn encoder)

Specifications:

- 128 sin/cos periods per revolution
- Absolute position with a revolution of 4,096 steps per revolution
- Measuring of 4,096 revolutions (multi-turn)
- Programming of the position value
- HIPERFACE®-interface
- Electronic type label

SRS / SRM50

(Single-/ Multi-turn encoder)



Specifications:

- 1,024 sin/cos periods per revolution
- Absolute position with a revolution of 32,768 steps per revolution
- Measuring of 4,096 revolutions (multi-turn)
- Programming of the position value
- HIPERFACE®-interface
- Electronic type label

Specifications	SEK/SEL37	SKS/SKM36	SRS/SRM50
Number of sin/cos periods per revolution	16	128	1.024
Maximum number of turns	Single SEK 1 Multi SEL 4,096	Single SKS 1 Multi SKM 4,096	Single SRS 1 Multi SRM 4,096
Code type for absolute value	binary	binary	binary
Code sequence [1]	ascending	ascending	ascending
Measuring step during interpolation of the sin/cos signals (for 12 bit)	20 arc seconds	2.5 arc seconds	0.3 arc seconds
Maximum sin/cos signals interpretation error, integral non-linearity	± 288 arc seconds	± 80 arc seconds	± 45 arc seconds
Non-linearity of a sin/cos period differential non-linearity	± 144 arc seconds [2]	± 40 arc seconds [2]	± 7 arc seconds [2]
Output frequency	-	0 ... 65 kHz	0 ... 200 kHz
Resistance to shocks	100 g / 10 ms	100 g / 6 ms	100 g / 10 ms
Resistance to vibration	50 g / 10...2,000 Hz	50 g / 10...2,000 Hz	50 g / 10...2,000 Hz
Operating voltage range	7...12 V	7...12 V	7...12 V
Recommended supply voltage	8 V	8 V	8 V
Maximum operating current without load	< 50 mA	60 mA	80 mA
Available memory area within EEPROM 2048 [3]	1,792 bytes	1,792 bytes	1,792 bytes
Interface signals Process data cable = SIN, REFSIN, COS, REFCOS Parameter channel = RS 485	analog, differential digital	analog, differential digital	analog, differential digital

Safety norms		SKS/SKM36S	
Safety Integrity Level [4]	-	SIL2 (EN 61800-5-2 / EN 62061)	-
Category [4]	-	3 (EN ISO 13849-1)	-
Performance Level [4]	-	PL d (EN ISO 13849-1)	-

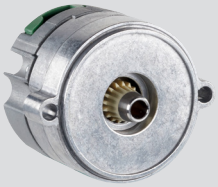
1) For rotation of the shaft in clockwise direction when facing in the direction of "A"
2) In the nominal position ± 0.1 mm
3) When using the electronic nameplate in operative connection with numerical controls, consider the patent EP 425 912 B 2; use in operative connection with speed controllers is excluded from this rule.
4) Safety norms are only valid for motors with safely mounted encoders.

Option absolute encoders

Capacitive sensing encoder - HIPERFACE DSL®

EES / EEM37

(Single- or multi-turn encoder)



Specifications:

- Absolute position with a resolution of 131,072 steps per revolution
- Measuring of 4,096 revolutions (multi-turn)
- Programming of the position value
- HIPERFACE DSL®-interface
- Electronic type label

Optical sensing encoder - HIPERFACE DSL®

EKS / EKM36

(Single- or multi-turn encoder)

Specifications:

- Absolute position with a resolution of 262,144 steps per revolution
- Measuring of 4,096 revolutions (multi-turn)
- Programming of the position value
- HIPERFACE DSL®-interface
- Electronic type label

EFS / EFM50

(Single- or multi-turn encoder)

Specifications:

- Absolute position with a resolution of 8,388,608 steps per revolution
- Measuring of 4,096 revolutions (multi-turn)
- Programming of the position value
- HIPERFACE DSL®-interface
- Electronic type label

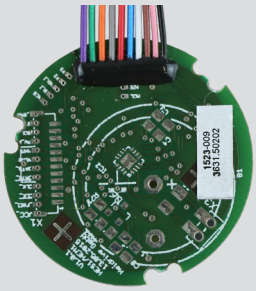
Specifications	EES/EEM37	EKS/EKM36	EFS/EFM50
Number of sin/cos periods per revolution	-	-	-
Maximum number of turns	Single EES1 Multi EEM 4.096	Single EKS 1 Multi EKM 4.096	Single EFS 1 Multi EFM 4.096
Code type for absolute value	binary	binary	binary
Code sequence [1]	ascending	ascending	ascending
Measuring step during interpolation of the sin/cos signals (for 12 bit)	-	-	-
Maximum sin/cos signals interpretation error, integral non-linearity	± 160 arc seconds [2]	± 80 arc seconds	± 45 arc seconds
Non-linearity of a sin/cos period differential non-linearity	-	± 40 arc seconds	± 7 arc seconds
Output frequency	-	0 ... 75 kHz (digital position value)	0 ... 75 kHz (digital position value)
Resistance to shocks	100 g / 6 ms	100 g / 6 ms	100 g / 6 ms
Resistance to vibration	50 g / 10...2,000 Hz	50 g / 10...2,000 Hz	30 g / 10...2,000 Hz
Operating voltage range	7...12 V	7...12 V	7...12 V
Recommended supply voltage	-	8 V	9 V
Maximum operating current without load	150 mA	150 mA	150 mA
Available memory area within EEPROM 2048 [3]	8,192 bytes	8,192 bytes	8,192 bytes
Interface signals Process data cable = SIN, REFSIN, COS, REFCOS Parameter channel = RS 485	differential, digital	differential, digital	differential, digital

Safety norms		EKS/EKM36-2	
Safety Integrity Level [4]	-	SIL2 (EN 61800-5-2 / EN 62061)	-
Category [4]	-	3 (EN ISO 13849-1)	-
Performance Level [4]	-	PL d (EN ISO 13849-1)	-

1) For rotation of the shaft in clockwise direction when facing in the direction of "A"
2) System accuracy
3) When using the electronic nameplate in operative connection with numerical controls, consider the patent EP 425 912 B 2; use in operative connection with speed controllers is excluded from this rule.
4) Safety norms are only valid for motors with safely mounted encoders.

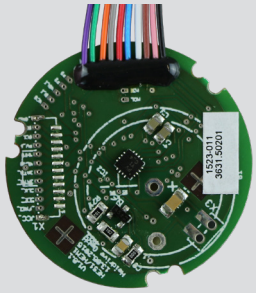
Option hall encoders

HES1-002



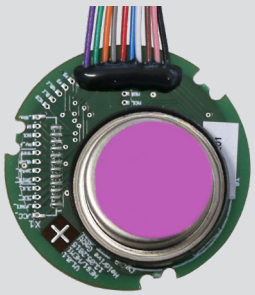
Specifications:
- Single-turn encoder with a resolution of 12 bit (interpolated 14 bit)
- SSI interface differential and single-ended
- Differential sin/cos signals with 1.0 V_{p-p}

HEM1-001



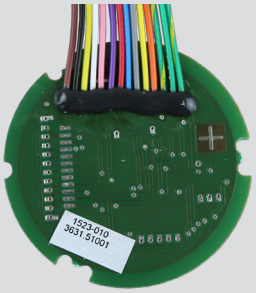
Specifications:
- Multi-turn encoder with a resolution of 32 bit (≈ 4.2 billion revolutions measurable)
- Single-turn encoder with a resolution of 12 bit (interpolated 14 bit)
- SSI interface differential and single-ended
- Differential sin/cos signals with 1.0 V_{p-p}
- External battery connector

HEM1-002*



Specifications:
- Multi-turn encoder with a resolution of up to 32 bit (≈ 4.2 billion revolutions measurable)
- Single-turn encoder with a resolution of 12 bit (interpolated 14 bit)
- BiSS interface differential and single-ended
- Differential sin/cos signals with 1.0 V_{p-p}
- Battery on board

HES3



Specifications:
- Single-turn encoder with a resolution of 10 bit (interpolated 12 bit)
- Commutation and incremental signals ABZ, differential and single-ended
- Commutation signals for 2/4/6 or 8-pole motors

*Further information for your application upon request

Specifications (according to DIN 32878)	**HES1-002**	**HEM1-001**	**HEM1-002**	**HES3**
Diameter (mm)	34.95 ± 0.05	34.95 ± 0.05	34.95 ± 0.05	34.95 ± 0.05
Power supply voltage	5.0 V_{DC} ± 10%	5.0 V_{DC} ± 10%	5.0 V_{DC} ± 10%	5.0 V_{DC} ± 10%
Maximum output current	50 mA	50 mA	50 mA	50 mA
Maximum resolution single-turn	12 bit 0.088°	12 bit 0.088°	12 bit 0.088°	10 bit 0.35
Maximum resolution single-turn interpolated	14 bit 0.022°	14 bit 0.022°	14 bit 0.022°	12 bit 0.088°
Maximum number of turns	-	32 bit ≈ 4.2 billion	32 bit ≈ 4.2 billion	-
Backup battery for multi-turn encoder	-	external	on board	-
SSI interface	differential & single ended	differential & single ended	differential & single ended	-
Maximum SSI operating frequency	4 MHz	4 MHz	4 MHz	-
Sin/cos signals	differential	differential	differential	-
Number of sin/cos periods per turn	1	1	1	-
Amplitude sin/cos	1.0 V_{p-p}	1.0 V_{p-p}	1.0 V_{p-p}	-
Incremental signals ABZ	-	-	-	differential
High-level output voltage ABZ	-	-	-	min. 3.8 V
Low-level output voltage ABZ	-	-	-	max. 0.7 V
Commutation signals	-	-	-	differential
Commutation high-level output voltage (UVW)	-	-	-	min. 3.8 V
Commutation low-level output voltage (UVW)	-	-	-	max. 0.7 V
ESD voltage	2 kV	2 kV	2 kV	2 kV
Order code segment	XXM2SXXXX	XXM1MXXXX	XXM2MXXXX	XXM1IXXXX
Permissible operating temperature range	- 30 °C to + 105 °C			
Permissible storage temperature	- 30 °C to + 125 °C			
Permissible relative humidity	15 to 85 % without condensation			

HS/M 16 Encoder

Features:

- Integrated, compact dual encoder in the standard HeiMotion modular system
- Singleturn with SSI and Sin/Cos
- Multiturn with BiSS-C
- Speeds up to 12000 min-1
- Temperature evaluation via BiSS-C possible
- Electronic nameplate possible on request

Specifications	HS 16 (Singleturn)	HM 16 (Multiturn)
Supply voltage	5.0 V_{DC} +10/-5%	5.0 V_{DC} +10/-5%
Power consumption	0.6 W	0.6 W
Max. resolution singleturn	16 Bit [2)]	16 Bit [2)]
Max. number of absolute revolutions detected	-	12 Bit (mechanisch)
Data interface	SSI gray + SinCos 1Vpp	BiSS-C + SinCos 1Vpp
Sin/Cos tracks	differential	differential
Number of sin/cos periods per revolution	256 (8 Bit)	256 (8 Bit)
Max. angular acceleration	100,000 rad/sec^2	100,000 rad/sec^2
Resistance to shocks (DIN EN 60068-2-27)	3000 m/s^2 (6ms)	3000 m/s^2 (6ms)
Resistance to vibration (DIN EN 60068-2-6)	300 m/s^2	300 m/s^2
Order code	XXS1SXXXX	XXB1MXXXX

Option holding brake

Any HeiMotion Dynamic motor can be equipped with a permanent-magnet DC holding brake.
The standard motors are not suiteable for dynamic brakes.

Insulation class:	F (155 °C)
Maximum speed:	10,000 rpm
Voltage supply:	24 V_{DC} + 6 % / -10 %

Specifications brake	HMD06			HMD08			
	-011	-019	-026	-024	-032	-042	-057
Moment of inertia motor with brake * [kg-cm²]	3.47E-01	5.73E-01	8.00E-01	1.04E+00	1.37E+00	1.71E+00	2.36E+00
Static braking torque min. at 20°C [Nm]	2.0	2.0	2.0	4.5	4.5	4.5	4.5
Dynamic braking torque at 20°C [Nm]	1.7	1.7	1.7	3.8	3.8	3.8	3.8
Rated input power at rated voltage and 20°C [W]	11	11	11	12	12	12	12
Working voltage [V_{DC}]	24	24	24	24	24	24	24
Input current brake at 20°C [A]	0.46	0.46	0.46	0.50	0.50	0.50	0.50
Energy rating [kJ]	410	410	410	580	580	580	580
Separating time brake [ms]	≤40	≤40	≤40	≤ 38	≤ 38	≤38	≤38
Brake delay [ms]	≤3	≤3	≤3	≤3	≤3	≤3	≤3
Application delay time [ms]	≤15	≤15	≤15	≤20	≤20	≤20	≤20
Weight of motor with brake * [kg]	1.55	1.95	2.35	3.15	3.55	3.95	5.05
Slipping time ** [s]	0,5	0.5	0.5	0.5	0.5	0.5	0.5
Idle time ** [s]	0,5	0.5	0.5	0.5	0.5	0.5	0.5
Speed ** [min^{-1}]	100	100	100	100	100	100	100
Cycle quantity ** [-]	5	5	5	5	5	5	5

Specifications brake	HMD10				HMD13		
	-039	-057	-076	-105	-133	-190	-245
Moment of inertia motor with brake * [kg-cm²]	2.62E+00	3.43E+00	4.25E+00	5.89E+00	1.01E+01	1.39E+01	2.32E+01
Static braking torque min. at 20°C [Nm]	9.0	9.0	9.0	9.0	20.0	20.0	36.0
Dynamic braking torque min. at 20°C [Nm]	7.5	7.5	7.5	7.5	15.0	15.0	30.0
Rated input power at rated voltage and 20°C [W]	18	18	18	18	28	28	26
Working voltage [V_{DC}]	24	24	24	24	24	24	24
Input current brake at 20°C [A]	0.75	0.75	0.75	0.75	1.17	1.17	1.08
Energy rating [kJ]	890	890	890	890	1,290	1,290	2,900
Separating time brake [ms]	≤70	≤70	≤70	≤70	≤90	≤90	≤135
Brake delay [ms]	≤3	≤3	≤3	≤3	≤3	≤3	≤7
Application delay time [ms]	≤30	≤30	≤30	≤30	≤35	≤35	≤35
Weight of motor with brake * [kg]	5.50	6.00	6.50	7.50	9.50	12.10	16.50
Slipping time ** [s]	0.5	0.5	0.5	0.5	0.5	0.5	0.5
Idle time ** [s]	0.5	0.5	0.5	0.5	0.5	0.5	0.5
Speed ** [min^{-1}]	100	100	100	100	75	75	50
Cycle quantity ** [-]	5	5	5	5	5	5	3

Specifications brake	HMD15			HMD19		
	-036	-043	-049	-051	-078	-105
Moment of inertia motor with brake * [kg-cm²]	4.69E+01	5.63E+01	7.01E+01	8.23E+01	1.60E+02	1.95E+02
Static braking torque min. at 20°C [Nm]	45.0	45.0	65.0	65.0	115.0	115.0
Dynamic braking torque at 20°C [Nm]	24.0	24.0	35.0	35.0	70.0	70.0
Rated input power at rated voltge and 20°C [W]	21	21	28	40	50	50
Working voltage [V_{DC}]	24	24	24	24	24	24
Input current brake at 20°C [A]	0.853	0.853	1.16	1.67	2.08	2.08
Energy rating [kJ]	2,600	2,600	4,500	4,500	13,000	13,000
Separating time brake [ms]	≤200	≤200	≤200	≤200	≤190	190
Brake delay [ms]	6	6	10	10	12	12
Application delay time [ms]	≤50	≤50	≤50	≤50	65	65
Weight of motor with brake * [kg]	22.0	26.0	31.5	40.0	51.5	61.5
Slipping time ** [s]	0.5	0.5	0.5	0.5	0.5	0.5
Idle time ** [s]	0.5	0.5	0.5	0.5	0.5	0.5
Speed ** [min^{-1}]	50	50	25	25	15	15
Cycle quantity ** [-]	3	3	3	3	3	3

* Incl. all attachment parts

** In order to ensure the optimum function of the brake at all times, it is recommended that the respective maintenance cycle (refreshment) be carried out when the brake is first put into operation and at four-week intervals.

Option connector Y-Tec

Power

Pin	Function
A	U
B	V
C	W
Ground.	PE
1	Therm. Prot. + 2)
2	Therm. Prot. - 2)
3	Brake + 1)
4	Brake - 1)
5	-

1) If applicable
2) Only with CKS 36, HES3 and HEM1-001

Signal Resolver

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin- / refsin
5	R1 (ref +)
6	R2 (ref -)
7	-
8	-
9	Therm. Prot. + / Temp +
10	Therm. Prot. - / Temp -
11	-
12	-

Signal HIPERFACE®

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin- / refsin
5	Data +
6	Data -
7	Us
8	GND
9	Therm. Prot. + / Temp +
10	Therm. Prot. - / Temp -
11	-
12	-

Signal SSI/BiSS

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin- / refsin
5	V_{CC} / 5 V
6	GND
7	Data +
8	Data -
9	CLK +
10	CLK -
11	Therm. Prot. + / Temp + 3)
12	Therm. Prot. - / Temp - 4)

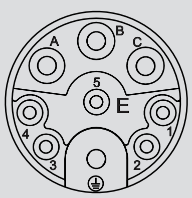
3) Battery + at HEM1-001
4) Battery - at HEM1-001

Signal EnDat 2.2

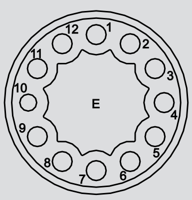
Pin	Function
1	-
2	-
3	-
4	-
5	U_p
6	GND / 0 V
7	Data +
8	Data -
9	CLK +
10	CLK -
11	Therm. Prot. +
12	Therm. Prot. -

Motor connector

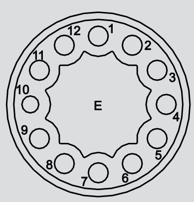
View mating face



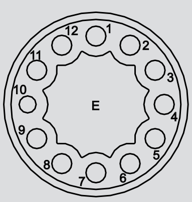
9-pole
9 x Ø 1 mm (3+PE+5)



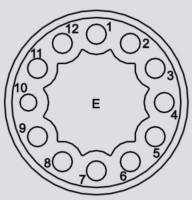
12-pole
12 x Ø 1 mm



12-pole
12 x Ø 1 mm



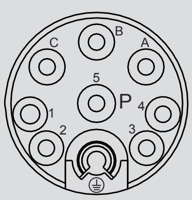
12-pole
12 x Ø 1 mm



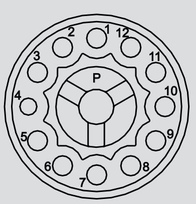
12-pole
12 x Ø 1 mm

Mating connector

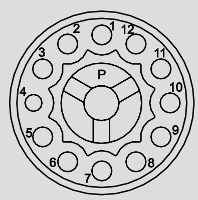
View mating face



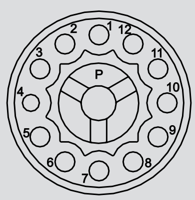
Intercontec type designation
ESTA 202 NN00 34 0500 000
(Cable clamping range
10.5 - 12 mm)



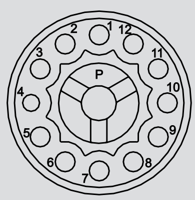
Intercontec type designation
ESTA 002 NN00 33 0001 000
(Cable clamping range
8.5 - 10.5 mm)



Intercontec type designation
ESTA 002 NN00 33 0001 000
(Cable clamping range
8.5 - 10.5 mm)



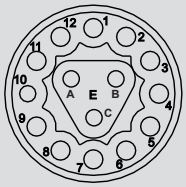
Intercontec type designation
ESTA 002 NN00 33 0001 000
(Cable clamping range
8.5 - 10.5 mm)



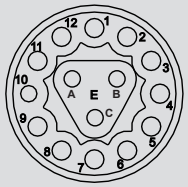
Intercontec type designation
ESTA 002 NN00 33 0001 000
(Cable clamping range
8.5 - 10.5 mm)

Signal Incremental

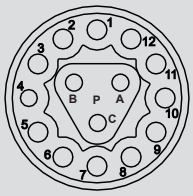
Pin	Function
1	Z
2	$\overline{Z}$
3	A
4	$\overline{A}$
5	B
6	$\overline{B}$
7	$\overline{U}$ ($\overline{R}$)
8	U (R)
9	$\overline{V}$ ($\overline{S}$)
10	V (S)
11	$\overline{W}$ ($\overline{T}$)
12	W (T)
A	V_{CC} / 5 V
B	GND
C	-



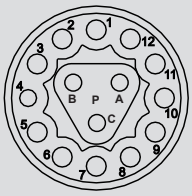
15-pole
15 x Ø 1 mm



15-pole
15 x Ø 1 mm



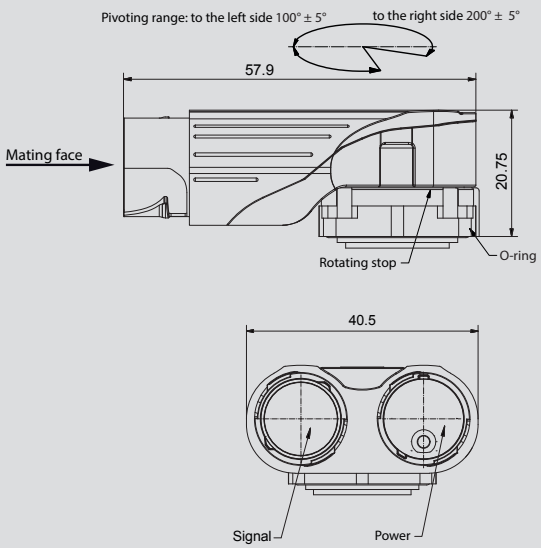
Intercontec type designation
ESTA 205 NN00 33 0001 000
(Cable clamping range
8.5 - 10.5 mm)



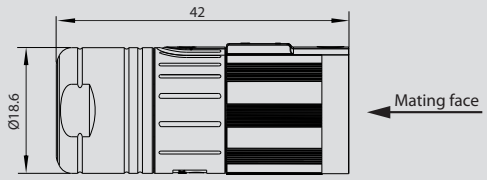
Intercontec type designation
ESTA 205 NN00 33 0001 000
(Cable clamping range
8.5 - 10.5 mm)

Mating connector with metal gland
as shown or with plastic gland.

Motor connector Angled receptacle Y-Tec, rotatable



Mating connector



Option connector M23

Power

Pin	Function
A	Brake + [1)]
B	Brake - [1)]
C	Therm. Prot. +
D	Therm. Prot. -
1	U
4	V
3	W
Ground.	PE

1) If applicable
2) Battery + at HEM1-001
3) Battery - at HEM1-001

Signal Resolver

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin - / refsin
5	-
6	R1 (ref +)
7	R2 (ref -)
8	-
9	-
10	-
11	Therm. Prot. + / Temp +
12	Therm. Prot. - / Temp -

Signal HIPERFACE®

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin - / refsin
5	-
6	-
7	GND
8	-
9	US
10	Data +
11	Data -
12	-
13	-
14	Therm. Prot. + / Temp +
15	Therm. Prot. - / Temp -
16	-
17	-

Signal SSI/BiSS

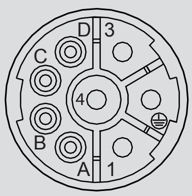
Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin - / refsin
5	V_{CC} / 5 V
6	GND
7	Data +
8	Data -
9	CLK +
10	CLK -
11	Therm. Prot. + / Temp +
12	Therm. Prot. - / Temp -
13	- [2)]
14	- [3)]
15	-
16	-
17	-

Signal EnDat 2.2

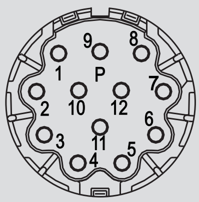
Pin	Function
1	-
2	-
3	-
4	-
5	U_P
6	GND/0V
7	Data +
8	Data -
9	Clock +
10	Clock -
11	Therm. Prot. +
12	Therm. Prot. -
13	-
14	-
15	-
16	-
17	-

Motor connector

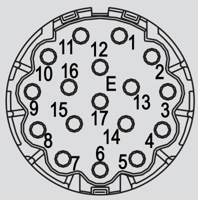
View mating face



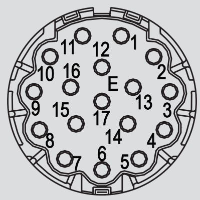
8-pole
4 x Ø 2 mm (3+PE)
+ 4 x Ø 1 mm



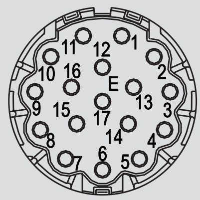
12-pole
12 x Ø 1 mm, 0° coded



17-pole
17 x Ø 1 mm, 0° coded



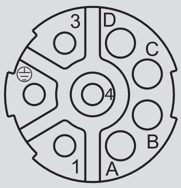
17-pole
17 x Ø 1 mm, 0° coded



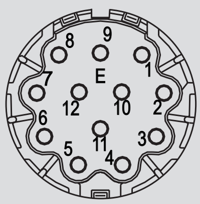
17-pole
17 x Ø 1 mm, 0° coded

Mating connector

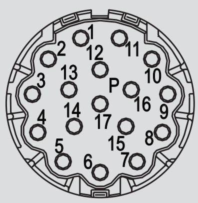
View mating face



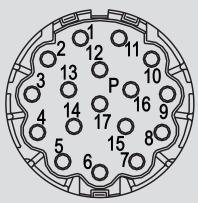
Intercontec type designation
BSTA 078 NN00 42 0100 000
(Cable clamping range
9.5-14.5 mm)



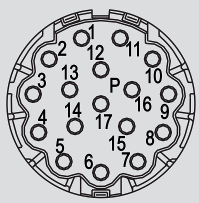
Intercontec type designation
ASTA 013 NN00 41 0100 000
(Cable clamping range
6-10 mm)



Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)



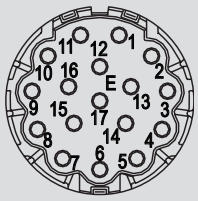
Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)



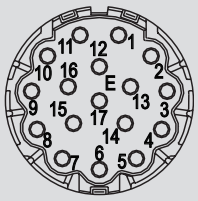
Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)

Signal Incremental

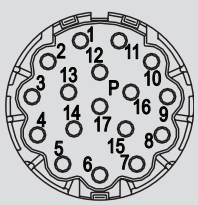
Pin	Function
1	Z
2	$\overline{Z}$
3	A
4	$\overline{A}$
5	B
6	$\overline{B}$
7	U (R)
8	$\overline{U}$ ($\overline{R}$)
9	V (S)
10	$\overline{V}$ ($\overline{S}$)
11	W (T)
12	$\overline{W}$ ($\overline{T}$)
13	V_{CC} / 5 V
14	GND
15	Therm. Prot. +
16	Therm. Prot. -
17	-



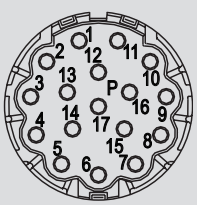
17-pole
17 x Ø 1 mm, 0° coded



17-pole
17 x Ø 1 mm, 0° coded

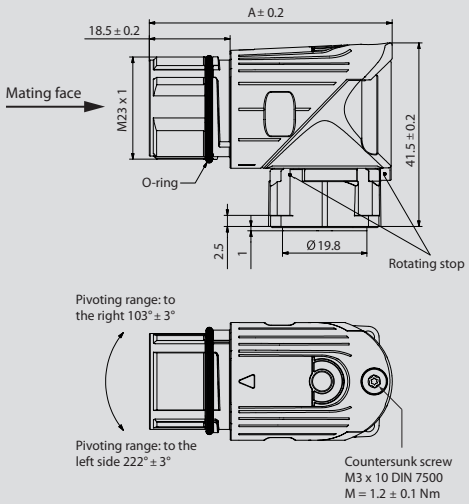


Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)

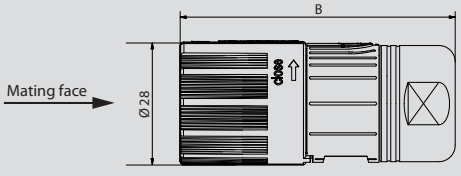


Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)

Motor connector



Mating connector



Connector type	A	B
Signal	55.6	59
Power	55.3	78

Option connector M40 + M23

Power

Pin	Function
+	Brake + *
-	Brake - *
1	Therm. Prot. +
2	Therm. Prot. -
U	U
V	V
W	W
Ground.	PE

* If applicable

Signal Resolver

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin - / refsin
5	-
6	R1 (ref +)
7	R2 (ref -)
8	-
9	-
10	-
11	Therm. Prot. + / Temp +
12	Therm. Prot. - / Temp -

Signal HIPERFACE®

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin - / refsin
5	-
6	-
7	GND
8	-
9	US
10	Data +
11	Data -
12	-
13	-
14	Therm. Prot. + / Temp +
15	Therm. Prot. - / Temp -
16	-
17	-

Signal SSI/BiSS

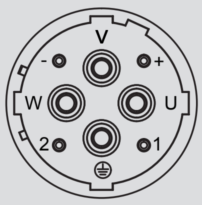
Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin - / refsin
5	V_{CC} / 5 V
6	GND
7	Data +
8	Data -
9	CLK +
10	CLK -
11	Therm. Prot. + / Temp +
12	Therm. Prot. - / Temp -
13	-
14	-
15	-
16	-
17	-

Signal EnDat 2.2

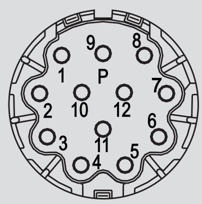
Pin	Function
1	-
2	-
3	-
4	-
5	U_p
6	GND / 0 V
7	Data +
8	Data -
9	CLK +
10	CLK -
11	Therm. Prot. +
12	Therm. Prot. -
13	-
14	-
15	-
16	-
17	-

Motor connector

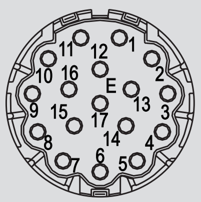
View mating face



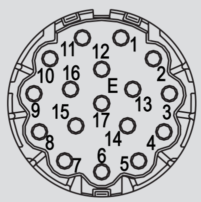
8-pole
4 x Ø 3.6 mm (3+PE)
+ 4 x Ø 2 mm



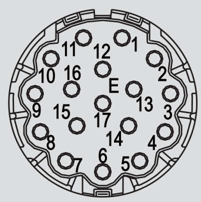
12-pole
12 x Ø 1 mm, 0° coded



17-pole
17 x Ø 1 mm, 0° coded



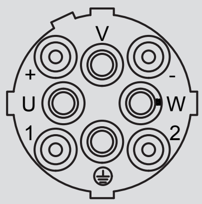
17-pole
17 x Ø 1 mm, 0° coded



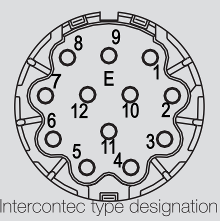
17-pole
17 x Ø 1 mm, 0° coded

Mating connector

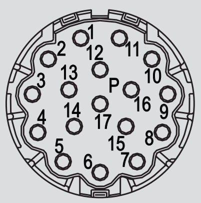
View mating face



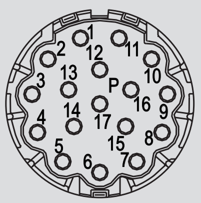
Intercontec type designation
CSTA 264 NN00 4400 20000
(Cable clamping range
9-16 mm)



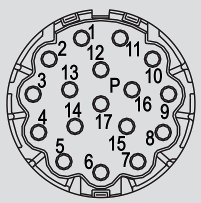
Intercontec type designation
ASTA 013 NN00 41 0100 000
(Cable clamping range
6-10 mm)



Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)



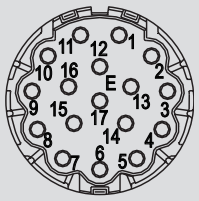
Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)



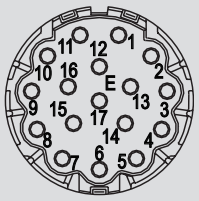
Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)

Signal Incremental

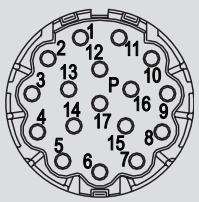
Pin	Function
1	Z
2	$\overline{Z}$
3	A
4	$\overline{A}$
5	B
6	$\overline{B}$
7	U (R)
8	$\overline{U}$ ($\overline{R}$)
9	V (S)
10	$\overline{V}$ ($\overline{S}$)
11	W (T)
12	$\overline{W}$ ($\overline{T}$)
13	V_{CC} / 5 V
14	GND
15	Therm. Prot. +
16	Therm. Prot. -
17	-



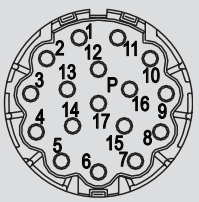
17-pole
17 x Ø 1 mm, 0° coded



17-pole
17 x Ø 1 mm, 0° coded

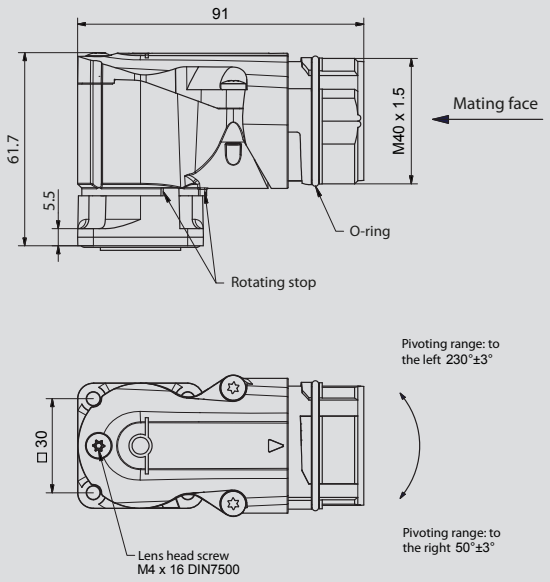


Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)



Intercontec type designation
ASTA 014 NN00 41 0100 000
(Cable clamping range
6-10 mm)

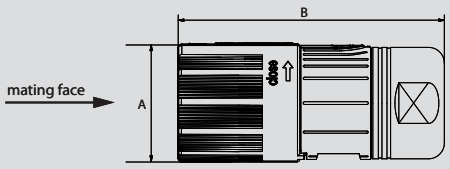
Power connector M40



Signal connector M23

See connector dimensions M23 on page 55.

Mating connector



Connector type	A	B
Signal	Ø 28	59
Power	Ø 46	99

Terminal Box

Signal DSL

Pin	Function
1	-
2	-
3	-
4	-
5	-
6	-
7	-
8	US (DSL +)
9	GND (DSL -)
10	-
11	-
12	Brake +
13	-
14	-
15	-
16	-
17	-
18	-
19	Brake -

Signal Resolver

Pin	Function
1	cos +
2	cos -
3	sin +
4	sin -
5	Ref+
6	-
7	Ref-
8	-
9	-
10	-
11	-
12	Brake +
13	
14	
15	
16	
17	Therm. Prot. + / Temp +
18	Therm. Prot. - / Temp -
19	Brake -

Signal HIPERFACE®

Pin	Function
1	cos +
2	cos -
3	sin +
4	sin -
5	-
6	-
7	GND
8	-
9	US
10	Data +
11	Data -
12	Brake+
13	-
14	-
15	-
16	-
17	Therm. Prot. + / Temp +
18	Therm. Prot. - / Temp -
19	Brake -

Signal SSI/BiSS

Pin	Function
1	cos +
2	cos - / refcos
3	sin +
4	sin - / refsin
5	Battery+[1)]
6	-
7	Battery-[1)]
8	Data +
9	Data -
10	CLK+
11	CLK-
12	Brake +
13	-
14	-
15	Vcc/5V
16	GND
17	Therm. Prot. + / Temp +
18	Therm. Prot. - / Temp -
19	Brake -

Signal EnDat 2.2

Pin	Function
1	-
2	-
3	-
4	-
5	-
6	-
7	-
8	Data +
9	Data -
10	CLK +
11	CLK -
12	Brake +
13	-
14	-
15	Up
16	GND
17	Therm. Prot. + / Temp +
18	Therm. Prot. - / Temp -
19	Brake -

[1)] Battery +/- for HEM1-001

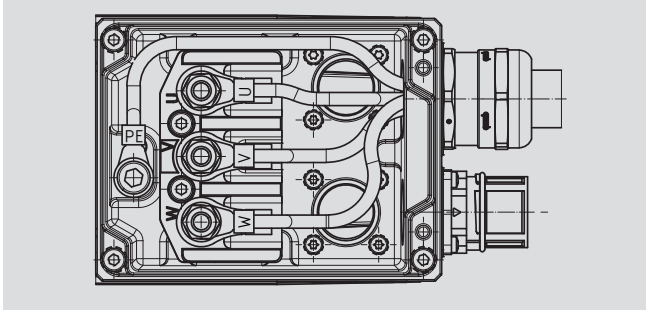
Power

According to power connection terminal board (see picture below).
Possible cable to be used: Helucable TOPSERV 109 PUR 4 G 10 Art. No.: 75947
VDE 0298-4 must be considered when selecting cables

Ring Tongue:
6,73 x 22,05
E-CU-galv. tinned
6,64 – 10,5 mm²

Bolt:
M6 x 25 brass according to DIN 933 / ISO 4017

Power connection terminal board



Oder code	Explanation
KA0	Connections in A-side direction without cable gland
KA2	Connections in A-side direction, with cable gland
KB0	Connections in B-side direction, without cable cover
KB2	Connections in B-side direction with cable gland

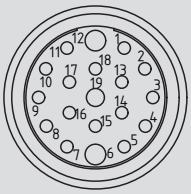
For UL approval, an S1 characteristic curve deviating by approx. 15 % applies. The specifications on the nameplates correspond to the UL values

Signal Incremental

Pin	Function
1	Z
2	$\bar{Z}$
3	A
4	$\bar{A}$
5	B
6	-
7	$\bar{B}$
8	U (R)
9	-
10	V (S)
11	-
12	Brake +
13	W (T)
14	-
15	Vcc/5c
16	GND -
17	Therm. Prot. + / Temp +
18	Therm. Prot. - / Temp -
19	Brake -

Motor Connector

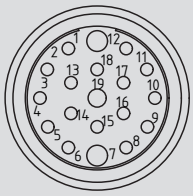
View mating face



19-pole P
(16 x Ø 1 mm +
3 x Ø 1.5 mm)

Mating Connector

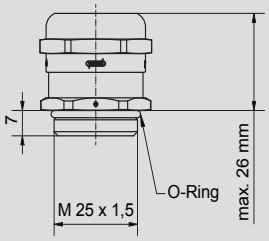
View mating face



Intercontec type designation
ASTA 558 NN 00 41 0100 000
(Cable clamping range
6-10 mm)

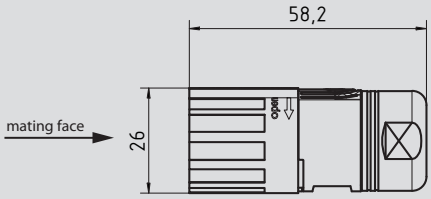
Cable Gland

Clamping range 13-18mm

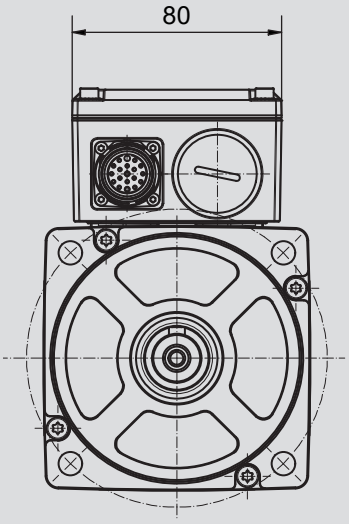


For order codes KA2 and KB2 cable gland can be ordered optionally.

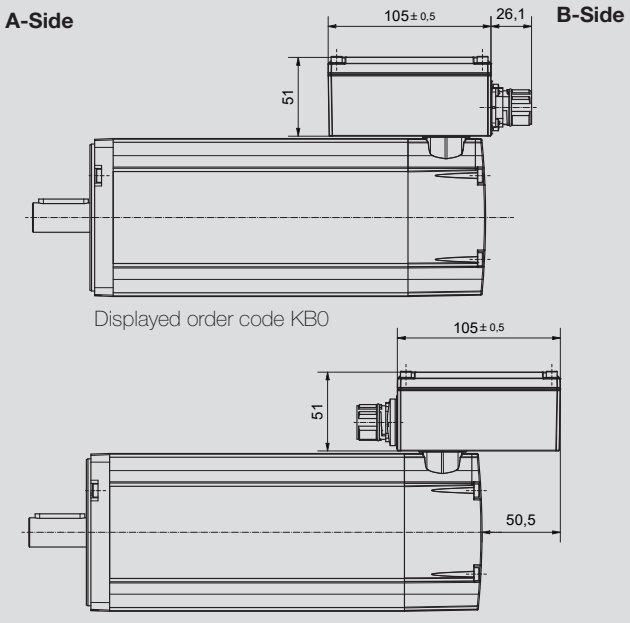
Mating connector



Front View

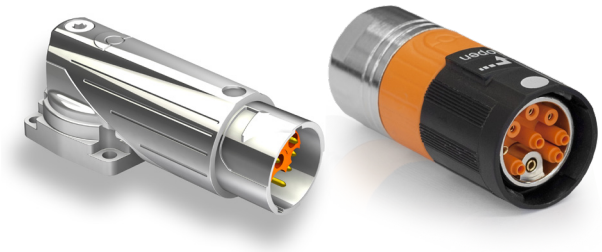


Mounting Direction



Option connectors for one cable solution

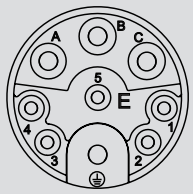
I-Tec connector



Power / Signal

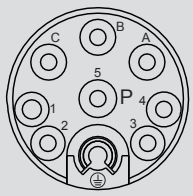
Pin	Function
A	U
B	V
C	W
Grounding	PE
1	U_S (DSL +)
2	GND (DSL -)
3	Brake + *
4	Brake - *
5	-

Motor connector



9-pole
9 x Ø 1 mm (3+PE+5)

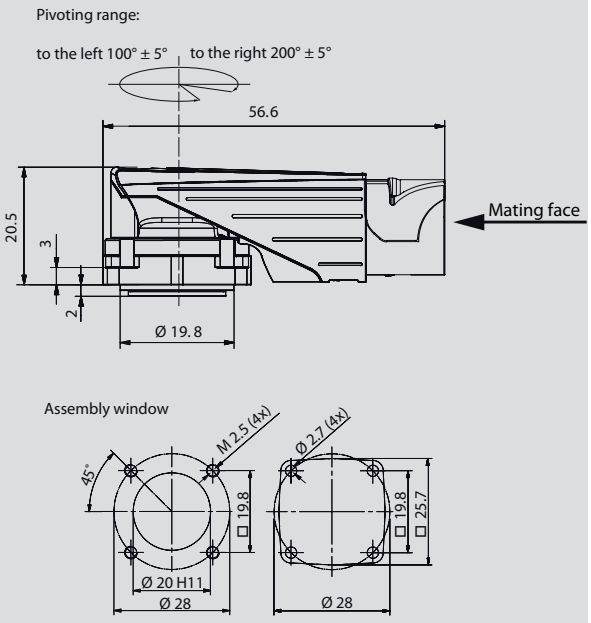
Mating connector



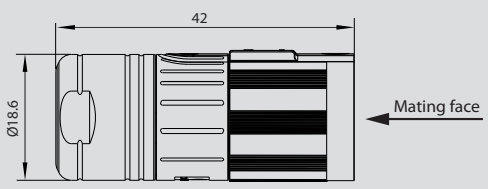
Intercontec type designation
ESTA 202 NN00 34 0500 000
(Cable clamping range 10.5 - 12 mm)

* If available

Motor connector



Mating connector

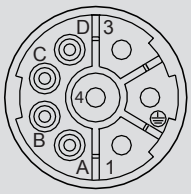


M23 connector

Power / Signal

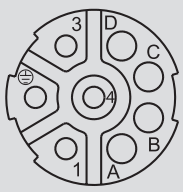
Pin	Function
A	Brake + *
B	Brake - *
C	U_s (DSL+)
D	GND (DSL-)
1	U
4	V
3	W
Grounding	PE

Motor connector



8-pole
4 x Ø 2mm (3+PE) + 4 x Ø 1mm

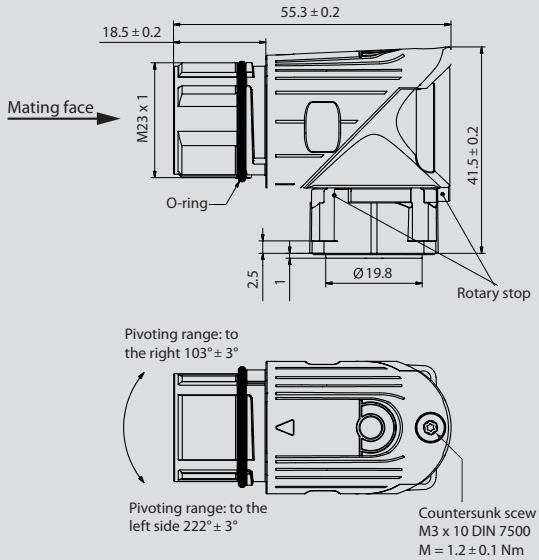
Mating connector



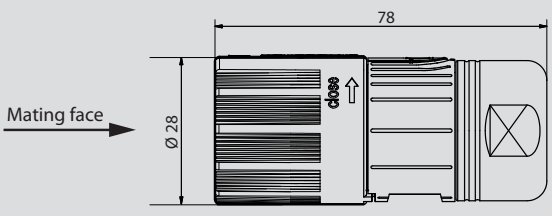
Intercontec type designation
BSTA 078 NN00 42 0100 000
(Cable clamping range 9.5 - 14.5 mm)

* If available

Motor connector



Mating connector



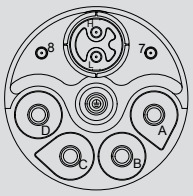
Option connectors for one cable solution

M23 H-Tec (hybrid) connector

Power / Signal

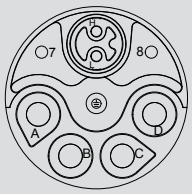
Pin	Function
A	U
B	V
C	W
D	-
Grounding	PE
7	Brake + *
8	Brake - *
H	U_S (DSL +)
L	GND (DSL -)

Motor connector



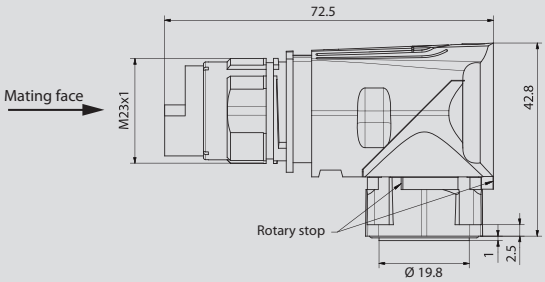
7-pole
5 x Ø 2 mm (4+PE)
+ 2 x Ø 1 mm

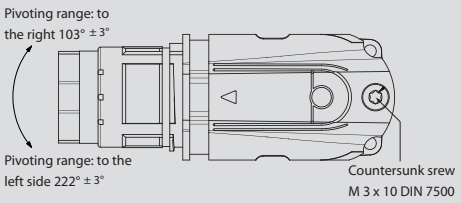
Mating connector



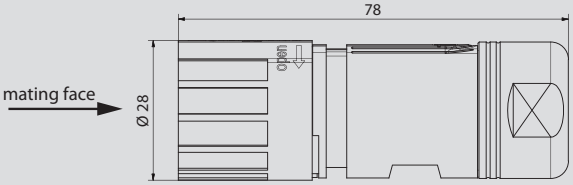
Intercontec type designation
H51A 425 NN00 59 0100 000
(Cable clamping range 14 - 17 mm)

Motor connector



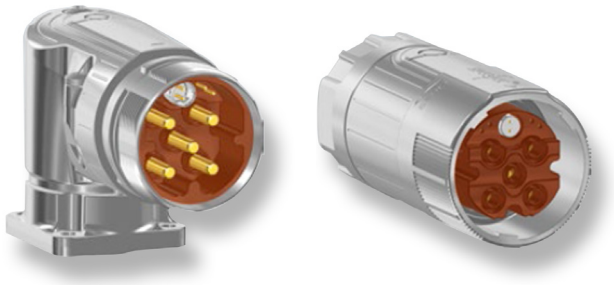


Mating connector



* If available

M40 H-Tec (hybrid) connector



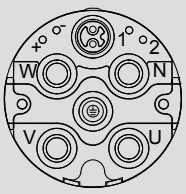
Power / Signal

Pin	Function
U	U
V	V
W	W
Grounding	PE
+	Brake + *
-	Brake - *
1	-
2	-
H	U_S (DSL +)
L	GND (DSL -)

Motor connector

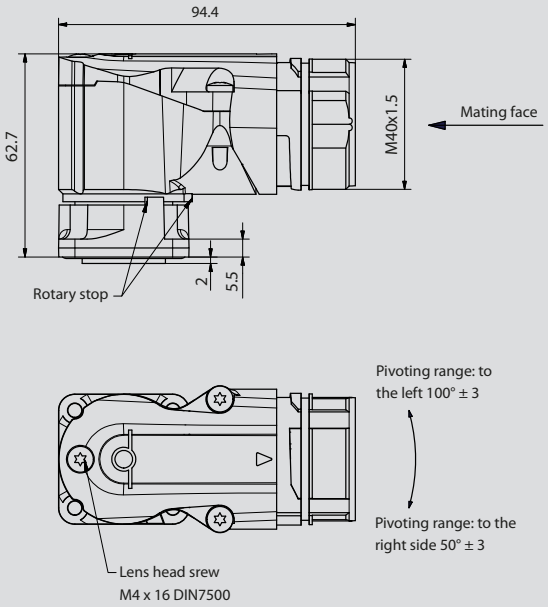
9-pole
5 x Ø 3,6 mm (4+PE)
+ 2 x Ø 1mm

Mating connector

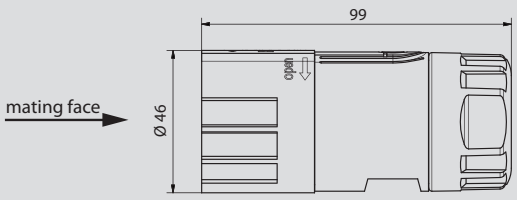


Intercontec type designation
H81A 501 NN00 45 0100 000
(Cable clamping range 16.5 - 25 mm)

Motor connector



Mating connector



* If available

HCD servo drive, 230 V_{AC}

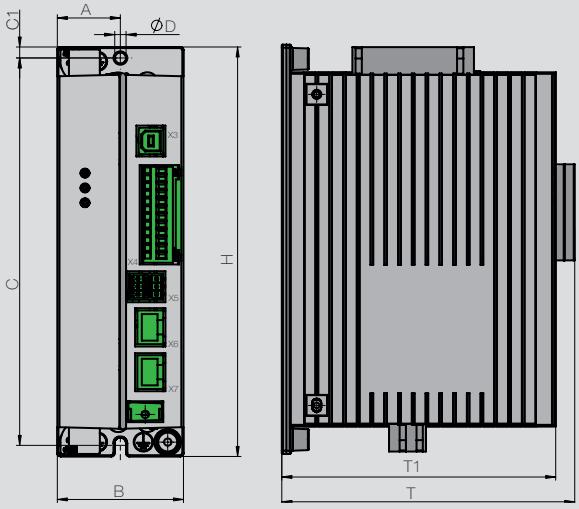
Specifications servo drive

Type	Supply voltage	DC bus voltage	Output Voltage	Continuous output current	Maximum output current	Rated power	Order Code
	[V_{AC}]	[V]	[V_{rms}]	[A_{rms}]	[A_{rms}]	[W]	
HCD	1 x 230	320	3 x 0 - 230	4	8	800	HCD2-004-0011-00

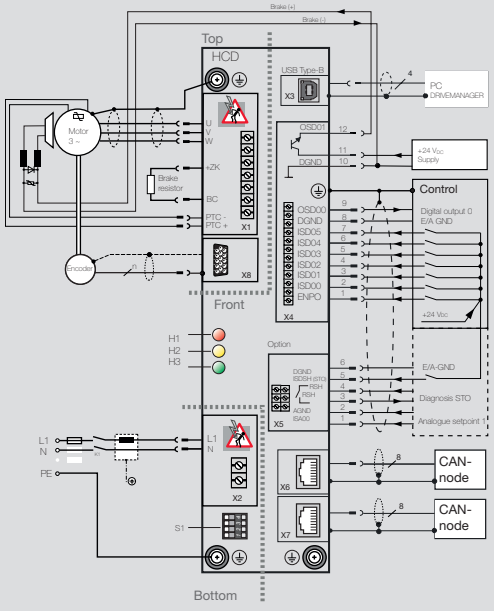
Switch frequency [kHz]: 4, 8, 12, 16 (Factory setting 8 kHz)
Power rating [kVA]: 1.84
Cable cross-section [mm²]: 0.2...1.5
Mains frequency [Hz]: 50 / 60 ± 10 %

The small 4-Q-servo-drive HCD has been specially developed for cost-sensitive and simple control tasks, such as speed-, torque-, and position-controlled applications. Its drive control uses digital and analogue inputs, PLC Motion or fieldbus (CANopen). Depending on the motor, the HCD has an output power up to 800 W in S1 mode. Our specially developed HES/HEM encoder systems is suitable for this porpuse.

Dimensions



Connection plan



Connections

Type	Connection	Function
H1, H2, H3	Light emitting diodes (integrated)	Device status display
S1	DIP circuit	Setting the CAN address
X2	Plug-in terminal (2-pole)	Single phase supply
PE	PE connection pins	Protective grounding
X4	Plug-in terminal (12-pole)	6 digital inputs 1 digital output Interface for motor brake
X1	Plug-in terminal (7-pole)	Motor phases (U/V/W) Brake resistor (+ZK, BC) Temperature monitoring (PTC+, PTC-)
X3	USB connector (Type-B)	Connection for PC with DriveManager
X6/ X7	2x RJ45 connector	CANopen interface
X8	D-Sub connector (15-pole)	Interface for rotary encoder
X5 (opt.)	Plug-in terminal (6-pole)	Connections for STO functionality (ISDSH, RSH)
X5 (opt.)	Plug-in terminal (6-pole)	Analogue input (ISA00), resolution 10-bit ADC

Ambient conditions

Humidity in operation:	relative humidity 5 - 85 % without condensation
Ambient temperature in operation:	+ 5 °C ... - + 40 °C
Storage humidity:	relative humidity 5 - 95 %
Storage temperature:	- 25 °C ... + 55 °C
Protection class:	IP00
Installation altitude:	up to 1,000 m, up to 2,000 meter with power reduction

Supported encoder systems

SSI, TTL

Interface

CANopen (CiA 402)

Functions

- PLC Motion
- Speed control
- Torque control
- Positioning
- Ramp generator
- Integrated mains filter
- Integrated braking chopper
- UL approval*: Certified according to UL 508c
- Safety function STO

* Valid as long as the prescribed operating conditions are observed.

HCB servo drive

General information

The compact single-axis servo drives of the HCB series are true all-rounders in drive technology. They combine maximum power density with extensive motion control functions.

The HCB series consists of two sizes, which are divided into two power stages for the 1-phase units and two power stages for the 3-phase units. All proven fieldbus interfaces are „on board“ - from CANopen to EtherCAT to PROFINET, which promise problem-free communication. Its versatility is further underlined by the numerous encoder interfaces, also for single-cable solutions. Complex positioning tasks through linked position sets can be interconnected. The position-synchronous or speed- synchronous motion of various drives with variable gear ratios can be quickly parameterised via the software assistant. Rotary table applications, position triggers, rotor position triggers or switching cams - a wide range of dynamic application tasks can be handled via the integrated software functions.

In combination with the HeiMotion servo motors with precisely matched encoder variant and a gearbox from the HMPG series mounted in the gearbox direct attachment, you get a customized drive axis from a single source at an unbeatable price-performance ratio.

Connections / inputs and outputs

Connection	Function
X1	I/O communication
X2A	Resolver connection
X2B	Multi-encoder connection
X3	STO interface (STOA, STOB), limit switch (DIN6, DIN7) Dig. output (DOUT0)
X4	CANopen
X5	RS232/RS485 / Serial interface
X6	Motor connection
X6A	Motor brake / HIPERFACE DSL® (BL 4300-C)
X9	Voltage supply
X9A	Brake resistor
X9B	24V supply
X18	Ethernet interface
X19	USB interfae
X21	Realtime Ethernet interface

Specifications servo drive

	single-phase		three-phase		
	HCB 2/6-1	HCB 4/12-1	HCB 4/12-3	HCB 8/24-3	HCB 12/30-3
Voltage supply	230 V_{AC} [± 10 %], 50...60 Hz		3 x 230...480 V_{AC} [± 10 %], 45...66 Hz		
Control voltage	24 V_{DC} [± 20 %] (0,35 A)		24 V_{DC} [± 20 %] (0.35 A)	24 V_{DC} [± 20 %] (0.45 A)	24 V_{DC} [± 20 %] (0.65 A)
DC link voltage	325 V_{DC} (with U_{mains} = 230 V_{AC})		565 V_{DC} (with U_{mains} = 400 V_{AC})		
Output power	400 W	800 W	1.6 kW	3.2 kW	4.8 kW
Max. output power for 2 s	1 kW	2 kW	4.8 kW	9.6 kW	12 kW
Rated output current 2 Arms 4 Arms	2 A_{rms}	4 A_{rms}	4 A_{rms}	8 A_{rms}	12 A_{rms}
Max. output current for 2 s Arms	6 A_{rms}	12 A_{rms}	12 A_{rms}	24 A_{rms}	30 A_{rms}
Internal brake resistor	75 Ω		30 Ω		
Continuous power / pulse power	until 2 kW		until 24 kW		
External brake resistor	75 Ω, max. 2 kW		≥ 30 Ω		
Holding brake	24 V_{DC}, max. 2 A		24 VDC, max. 2A		
Dimensions servo drive H x W x D	200 x 50 x 163 mm 245 x 50 x 163 mm with mounting plate		230 x 67 x 200 mm 275 x 67 x 200 mm with mounting plate		
Weight	1.5 kg		2.9 kg		
Encoder evaluation	EnDat 2.2, HIPERFACE®, HIPERFACE DSL®, resolver, analogue and digital incremental encoders with/without commutation signals, BISS (Type C)		EnDat 2.2, HIPERFACE®, HIPERFACE DSL®, resolver, analogue and digital incremental encoders with/without commutation signals, BISS (Type C)		
Interfaces	USB 2.0, Ethernet, CAN-Bus, EtherCAT, PROFINET, MicroSD-Card		USB 2.0, Ethernet, CAN-Bus, EtherCAT, PROFINET, MicroSD-Card		
Inputs / outputs	8 x digital in (24 VDC), 2 x analogue in (± 10 V) 3 x digital out (24 VDC)		8 x digital in (24 VDC), 2 x analogue in (± 10 V) 3 x digital out (24 VDC)		
Product numbers	12-225-020-01-0	12-225-020-02-0	12-405-020-11-0	12-405-020-12-0	12-405-020-13-0

HCB servo drive

Ambient conditions

Ambient temperature in operation:	0 °C to +40 °C +40 °C to +50 °C with power reduction 2.5 %/K
Storage temperature:	-25 °C to +70 °C
Operating and storage humidity:	relative humidity 90 % (without condensation)
Protection class:	IP20
Installation altitude:	Mounting height max. 2000 m above sea level, above 1000 m above sea level with power reduction 1 % per 100 m

Functions*

- Safety function „Safe Torque-Off (STO)
- Realization of functionality SS1 possible
- Switching cams
- Safe Brake Control (SBC) if configured
- Direct control of the holding brake in the motor
- Automatic determination of motor parameters
- Flying Saw
- Path program / linking
- Integrated position control
- Parameterizable belt locks

* Some functions are not available for all models

Power Cable

Length	Heidrive-No.
3 m	14-007-051-18-0
5 m	14-007-051-19-0
10 m	14-007-051-23-0

Signal cable (resolver)

Length	Heidrive-No.
3 m	14-007-051-60-0
5 m	14-007-051-62-0
10 m	14-007-051-67-0

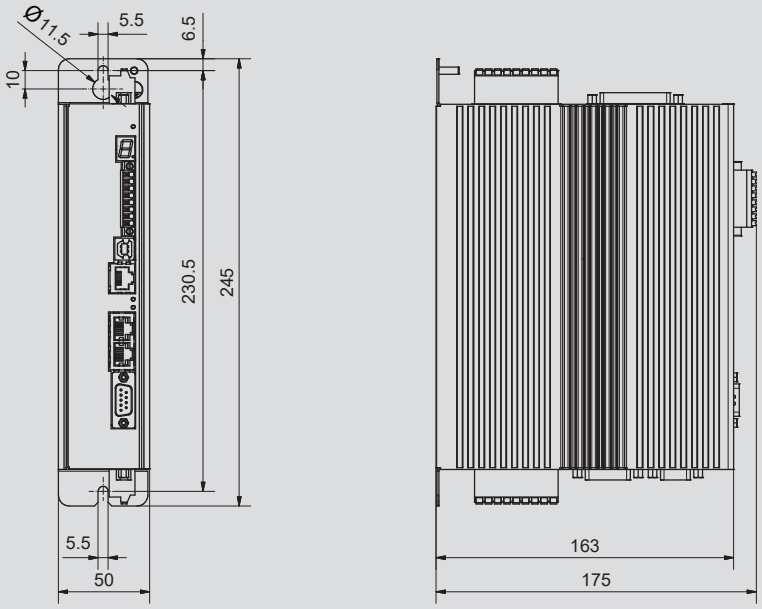
Signal cable (HIPERFACE)

Length	Heidrive-No.
3 m	14-007-051-78-0
5 m	14-007-051-80-0
10 m	14-007-051-85-0

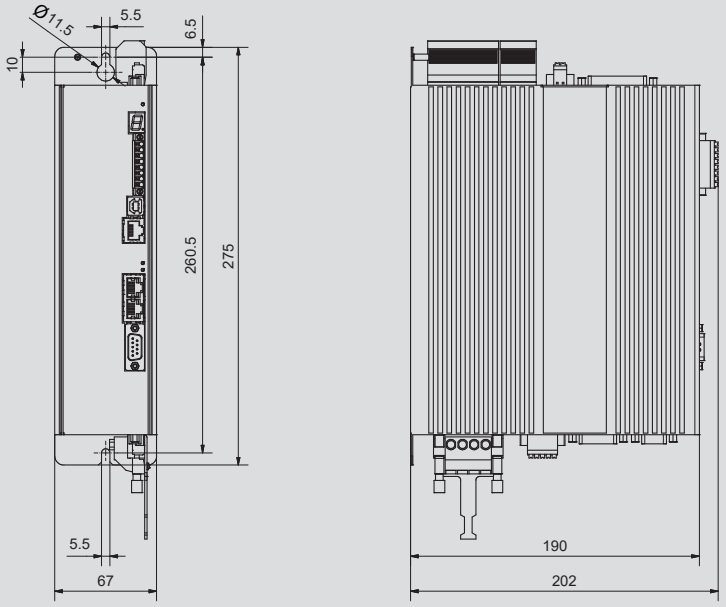
Connector sets

single-phase	three-phase
14-001-015-22-0	14-001-015-35-0

Dimensonal Drawing HCB / single phase



Dimensonal Drawing HCB / three-phase



HCF servo drive,
24 to 48 V_{DC}

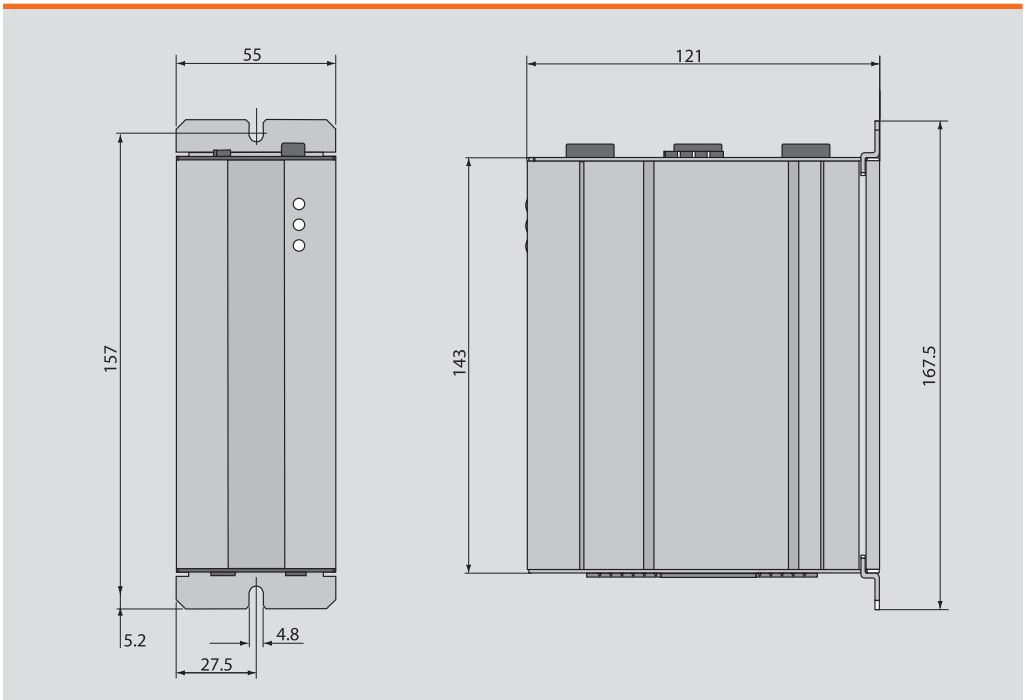
Specifications servo drive

Typ	Supply voltage [V_{DC}]	DC bus voltage [V_{DC}]	Output voltage [V_{rms}]	Continuous output current [A_{rms}]	Maximum output current [A_{rms}]	Rated power [W]	Order code
HCF	24 - 48	24 - 48	3 x 0 - 33	8	16	240	HCF0-008-1x.x.-0

Switch frequency [kHz]: 8, 16 (Factory setting 8 kHz)
Power rating [kVA]: 0.55
Cable cross-section [mm²]: 1.5...2.5
Logic supply [V_{DC}]: 24

The HCF servo drive is a cost-optimized, DC powered 24 V or 48 V motor controller for use in the demanding world of precision automation technology. The HCF features high precision positioning functionality, a sturdy mechanical design, CANopen CiA 402 support, safe stop according to Category 3 of IEC 954-1, and much more.

Dimensions (mm)



Connections / inputs and outputs

Type	Connection	Function
X1	Plug-in terminal (6-pole)	DC supply (L+ / L-) Brake resistor (L+ / RB)
X2	Plug-in terminal (2 x 10-pole)	Safe Stop with relay output 8 digital inputs 2 analog inputs 10-bit ADC 3 digital outputs 1 relay output (24 V / 1 A) Logic power supply
X3	Plug-in terminal (4-pole)	Motor phases (U/V/W/PE)
X4	D-sub connector (9-pole)	RS232 interface
X5	D-sub panel connector (9-pole)	CANopen interface
X6	D-sub connector (15-pole)	Interface for rotary encoders with temperature monitoring (PTC / KTY / Klixon)
S1	Rotary code switch	Setting the CANopen address

Ambient conditions

Ambient temperature in operation:	- 10 °C ... + 40 °C
Storage temperature:	- 25 °C ... + 55 °C
Operating and storage humidity:	15 ... 85 % relative humidity (without condensation)
Protection class:	IP20
Installation altitude:	up to 1,000 m

Supported encoder systems

Resolver, Incremental encoder, SSI absolute encoder

Interface

CANopen (CiA 402), RS232

Functions

- Brake driver
- PLC Motion
- DriveManager software
- Online position profile generator
- Integrated braking resistor
- Electronic cam
- Sequenced driving set positioning
- Safe stop according to EN 954-1, category 3

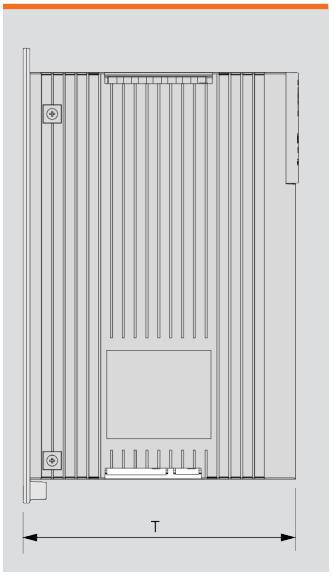
HCJ drive,
230 / 400 V_{AC}

Specifications servo drive

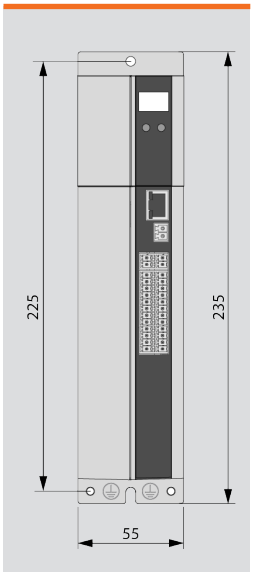
Typ	DC bus voltage	Input voltage	Continuous output current I_N	Maximum output current I_{MAX}	Frame size
	[V]	[V]	[A_{rms}]	[A_{rms}]	
HCJ22.003	325	1 / 3 x230	3	9	size 2
HCJ24.002	560	3 x 400	2	6	size 2
HCJ22.006	325	1 / 3 x 230	5.9	17.7	size 3
HCJ24.004	560	3 x 400	3.5	10.5	size 3
HCJ22.008	325	1 / 3 x 230	8	24	size 4
HCJ24.007	560	3 x 400	6.5	19.5	size 4
HCJ24.012	560	3 x 400	12	36	size 5
HCJ24.016	560	3 x 400	16	48	size 5

Mains frequency [Hz] 50 / 60 ± 10 %

size 2/3/4

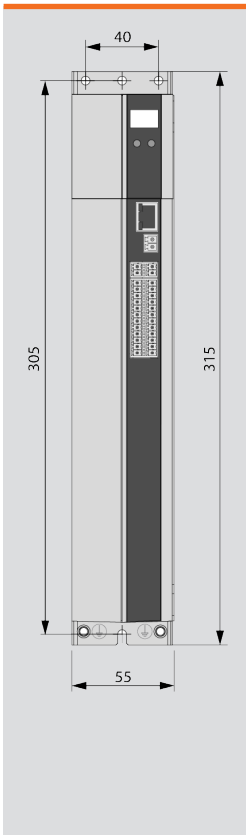


size 2/3

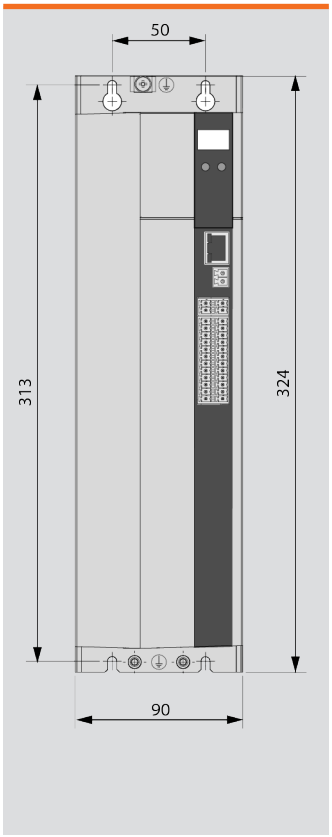


Type	T	Weight
size 2	142 mm	1.0 kg
size 3	189 mm	1.5 kg
size 4	235.5 mm	2.8 kg
size 5	235.5 mm	5.5 kg / 5.9 kg

size 4



size 5



Connections / inputs and outputs

Connection	Name	Function
X1	Plug-in terminal (7-pole)	Motor phases (U/V/W/PE) DC-link (L+/L-) Brake resistor (L+/RB)
X2	Plug-in terminal (2-pole)	Logic supply + 24 V_{DC}
X3	Plug-in terminal (4-pole)	Mains supply (L1/L2/L3/PE)
X4	Plug-in terminal (2x 10-pole)	7 digital inputs 2 analog inputs (10-bit ADC) 3 digital outputs 1 relay (24 V / 1 A) diagnosis STO
X5	Plug-in terminal (2-pole)	Temperature monitoring (PTC / KTY / Klixon)
X6	D-sub connector (9-pole)	Interface for resolver
X7	D-sub connector (15-pole)	Interface for rotary encoders (TTL / SSI / HIPERFACE / ENDAT)
X9	RJ-45 connector	Interface for Ethernet
X13	Plug-in terminal (4-pole)	Interface for motor brake
Option 1	Connector (depending on module)	Fieldbus interface e.g. CANopen, EtherCAT, SERCOS, ...
Option 2	Connector (depending on module)	Encoder interface e.g. second (safe) encoder, Encoder simulation, TwinSync, axis monitoring, ...

Ambient conditions

Ambient temperature in operation:	- 10 °C ... + 40 °C
Storage temperature:	- 25 °C ... + 55 °C
Operating and storage humidity:	< 85 % relative humidity (without condensation)
Protection class:	IP20 except clamps (IP00)
Installation altitude:	up to 1,000 m

Supported encoder systems

Resolver, HIPERFACE® encoder, HIPERFACE DSL® encoder, Incremental encoder, SSI absolute encoder
EnDat 2.2 encoder

Interface

CANopen (CiA 402), Ethernet (parameterization via DriveManager software)

Optional: EtherCAT, SERCOS III, Profibus DP or Profinet IRT

Functions

- PLC Motion
- Brake driver
- Sequenced driving set positioning
- Online position profile generator
- DriveManager software
- Integrated braking resistor (size 3+4)
- Safe stop according to EN 954-1, category 3
- Radio interference filters (RFI) up to 7.5 kW
- Electronic cam

Technical data subject to change! Last changes: 11/2023

Heidrive GmbH
Starenstraße 23
D-93309 Kelheim

Phone +49 9441/707-0
Fax +49 9441/707-259

info@heidrive.de
www.heidrive.com